

Design tools for Distributed Wind

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with contributions from R. Damiani, B. Summerville, D. Davis, R. Preus

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Outline

- Loads modeling options for DWT
 - simplified load methodology
 - aeroelastic modeling
- Loads validation
- More about aeroelastic modeling
 - Options for different types of turbines
 - Getting into aeroelastic modeling
 - Pre and post-processing
- Other useful tools



Simplified loads model

- Simple, conservative equations
- Only applicable for
 - Horizontal axis
 - 2+ cantilevered blades
 - Coordinated blade movement
 - Rigid hub
- Example: Load Case A

$$\Delta F_{zB} = 2m_B R_{cog} \omega_{n,design}^2$$

$$\Delta F_{x-shaft} = \frac{3}{2} \frac{\lambda_{design} Q_{design}}{R}$$

$$\Delta M_{xB} = \frac{Q_{design}}{B} + 2m_B g R_{cog}$$

$$\Delta M_{x-shaft} = Q_{design} + 2m_r g e_r$$

$$\Delta M_{yB} = \frac{\lambda_{design} Q_{design}}{B}$$

$$\Delta M_{shaft} = 2m_r g L_{rb} + \frac{R}{6} \Delta F_{x-shaft}$$

Table 2 – Design load cases for the simplified load calculation method

Design situation	Load cases	Wind inflow	Type of analysis	Remarks
Power production	A Normal operation		F	
	B Yawing	$V_{hub} = V_{design}$	U	
	C Yaw error	$V_{hub} = V_{design}$	U	
	D Maximum thrust	$V_{hub} = 2,5 V_{ave}$	U	Rotor spinning but could be furling or fluttering
Power production plus occurrence of fault	E Maximum rotational speed		U	
	F Short at load connection	$V_{hub} = V_{design}$	U	Maximum short-circuit generator torque
Shutdown	G Shutdown (Braking)	$V_{hub} = V_{design}$	U	
Extreme wind Loading	H Extreme wind loading	$V_{hub} = V_{e50}$	U	The turbine may be parked (idling or standstill) or governing. No manual intervention has occurred.
Parked and fault conditions	I Parked wind loading, maximum exposure	$V_{hub} = V_{ref}$	U	Turbine is loaded with most unfavourable exposure
Transport, assembly, maintenance and repair	J To be stated by manufacturer		U	

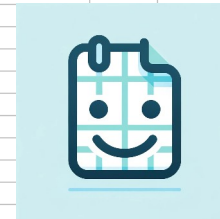
Key

F analysis of fatigue loads

U analysis of ultimate loads

Inputs and calculations

Description	Input Value	Units	Symbol	Description	Value	Units	Symbol
Air density	1.2250	kg/m ³	ρ	Design Wind Speed	10.50	m/s	V_design
Gravitational acceleration	9.8100	m/s ²	g	50 year extreme wind speed	52.50	m/s	V_e50
Reference Wind Speed	37.5000	m/s	V_ref	50yr extreme tip speed ratio	1.93	n/a	λ_{e50}
Average Wind Speed	7.5000	m/s	V_ave	Design Tip Speed Ratio	6.77	n/a	λ_{design}
Number of Blades	3	n/a	B	Drive Train Efficiency	0.60	n/a	$\hat{\eta}$
Blade Tip Radius	0.9700	m	R	Design Torque	11.32	Nm	Q_design
Total Platform Area of the Blade	0.2310	m ²	A_proj,B	Projected Area (turbine swept area)	2.96	m ²	A_proj
Drag Coefficient of the Blades	1.5000	n/a	C_d	Design Rotational Speed of the Rotor	73.30	rad/s	$\omega_{n,design}$
Max Lift Coefficient of the Blades	2.0000	n/a	C_l,max	Maximum Possible Rotor Speed	104.72	rad/s	$\omega_{n,max}$
Thrust Coefficient	0.5000	n/a	C_T	Max Yaw Rate	2.99	rad/s	$\omega_{yaw,max}$
Maximum Rotor Speed	1000.0000	rpm	n_max	50yr extreme tip speed ratio	1.93	n/a	λ_{e50}
Design Rotor Speed	700.0000	rpm	n_design	Eccentricity of the Rotor Centre of Mass	4.85E-03	m	e_r
Second Moment of Inertia for each Blade	0.0633	kgm ²	I_B	Effective brake torque	0.00	Nm	M_brake
Single Blade Mass	0.4000	kg	m_B	Cross Sectional Area of the Shaft	4.9087E-04	m ²	A_shaft
Rotor Mass (All Blades plus Hub)	3.9800	kg	m_r	The second moment of inertia for the shaft	1.9175E-08	m ⁴	I_x-shaft
Distance from Blade centre of gravity to rotor axis	0.3790	m	R_cog	Section modulus for the shaft	1.5340E-06	m ³	W_shaft
Distance Between Rotor Centre and First Bearing	0.0280	m	L_fb	Blade x-section modulus	3.0359E-06	m ³	W_xB
Distance Between the Rotor Centre and the yaw axis	0.2180	m	L_ft	Blade y-section modulus	1.5411E-04	m ³	W_yB
Gearbox Ratio (enter 1.0 for no gearbox)	1.0000	n/a	Gear	Number of Fatigue Cycles	2.21E+10	n/a	n_i
Enter "Y" if brake is on high speed side of gearbox, otherwise "N"	N	n/a	n/a				
Brake torque (enter 0.0 for no brake)	0.0000	Nm	M_brake				
Design Power	0.5000	kW	P_design				
Short Circuit Torque Factor	2.0000	n/a	G				
Type "Y" if blades are stationary during parking, otherwise "N"	Y	n/a	n/a				
Diameter of the Shaft	2.5000E-02	m					
Cross Sectional Area of the Blade Root	1.4600E-03	m ²	A_B				
I _{xx} for the blade	2.7900E-08	m ⁴	I_xxB				
x-distance from blade centroid to the maximum stress point	9.1900E-03	m	c_xB				
I _{yy} for the blade	1.1990E-06	m ⁴	I_yyB				
y-distance from blade centroid to the maximum stress point	7.7800E-03	m	c_yB				
Ultimate Material Strength for the Blades	1.2000E+02	MPa	f_kB				
Ultimate Material Strength for the Shaft	2.5000E+02	MPa	f_k-shaft				
Design life of the turbine	20	Years					
	631152000	s	T_d				
Number of Cycles to Failure as a Function of Stress (Shaft)	1.00E+10	n/a	N_shaft				
Number of Cycles to Failure as a Function of Stress (Blade)	1.23E+13	n/a	N_blade				



SLM results

Loads from SLM

Load Case A - Fatigue Loads on Blades and Rotor Shaft

Equation	Description	SLM Value	Units	Symbol
Blade Loads				
9.4 (IEC 21)	Centrifugal Force at the Blade Root (z-axis)	1629.23	N	ΔF_{zB}
9.5 (IEC 22)	Lead-lag Root Bending Moment (x-axis)	6.75	Nm	ΔM_{xB}
9.6 (IEC 23)	Flapwise Root Bending Moment (y-axis)	25.55	Nm	ΔM_{yB}
Shaft Loads				
9.7 (IEC 24)	Thrust on shaft (x-axis)	118.55	N	$\Delta F_{x-shaft}$
9.8 (IEC 25)	Shaft Moment about x-axis	11.70	Nm	$\Delta M_{x-shaft}$
9.9 (IEC 26)	Shaft Moment	21.20	Nm	ΔM_{shaft}

Load Case B - Blade and Rotor Shaft Loads during Yaw

Equation	Description	SLM Value	Units	Symbol
9.16 (IEC 28)	Flapwise Root Bending Moment (y-axis)	40.83	Nm	M_{yB}
9.11,12 (IEC 29,30)	Bending moment on the shaft	61.81	Nm	M_{shaft}

Load Case C - Yaw Error Load on Blades

Equation	Description	SLM Value	Units	Symbol
9.13 (IEC 31)	Flapwise Root Bending Moment (y-axis)	422.82	Nm	M_{yB}

Load Case D - Maximum Thrust on Shaft

Equation	Description	SLM Value	Units	Symbol
9.14 (IEC 32)	Maximum Thrust on Shaft	318.25	N	$F_{x-shaft}$

Load Case E - Maximum Rotational Speed

9.11,12 (IEC 29,30)	Bending moment on the shaft	61.81	Nm	M_{shaft}
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Load Case C - Yaw Error Load on Blades

Equation	Description	SLM Value	Units	Symbol
9.13 (IEC 31)	Flapwise Root Bending Moment (y-axis)	422.82	Nm	M_{yB}

Load Case D - Maximum Thrust on Shaft

Equation	Description	SLM Value	Units	Symbol
9.14 (IEC 32)	Maximum Thrust on Shaft	318.25	N	$F_{x-shaft}$

Load Case E - Maximum Rotational Speed

Equation	Description	SLM Value	Units	Symbol
9.15 (IEC 33)	Centrifugal Force at the Blade Root (z-axis)	1662.48	N	F_{zB}
9.16 (IEC 34)	Bending Moment on the shaft	6.52	Nm	M_{shaft}

Load Case F - Short at Load Connection

Equation	Description	SLM Value	Units	Symbol
9.17 (IEC 35)	Bending Moment on Shaft	22.64	Nm	$M_{x-shaft}$
9.18 (IEC 36)	Lead-lag Root Bending Moment (x-axis)	7.55	Nm	M_{xB}

Load Case G - Shutdown Braking

Equation	Description	SLM Value	Units	Symbol
9.19 (IEC 37)	Bending Moment on Shaft	n/a	Nm	$M_{x-shaft}$
9.20 (IEC 38)	Lead-lag Root Bending Moment (x-axis)	n/a	Nm	M_{xB}

Load Case H - Parked Wind Loads during Idling

Equation	Description	SLM Value	Units	Symbol
9.23,24 (IEC 39,40)	Flapwise Root Bending Moment (y-axis)	283.71	Nm	M_{yB}
9.25,26 (IEC 41,42)	Maximum Thrust on Shaft	1754.89	N	$F_{x-shaft}$

SLM applicability and safety factors

	Micro wind turbines up to 1 kW Peak Power	1-30 kW Peak Power	30-65 kW Peak Power	65-150 kW Peak Power
STRUCTURAL DESIGN				
SLM	Not required	Not recommended for turbines with Peak Power greater than 10 kW	Not allowed	Not allowed
Aeroelastic model	Not required	Allowed with validation through power, rotor speed. Validate weight of major components.	Allowed with validation through power, rotor speed, blade first flapwise (static) natural frequency*. Validate weight of major components.	Allowed with validation through power, rotor speed, blade first flapwise (static) natural frequency, tower loads*. Validate weight of major components.
Structural Analysis	Not required	Required	Required	Required

Ref. ANSI/ACP 101-1 2021 The Small Wind Turbine Standard

Table 7 – Partial safety factors for loads

Load determination method (see 5.2)	Fatigue loads, γ_f	Ultimate loads, γ_f
1. Simplified equations	1,0	3,0
2. Simulation model	1,0	1,35
3. Full scale load measurement	1,0	3,0

Ref. International Electrotechnical Commission, Wind turbines - Part 2: Small wind turbines, EN 61400-2:2014.



SLM applicability and safety factors

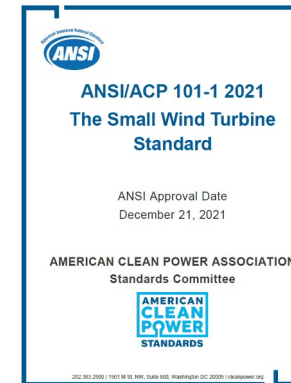
	Micro wind turbines up to 1 kW Peak Power	1-30 kW Peak Power	30-65 kW Peak Power	65-150 kW Peak Power
STRUCTURAL DESIGN				
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Structural Analysis	Not required	Required	Required	Required

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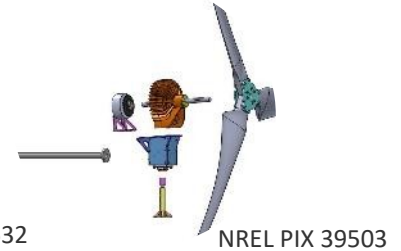
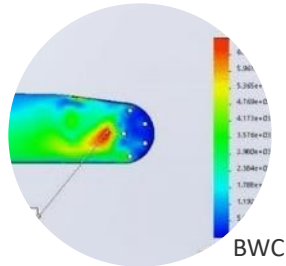
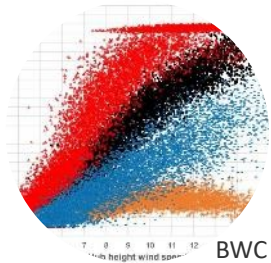
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3. Full scale load measurement	1,0	3,0

Ref. International Electrotechnical Commission, Wind turbines - Part 2: Small wind turbines, EN 61400-2:2014.



Aeroelastic modeling pros & cons



Understand the load and power behavior of the turbine before witnessing it in the field

Control parameters that have the highest impact on design

Optimize the configuration most efficiently

Provide a more realistic basis for design certification

Simplify conformity assessment following a change in the turbine architecture

Ref. R. Damiani, D. Davis, B. Summerville (2021): Aeroelastic Modeling for Distributed Scale Wind Turbines.

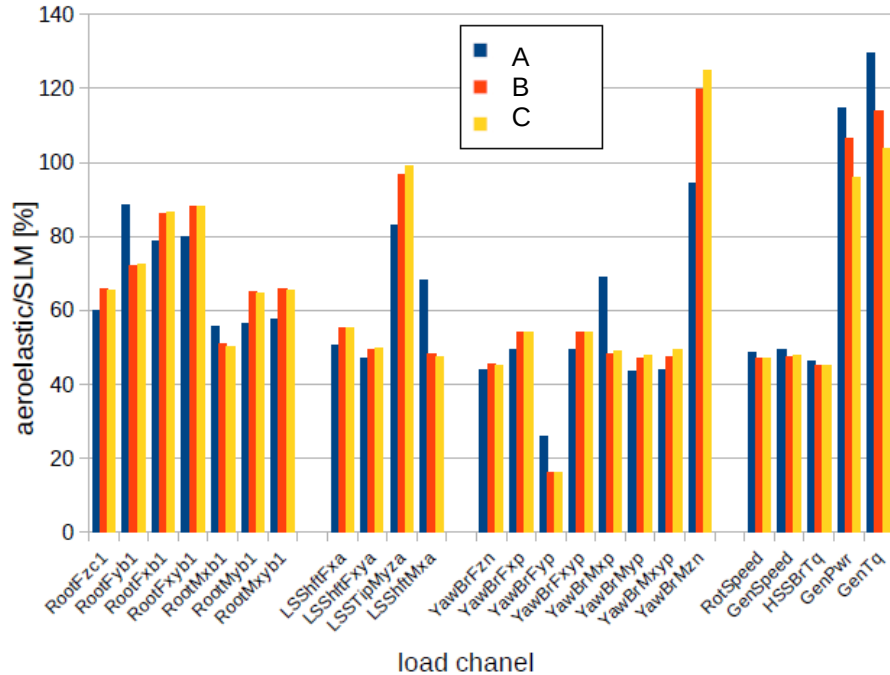
- Disadvantages

- Mostly HAWT-centric
- Steep learning curve, labour intensive
- Computationally expensive
- License fee for some codes

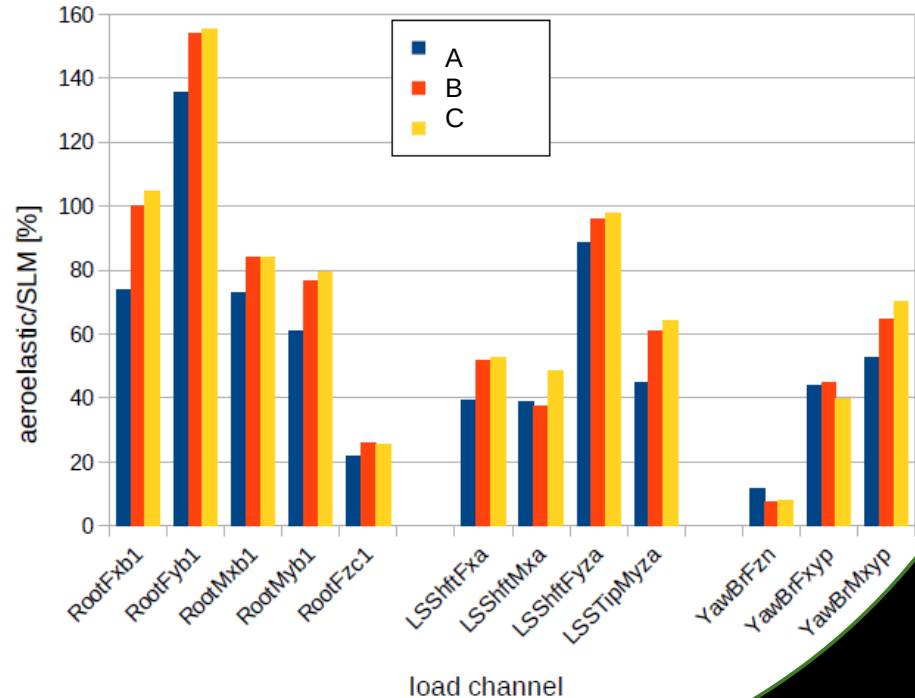


Aeroelastic vs. SLM

Extreme w/ SF



Fatigue



- Aeroelastic generally results in reduced loads



Tests to verify design data and validate model

According to ANSI/ACP-101-1

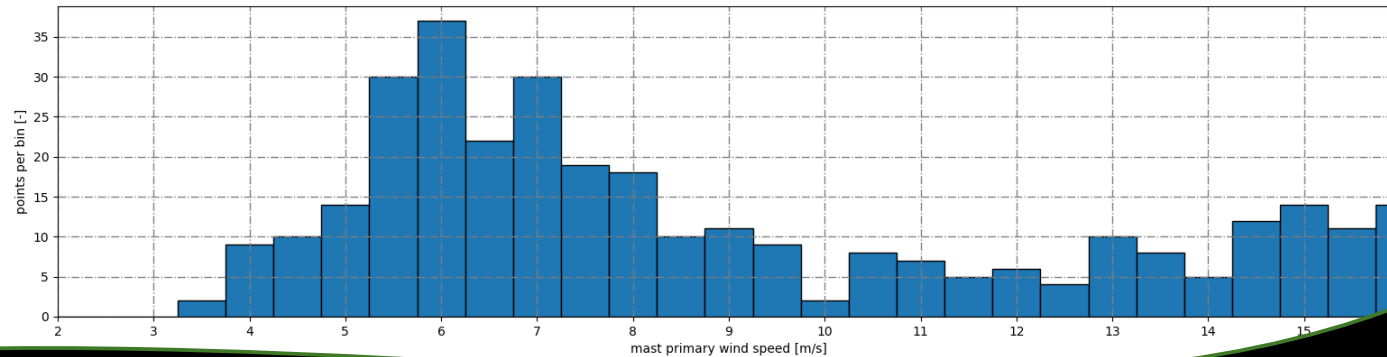
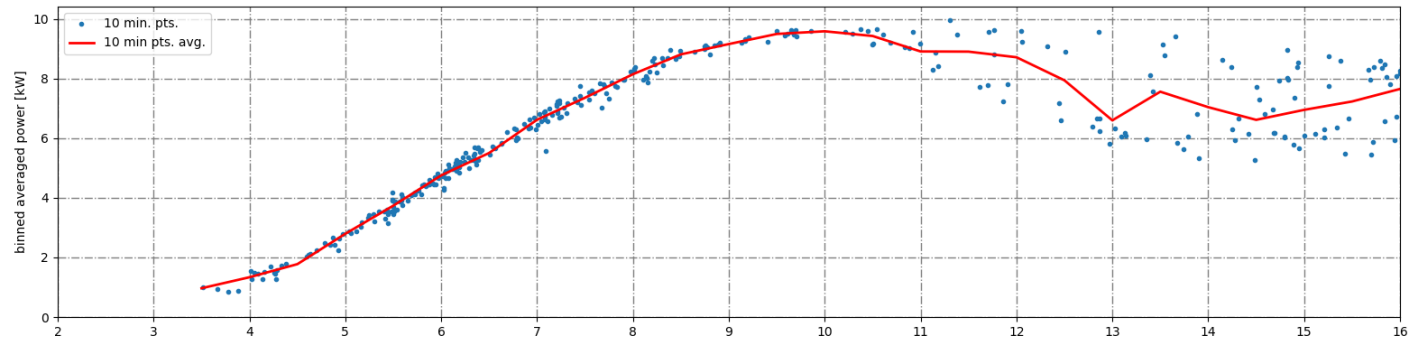
		Design values @ $1.4V_{ave}$			maximums		Weights of major components	Blade first flapwise (static) natural frequency	Tower loads
		power	Rotor speed	Shaft torque*	Rotor speed	Yaw rate			
SLM		X	X	X	X	X			
Aeroelastic	1 - 30 kW	X	X	X	X	X	X		
	30 - 65 kW	X	X	X	X	X	X		
	65 - 150 kW	X	X	X	X	X	X	X	

*May be calculated from power and rotor speed



Validation measurements requirements

- Measured data shall be binned into 0.5 m/s wind speed bins
- Each bin from 1 m/s below V_{in} to $2V_{ave}$ shall contain at least 10 data points



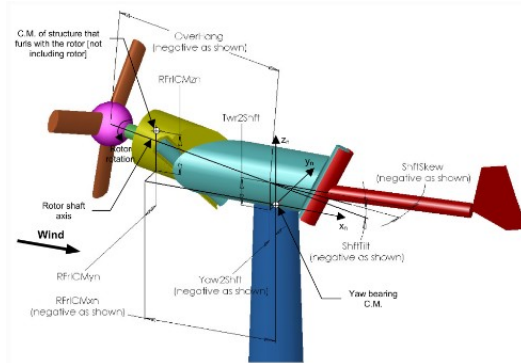
Validation measurements requirements

- Max yaw rate
 - Passive yaw: Measured value cannot be used for SLM (use 61400-2 eq. 27)
 - Semi-active / damped yaw
 - Measured value may be used in SLM
 - Must see an upper limit in measured values
- Max rotor speed
 - Shall be measured during condition most likely to give highest speed (e.g. loss of load or wind gust)
 - Wind speeds from 10 m/s – 20 m /s
 - 2h of data
 - At least 1/2 h below 15 m/s and 1/2 h above
 - Max speed shall be extrapolated to V_{ref}

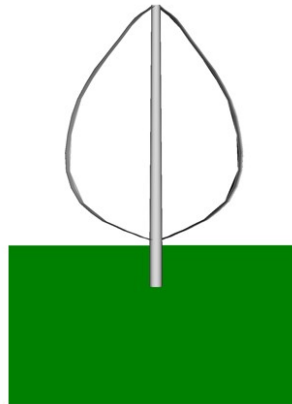


Aeroelastic modeling – Code options

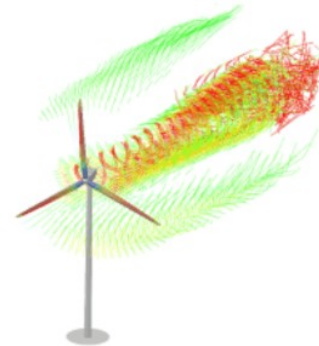
	OpenFAST	HAWC2	MSC.Adams	Bladed	QBlade	Flex5	OWENS	SimPack	SamCef	ASHES	alaska/ Wind
HAWT	X	X	X	X	X	X		X	X	X	X
VAWT		X			X		X				
General purpose			X					X	X		X
free	X	trial available			trial available					trial available	



Ref. FAST User's Guide, Jonkman, Buhl, 2005.



Ref. "Study of Design Load Cases for Multi-Megawatt Onshore Vertical Axis Wind Turbines", DTU Wind Energy, June 2015.



Ref. D. Marten, J. Saverin, R. Behrens de Luna, S. Perez-Becker. 2021.



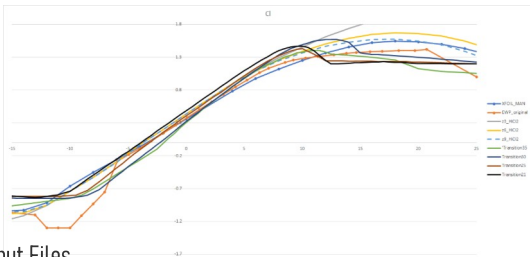
Aeroelastic modeling workflow

Preprocessing

- Blade/tower structural definition, eigenmodes
- Airfoil Aerodynamics
- RNA properties
- Controller settings

Model Creation

- Assemble Input Files



Preliminary Validation

- Assess major properties (mass, eigenfrequencies, steady-state power, RPM, etc.)

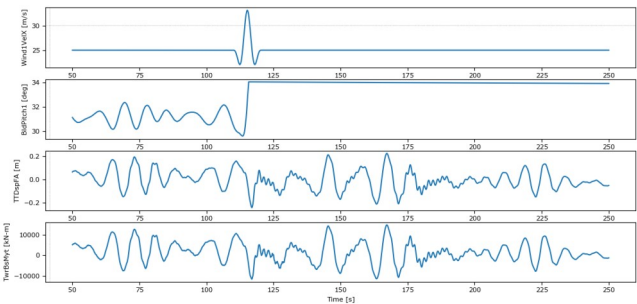
Design Basis

- Select DLCs and Environmental Conditions
- Create wind files, batch runs, PC req.ts

Simulation Runs

Postprocessing

- Extract ULS, FLS, SLS driving loads, deflections, etc.
- Assess resonance & instability risk



Design situation	DLC	Wind condition	Other conditions	Type of analysis
1) Power production	1.1	NTM $V_{in} < V_{hub} < V_{out}$ or $3 \times V_{ave}$		F, U
	1.2	ECD $V_{hub} < V_{design}$		U
	1.3	EOG ₅₀ $V_{in} < V_{hub} < V_{out}$ or $3 \times V_{ave}$		U
	1.4	EDC ₅₀ $V_{in} < V_{hub} < V_{out}$ or $3 \times V_{ave}$		U
	1.5	ECG $V_{hub} = V_{design}$		U
2) Power production plus occurrence of fault	2.1	NWP $V_{hub} = V_{design}$ or V_{out} or $2,5 \times V_{ave}$	Control system fault	U
	2.2	NTM $V_{in} < V_{hub} < V_{out}$	Control or protection system fault	F, U
	2.3	EOG ₁ $V_{in} < V_{out}$ or $2,5 \times V_{ave}$	Loss of electrical connection	U
3) Normal shutdown	3.1	NTM $V_{in} < V_{hub} < V_{out}$		F
	3.2	EOG ₁ $V_{hub} = V_{out}$ or $V_{max,shutdown}$		U
4) Emergency or manual shutdown	4.1	NTM To be stated by the manufacturer		U
5) Extreme wind loading (standing still or idling; or spinning)	5.1	EWM $V_{hub} = V_{e50}$	Possible loss of electrical power network	U
	5.2	NTM $V_{hub} < 0,7 V_{ref}$		F
6) Parked and fault condition	6.1	EWM $V_{hub} = V_{e1}$		U
7) Transport, assembly, maintenance and repair	7.1	To be stated by the manufacturer		U

Publicly available models

Archetype coverage table (HAWTs)

Active Yaw	Passive Yaw	Stall	Pitch	VarSpd	FixedSpd	Down-Wind	Up-Wind	
Gray	Gray	Green	Green ✓	Green ✓	Green ✓	White	Green ✓	Active Yaw
Gray	Gray	Green ✓	Yellow	Green ✓	Yellow ✓	Green ✓	Green ✓	Passive Yaw
Gray	Gray	Gray	Gray	Green ✓	Green ✓	Green ✓	Green ✓	Stall
Gray	Gray	Gray	Gray	Green ✓	Yellow	Yellow ✓	Green ✓	Pitch
Gray	Gray	Gray	Gray	Gray	Gray	Green ✓	Green ✓	VarSpd
Gray	Gray	Gray	Gray	Gray	Gray	Yellow ✓	Green ✓	FixedSpd
Gray	Gray	Gray	Gray	Gray	Gray	Gray	Gray	Down-Wind
Gray	Gray	Gray	Gray	Gray	Gray	Gray	Gray	Up-Wind

Where:

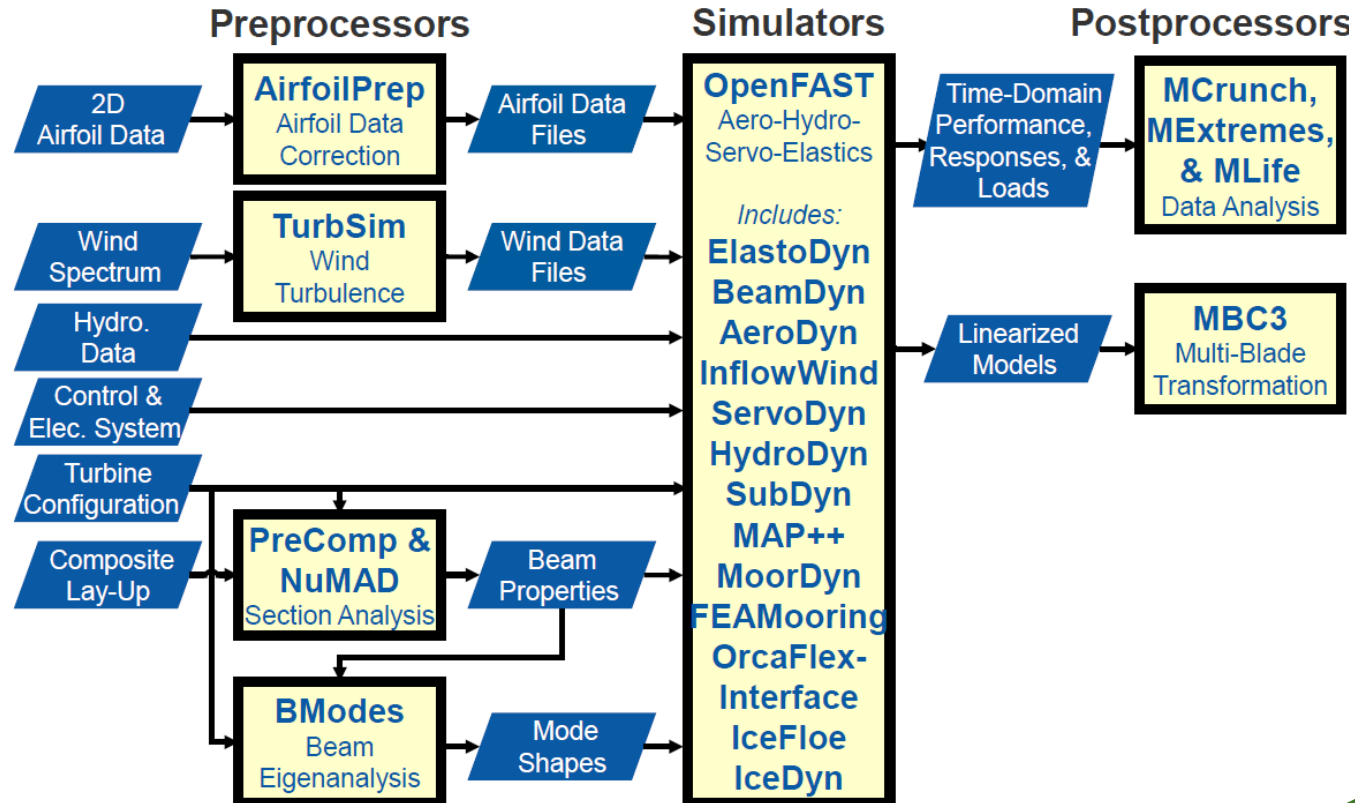
- Gray = N/A
- Green = common in the current market
- Yellow = rare in the current market
- White = not seen in the current market
- ✓ = aeroelastic model template available

- Other features included
 - Furling
 - Teetering
 - Tip brakes
 - Tail
 - Guyed tower
 - Lattice tower

Ref. R. Damiani, D. Davis, B. Summerville (2021): Aeroelastic Modeling for Distributed Scale Wind Turbines.



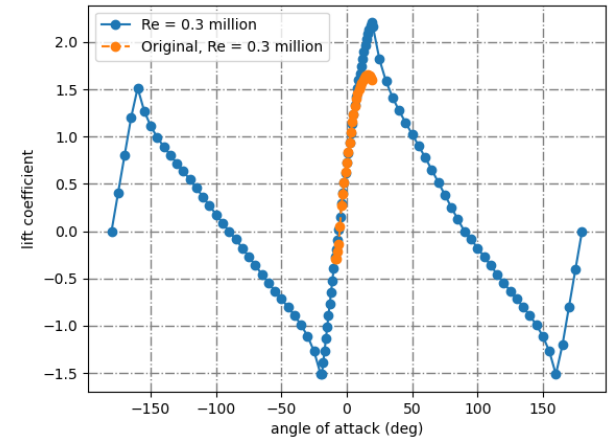
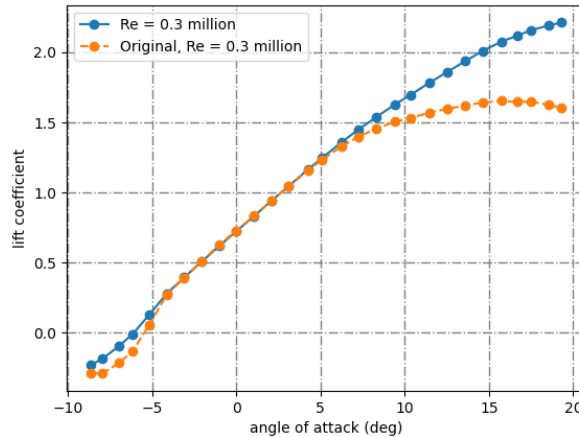
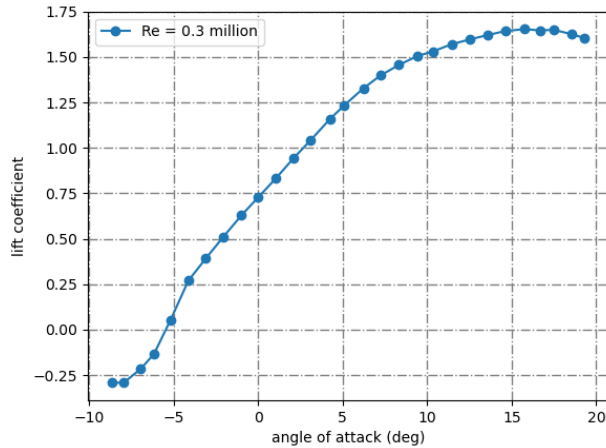
OpenFAST workflow



Credit: Dr. J. Jonkman



Preprocessing – airfoil data



Linear region*	3D correction	360° extrapolation
Xfoil**	AirfoilPreppy***	AirfoilPreppy
UIUC airfoil tests database		

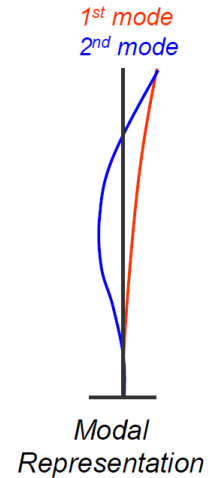
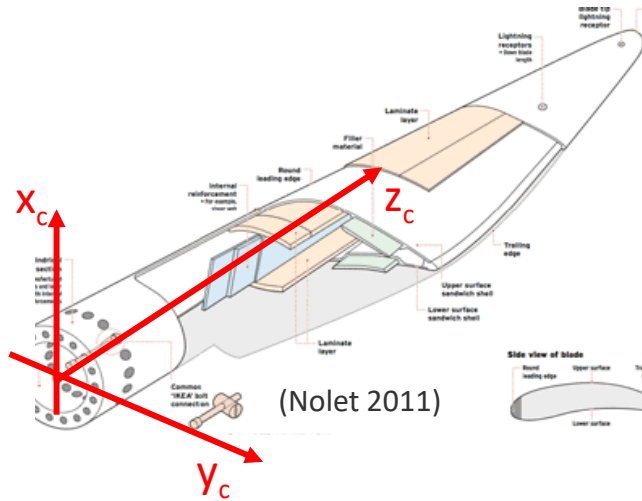
* Use data at correct Reynolds number(s)

** Be sure of data at low Reynolds numbers ($<5E5$). Measurements are best.

*** Also calculates unstable aerodynamics model coefficients



Preprocessing – structure files



Cross-sectional properties	Eigenfrequencies and mode shapes
PreComp	BModes
VABS	FEM
Sonata	Mode shape polynomial curve fitting



Running OpenFAST

Excellent material for learning OpenFAST from [NAWEA 2022 OpenFAST workshop](#)

Inputs and outputs

INPUTS:

- one main file (extension .fst) which references other files

OUTPUTS:

- one data file (.out or .outb) with time series of selected output channels
- optional files: summary (.sum), echo (.ech), linearization (.lin), visualization (vtk)

Time (s)	Rotor Speed (rpm)	Channel(s) (unit)
0	5.0	
0.1	4.9	
...	...	
tMax	5.5	

Output file and output channels [-L2]

- Each module define the output channels at the end of their input file, after the key "OutList"
- Output for selected sections is possible via "Gages" (see e.g. `ISOWake`, `TubeStr`, `TurcGage`, `BladeGage`)
- We have recently added "Nodal outputs" for ElastoDyn, AeroDyn and BeamDyn, which provides outputs for all blade sections. (See Challenge OF3 and Case2)
- You can find the list of output channels available for each module in the OpenFAST repository: [docs/OtherSupporting/OutListParameters.xlsx](#)

Module	Channel Name	Description	Units
ElastoDyn	rotorSpeed	Rotor speed	(rpm)
ElastoDyn	rotorTipSpeedRatio	Rotor tip speed ratio	(-)
AeroDyn	rotorDisAvgRelVelComp1	Rotor disk-averaged relative wind velocity (z-component)	(m/s)

Running OpenFAST

- Open a terminal/command line
Windows: From the File explorer: File -> Open Windows PowerShell
Also, see Challenges OF1 and T14
- Navigate to the folder where the OpenFAST executable and main input file are:
`cd path/to/folder`
- Call the OpenFAST executable with the main input file as argument:
`./openfast_x64.exe Main.fst`
- Pay attention to the **terminal outputs**

```

C:\Users\user> ./openfast_x64.exe Main.fst
OpenFAST
Copyright (C) 2022 National Renewable Energy Laboratory
Copyright (C) 2022 NREL
This program is licensed under a Creative Commons Attribution 4.0 International License. See the LICENSE file distributed with this software for more information.
OpenFAST [17.2.1]
Compiler: Intel(R) Fortran Compiler 19.0.4
Architecture: x86_64
Precision: Single
Number of processors: 20
Date: Tue Jul 2022
Time: 11:40:15
Elapsed time: 0.000
Time: 11:40:15.000
OpenFAST input file heading:
This is the further modeling workshop simulation
Run the following:
Running AeroDyn
Running ElastoDyn
Warnings/errors would show up here
Total wall time: 2.773 seconds
Total CPU time: 2.264 seconds
Simulation CPU time: 2.75 seconds
Simulation I/O: 0.000 seconds
I/O ratio (I/O/CPU): 0.000
OpenFAST terminated normally.
  
```

Case 3 – Steady Wind of 8m/s with simple controller

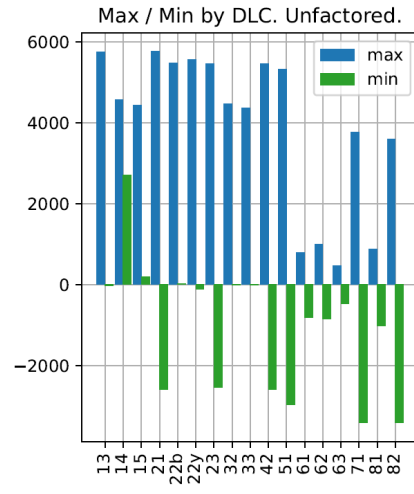
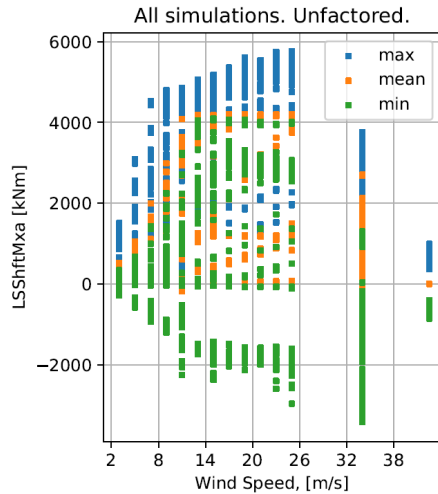
- We add a simple controller (generator torque) using the ServoDyn module. (we do not use a DLL to avoid platform compatibility issues)
- We refer to input files in the directory `../SIM_BaseLine` to avoid repeating common input files
- We output 3D surfaces for visualization (see challenge OF1)
- The turbine is started with a tower top displacement (to better see the tower motion)
- Important inputs for this case:
 - Main.fst: `CompServo = MVTK`, `VTK_type = VTK_fps`
 - ServoDyn.dat: `VSContrl_1 = VS_Rgn2k`, `VS_*`
- Try changing the initial rotor speed, or the `VS_*` parameters
- Clean your vtk folder if you change fps, tmax, or dt

Modeling trip ups

- Time step
- Initial conditions
- Aerodynamic models
 - Disable induction when parked/idling
 - Be aware of high AOAs and yaw errors
- Airfoil polars
 - 3D correction
 - 360° extrapolation
- The [NREL forum](#) is full of great tips and support from the developers
- Drivetrain frequency and damping
- Structural data issues
 - Tune mass, CM, natural frequencies to match reference data
 - Mode shapes
- Geometry and topology
 - Use visualization tools to check



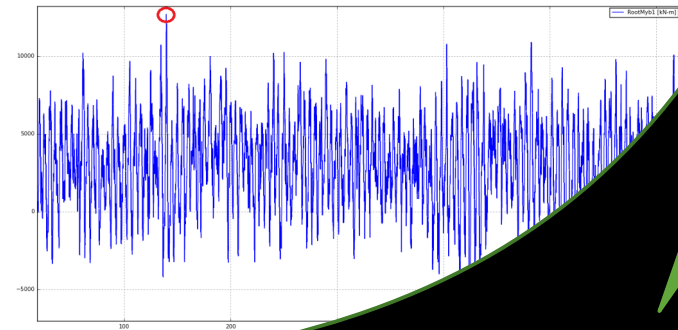
Postprocessing – Ultimate limit state (ULS)



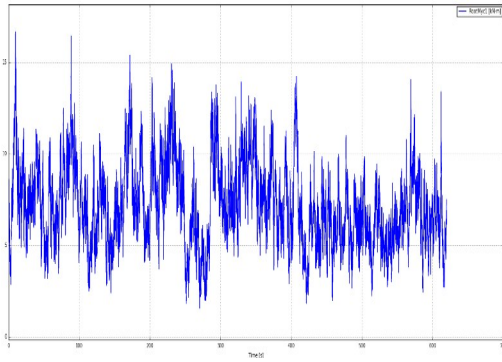
Contemporaneous load table: Blade 1 Root. Unfactored.

			RootFxc1	RootFyc1	RootFzc1	RootFyc1	RootMxc1	RootMyc1	RootMzc1	RootMxc1
			kN	kN	kN	kN	kNm	kNm	kNm	kNm
RootFxc1	Max	DLC22y_10020_19_300	4.84e+02	-1.89e+02	4.36e+02	5.19e+02	4.82e+03	1.78e+04	-7.61e+01	1.84e+04
RootFxc1	Min	DLC23_EOGO_55	-3.38e+02	5.74e+01	8.64e+02	3.43e+02	-3.33e+03	-1.40e+04	1.85e+02	1.44e+04
RootFyc1	Max	DLC62_12008_42_5_300	4.50e+01	4.40e+02	-1.49e+02	4.42e+02	-1.18e+04	6.94e+02	1.59e+02	1.18e+04
RootFyc1	Min	DLC62_12003_42_5_45	-7.26e+01	-4.84e+02	-1.70e+02	4.89e+02	1.30e+04	-1.91e+03	-3.95e+01	1.32e+04
RootFzc1	Max	DLC42_EOGO_56	-4.83e+00	-8.41e+01	1.07e+03	8.42e+01	5.42e+01	-2.63e+03	-1.27e+02	2.63e+03
RootFzc1	Min	DLC71_13002_34_30_0	-4.12e+01	-2.74e+02	-1.81e+02	2.77e+02	9.62e+03	-1.43e+03	1.88e+01	9.72e+03
RootFyc1	Max	DLC22y_10023_25_300	4.65e+02	-2.55e+02	4.88e+02	5.30e+02	6.72e+03	1.64e+04	-5.83e+01	1.77e+04
RootFyc1	Min	DLC71_13005_34_210_30	-3.73e-04	1.78e-02	-1.46e+02	1.79e-02	-1.01e+03	1.39e+02	9.19e+01	1.02e+03
RootMxc1	Max	DLC62_12003_42_5_45	-7.28e+01	-4.83e+02	-1.70e+02	4.89e+02	1.30e+04	-1.91e+03	-3.98e+01	1.32e+04
RootMxc1	Min	DLC62_12006_42_5_270	3.35e+01	4.38e+02	-1.60e+02	4.39e+02	-1.26e+04	6.75e+02	2.28e+02	1.26e+04
RootMyc1	Max	DLC22y_10020_19_300	4.84e+02	-1.89e+02	4.36e+02	5.19e+02	4.82e+03	1.78e+04	-7.61e+01	1.84e+04
RootMyc1	Min	DLC23_EOGO_55	-3.36e+02	5.00e+01	8.69e+02	3.40e+02	-3.12e+03	-1.41e+04	1.89e+02	1.44e+04
RootMzc1	Max	DLC62_12003_42_5_225	1.20e+01	3.96e+02	-1.68e+02	3.96e+02	-1.16e+04	4.28e+02	3.41e+02	1.17e+04
RootMzc1	Min	DLC62_12010_42_5_150	-8.92e+01	-3.53e+02	-1.72e+02	3.65e+02	1.03e+04	-1.72e+03	-3.33e+02	1.05e+04
RootMxc1	Max	DLC22y_10020_19_300	4.84e+02	-1.89e+02	4.36e+02	5.19e+02	4.82e+03	1.78e+04	-7.61e+01	1.84e+04
RootMxc1	Min	DLC21_10033_21_350	9.53e+00	-2.70e+01	-1.54e+02	2.86e+01	-3.77e-01	-1.79e-01	-1.88e+01	4.17e-01

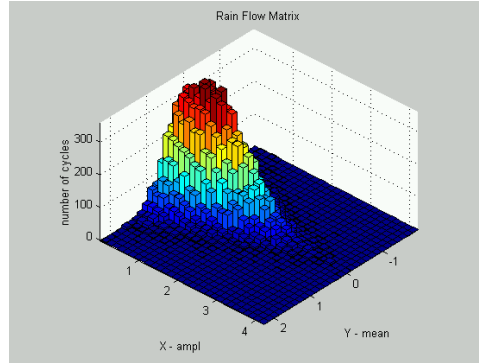
- Extract ultimate loads, deflections, clearance
 - MExtremes or Pcrunch
- Contemporaneous loads tables
- Apply binning, safety factors according to standards



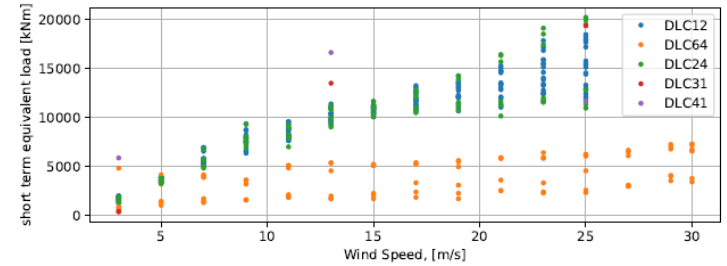
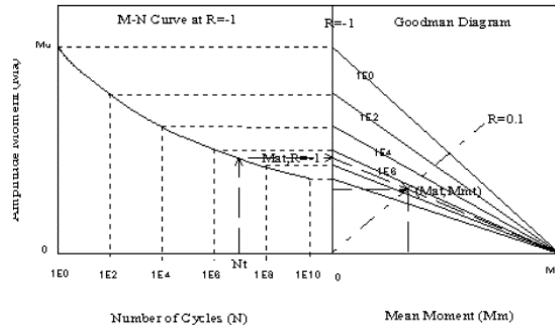
Postprocessing – Fatigue limit state (FLS)



Rainflow counting



Goodman correction



$$DEL = \frac{\sum_i n_i S_i^m}{n_{ref}}$$

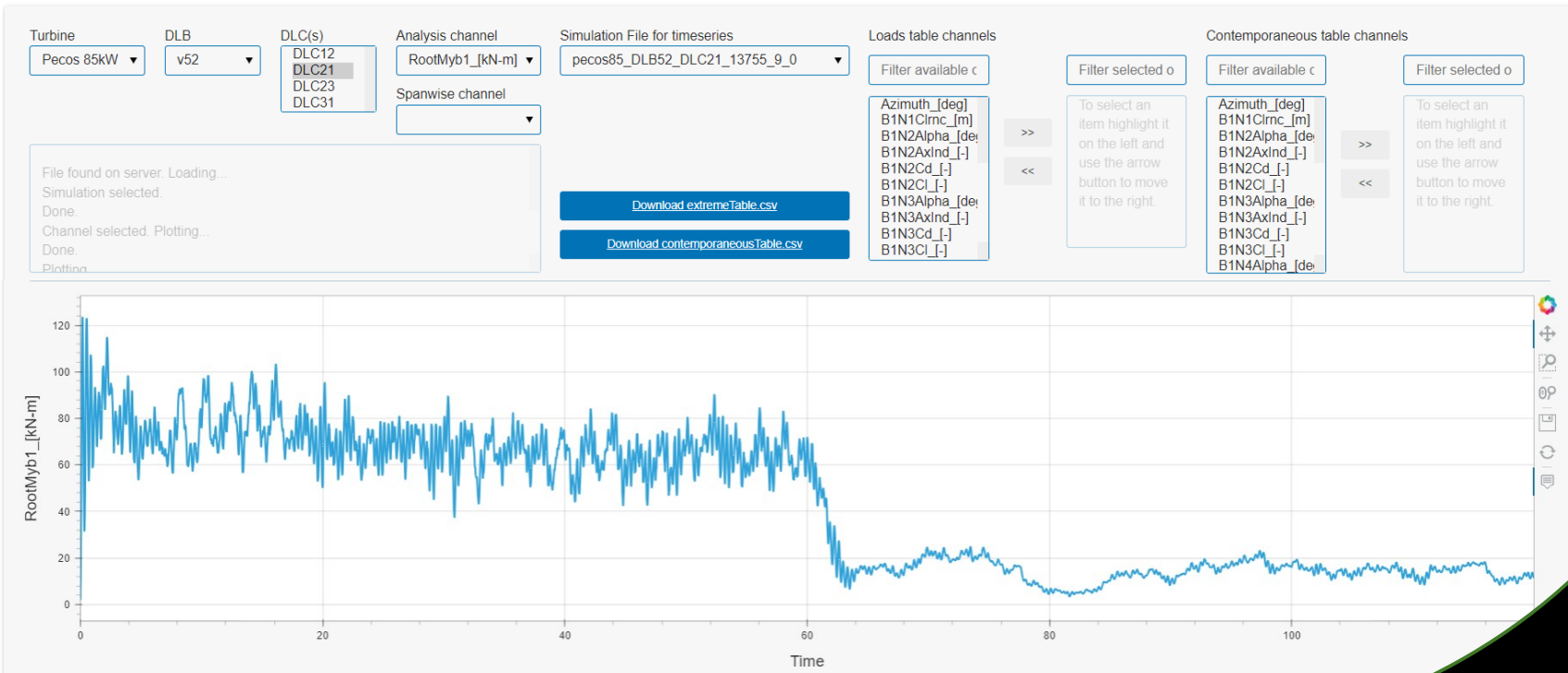
Damage Equivalent Load
(single m)

- Calculate damage equivalent loads/stresses
 - MLife or openfast-toolbox



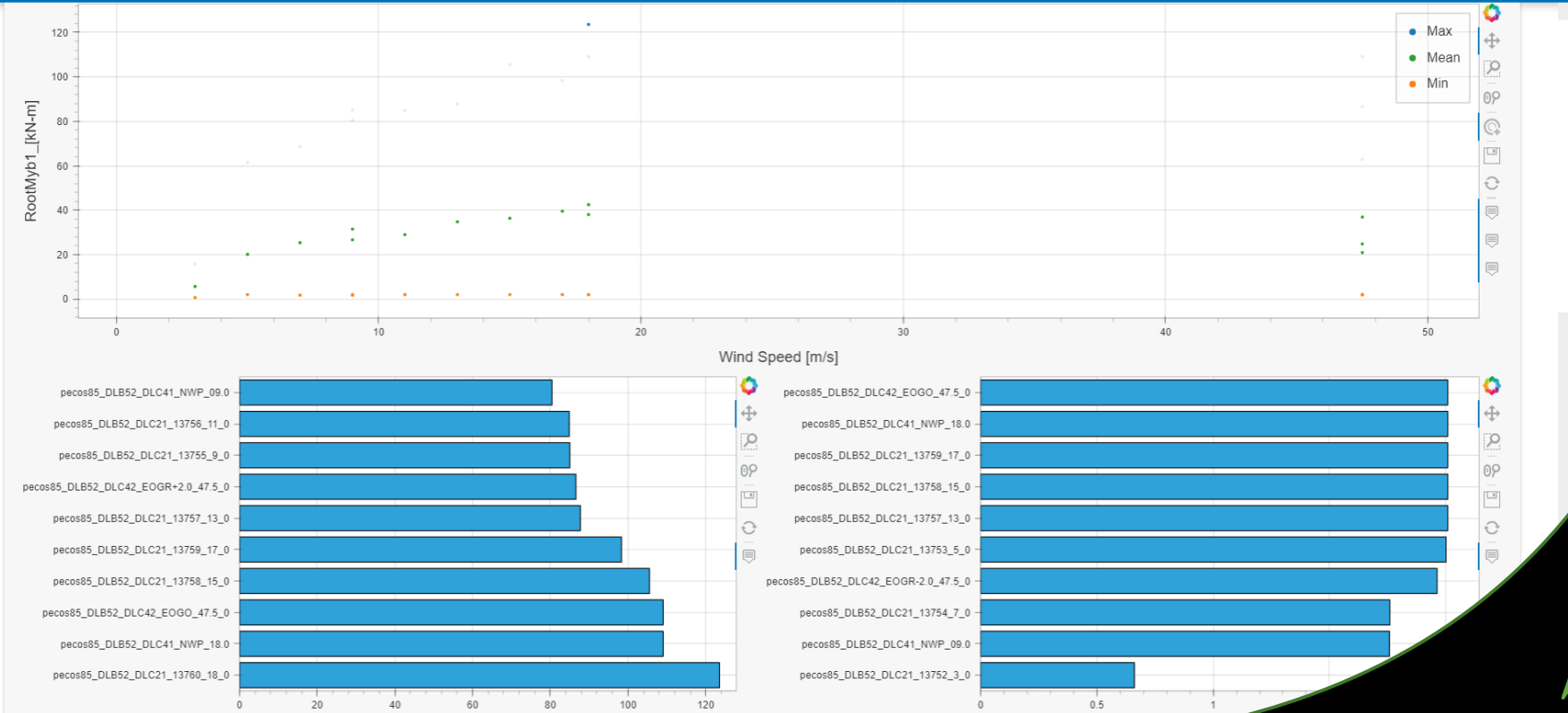
Interactive simulations analysis dashboard

Northwind Engineering - Aeroelastic Simulation Analysis Dashboard



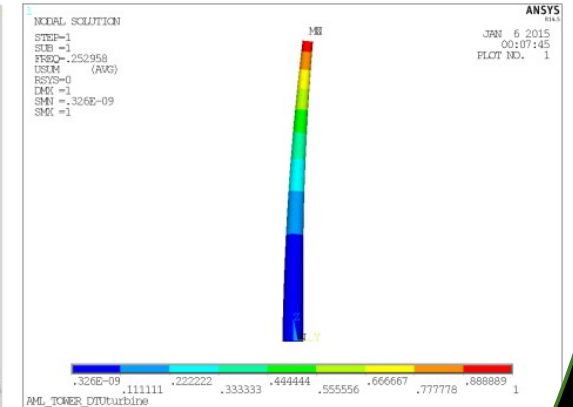
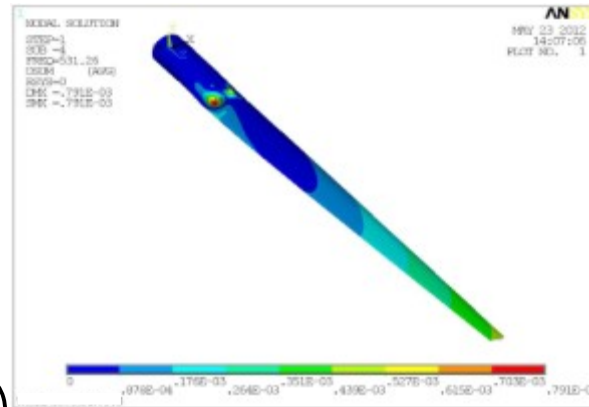
Interactive simulations analysis dashboard

Northwind Engineering - Aeroelastic Simulation Analysis Dashboard

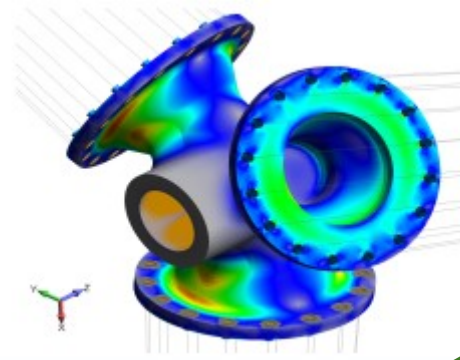


Structural verification of components

- Things to watch out for:
 - Sensitivity to Mesh
 - Boundary Conditions
 - Load Distribution
 - Failure Criteria (e.g. Tsai-Wu)
 - Buckling (linear vs. nonlinear)
 - Welds and stress concentrations
 - Bolts



Ref. R. Damiani (2021)



Hub FEA, Source Predictive Engineering



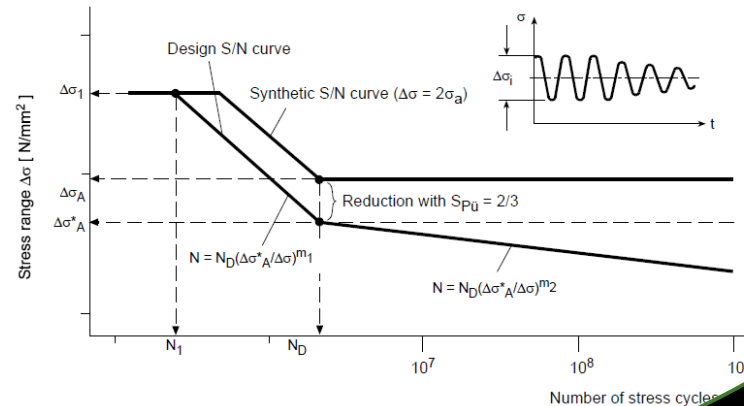
Structural verification of components

- Analytical options

	Circular blade root	Rectangular blade root	Rotor shaft
Axial load	$\sigma_{zB} = \frac{F_{zB}}{A_B}$	$\sigma_{zB} = \frac{F_{zB}}{A_B}$	$\sigma_{x\text{-shaft}} = \frac{F_{x\text{-shaft}}}{A_{\text{shaft}}}$
Bending	$\sigma_{MB} = \frac{\sqrt{M_{xB}^2 + M_{yB}^2}}{W_B}$	$\sigma_{MB} = \frac{M_{xB}}{W_{xB}} + \frac{M_{yB}}{W_{yB}}$	$\sigma_{M\text{-shaft}} = \frac{M_{\text{shaft}}}{W_{\text{shaft}}}$
Shear	Negligible	Negligible	$\tau_{M\text{-shaft}} = \frac{M_{x\text{-shaft}}}{2W_{\text{shaft}}}$
Combined (axial + bending)	$\sigma_{\text{eqB}} = \sigma_{zB} + \sigma_{MB}$		$\sigma_{\text{eq}} = \sqrt{(\sigma_{x\text{-shaft}} + \sigma_{M\text{-shaft}})^2 + 3\tau_{M\text{-shaft}}^2}$

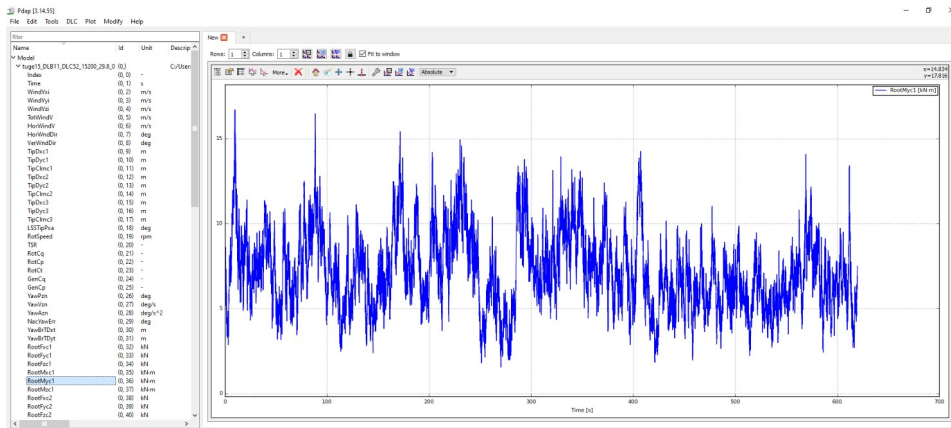
- Evaluate damage and check for safety

- Eurocodes, AISC
- GL Guideline for the certification of wind turbines



Other useful tools

- Scripts to setup models, run simulations and postprocess the results
 - `openfast_toolbox` DTU Wind Energy Toolbox
- Visualization of simulation results (and more)
 - `PyDatView` Pdap

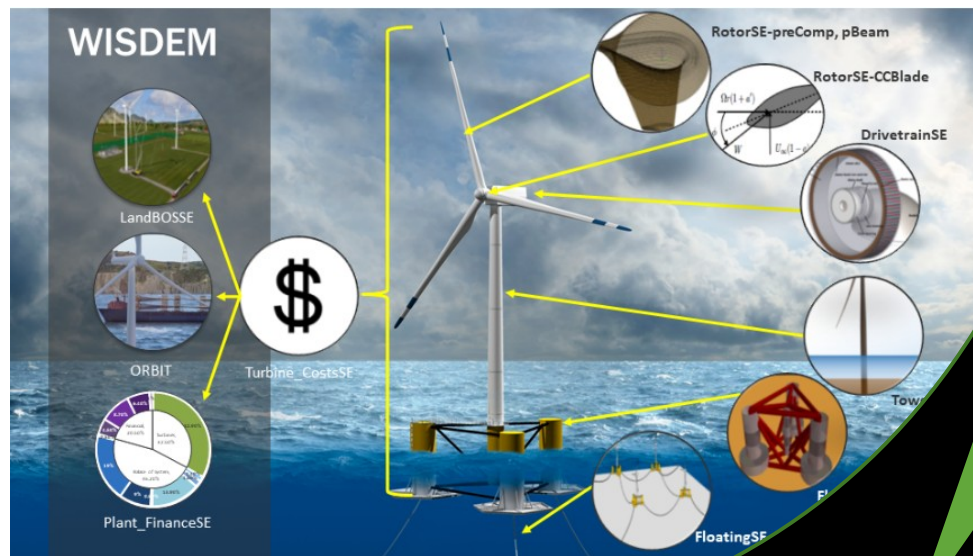


Other useful tools

- Wind Energy Library (welib)
 - Suite of python and matlab tools aerodynamics, controls, structure/elasticity

Airfoils - 3D correction	Airfoils - MGH dynamic stall model	Airfoils - Oye dynamic stall model	Airfoils - Wagner function	Beam - Analytical mode shapes of a beam
Beam - Analytical mode shapes different BC	BEM Steady - High thrust correction	BEM Steady - Performance curve	BEM Steady - CP-lambda-pitch	BEM Theory - Ideal rotor planform
BEM Unsteady - Prescribed surge motion	Dynamic Inflow (Oye) - induction step	FAST - interpolate radial time series	FAST - Average radial outputs	FEM - mode shapes of tower
FEM - mode shapes of a beam	Hydro - Wave kinematics	Hydro - Jonswap spectrum	Hydro - wave generation	Hydro - Morison loads on monopile

- WISDEM
 - A set of models for assessing overall wind plant cost of energy (COE)
 - Component and system optimization



Thanks!



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