

Overview of CGI/Dynos/PHIL Platform

Przemyslaw Koralewicz, Robb Wallen,
and Vahan Gevorgian
November 16, 2018

5th Annual International Workshop on
Grid Simulator Testing of Energy Systems and Wind
Turbine Powertrains

National Wind Technology Center

New: 430-kW PV array

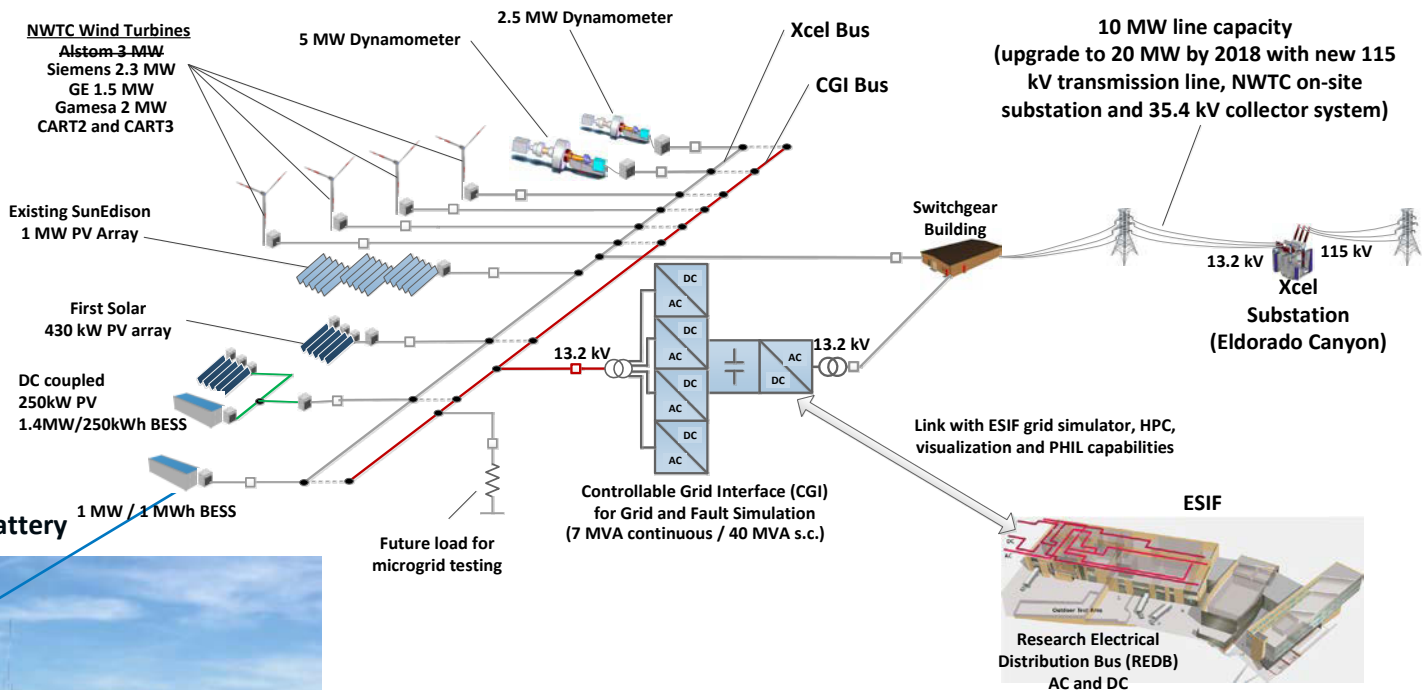


Source: NREL / Dennis Schroeder (40806)

New: 1-MW/1-MWh battery



Source: NREL



Source: NREL

NWTC Dynamometers

Specifications



Source: NREL/Mark McDade (27249)



Source: NREL/Robb Wallen (17400)



Source: NREL/Dennis Schroeder (25887)

2.5-MW Dyno

- 2.5 MW (on the low-speed shaft)
- 17–31 rpm (at full power)
- 1.64 MNm (1.2 M ft-lb) max torque
- Non-torque loads, 3 degrees of freedom
- 50-t crane, 30-ft (9-m) hook height
- 12.2 x 15.2-m test bay
- 0–6-degree adjustable-drive table tilt.

5-MW Dyno

- 5.8 MW (on the low-speed shaft)
- 12–24 rpm (at full power)
- 4.6 MNm (3.4 M ft-lb) max torque
- Non-torque loads, 5 degrees of freedom
- Dual 75-t cranes, 45-ft (14-m) hook height
- 20 x 12-m test bay
- 5-degree fixed-drive table tilt.

2.5-MW Dynamometer Projects

- Multiple projects in 2017–2018 for validating wind turbine power train low-voltage ride-through (LVRT) response to foreign grid codes (50 Hz using controllable grid interface [CGI])
- Preinstallation verification of Gearbox Reliability Collaborative 1.5 data acquisition system. The gearbox was installed in the U.S. Department of Energy-owned (DOE-owned) GE 1.5-MW turbine and is subjected to grid events using the CGI.
- Year 2019 projects include validation of two different wave energy devices.

GE 1.5-MW high-speed shaft instrumentation checkout at 2.5-MW dynamometer.



Source: NREL/Mark McDade (49050)



Source: NREL / Jonathan Keller (49498)

Installation of instrumented gearbox at NWTC.

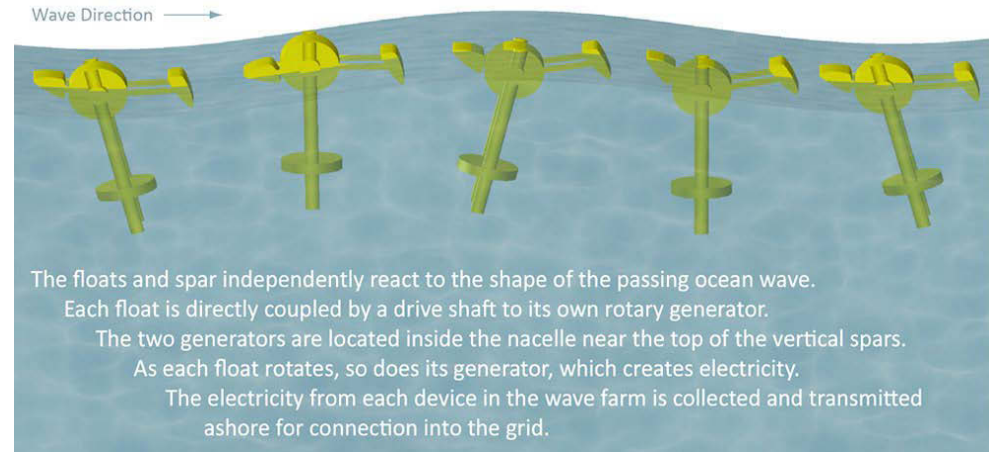
5-MW Dynamometer Projects

- 2016–2018: Validation of the Columbia Power Technologies (C-Power) utility-scale wave energy device. The device was tested using realistic, oscillating, bidirectional speed and torque profiles. Testing was complete as of Nov. 2018.
- 2018: Validation of multimewatt, medium-voltage, doubly-fed induction generator power train via direct coupling with 5-MW motor
- 2019: Projects include upgrading non-torque loading system to achieve 10-MNm moment capacity and potential wind turbine power train tests
- 2019: The 2.5-MW and 5-MW facilities will be upgraded with additional 13.2-kV medium-voltage feeds selectable between CGI or Xcel utility.



Source: NREL / Mark McDade (44103)

C-Power wave energy device installation at the NREL 5-MW dynamometer.



Source: C-Power website / www.columbiapwr.com/how-it-works/

C-Power wave energy device installation at the NREL 5-MW dynamometer C-Power

NWTC 7-MVA Controllable Grid Interface



Source: NREL / Mark McDade

Power rating

- 7-MW continuous
- 39-MVA short-circuit capacity (for 2 s)
- 4-wire, 13.2 kV.

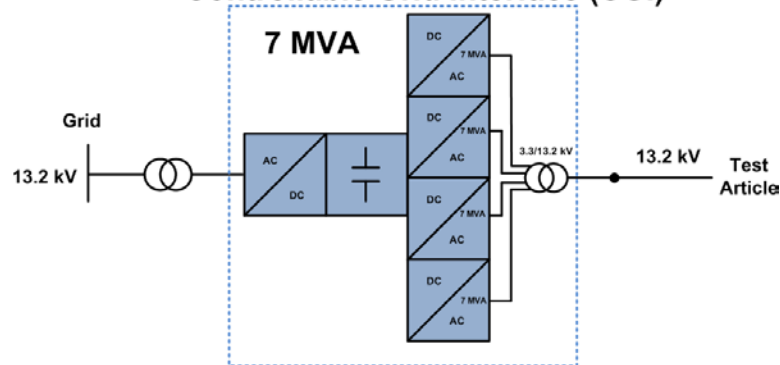
Frequency control

- Fast output frequency control (3 Hz/s) within a range of 45–65 Hz
- 50/60-Hz operation
- Can simulate frequency conditions for any type of power system.

Voltage control (no load total harmonic distortion <2%)

- Balanced and unbalanced voltage fault conditions (zero-voltage ride-through and 130% high-voltage ride-through [HVVRT])—independent voltage control for each phase on 13.2-kV terminals
- Response time: 1 ms (from full voltage to zero, or from zero back to full voltage)

Controllable Grid Interface (CGI)



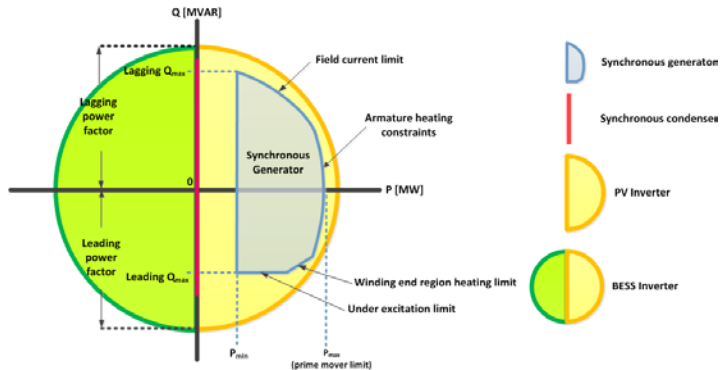
- Long-term symmetrical voltage variations ($\pm 10\%$) and voltage magnitude modulations (0–10 Hz)—subsynchronous resonance conditions
- Programmable impedance (strong and weak grids).

Real-time digital simulator (RTDS) – power-hardware-in-the-loop (PHIL) capability

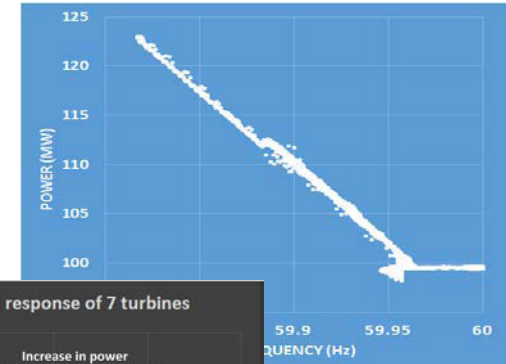
Open-Loop Single PCC: DER Validation

Testing of grid connected inverters and tightly coupled generation mixes

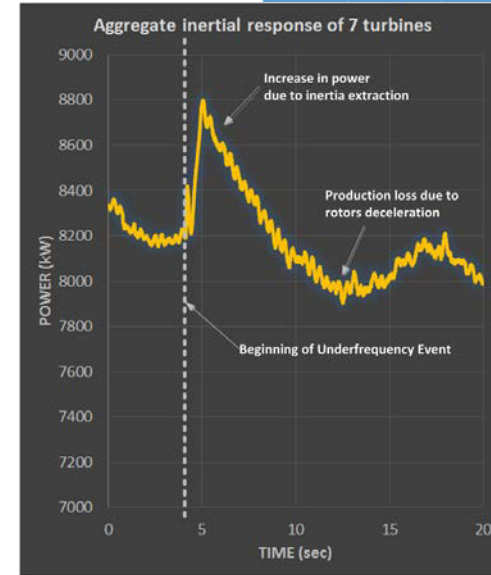
- Testing of frequency responses
- Characterization of droop characteristics
- LVRT/HVRT testing
- Full 4Q operation testing
- Models validation
- Wide spectrum analysis (impedance).



Source: NREL

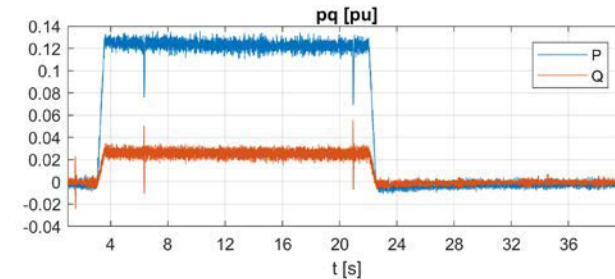
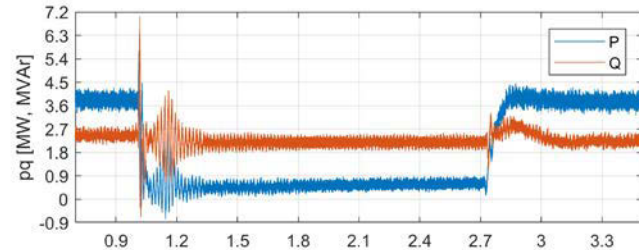
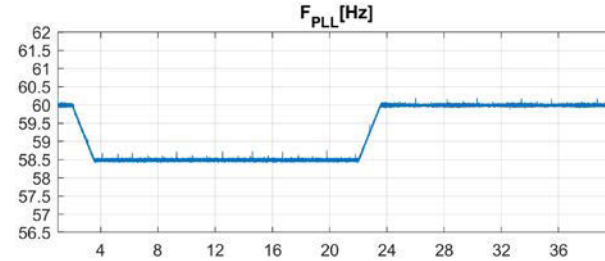
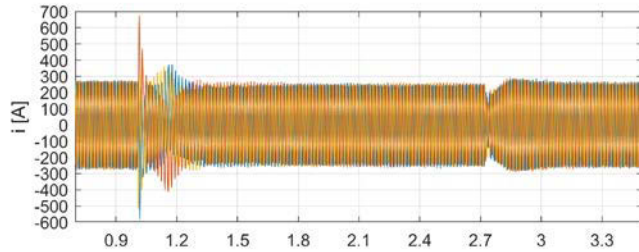
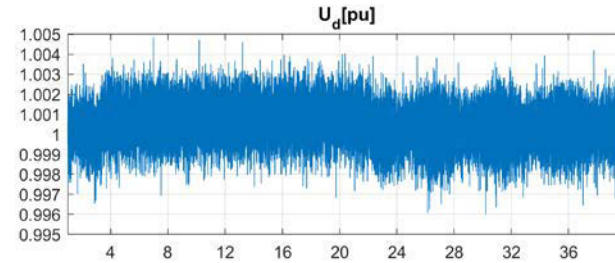
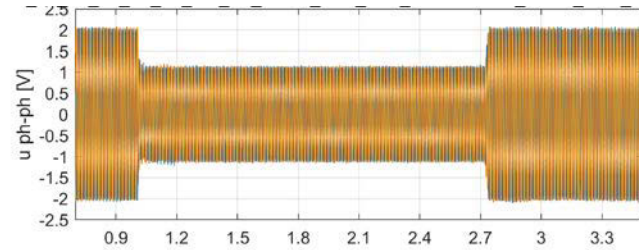


Source: NREL

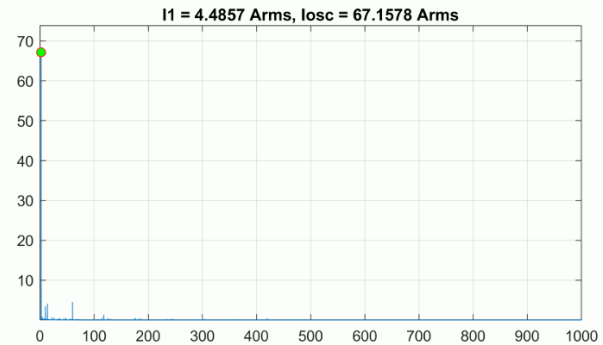
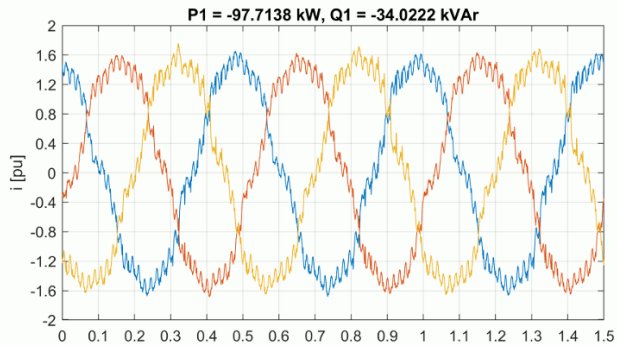
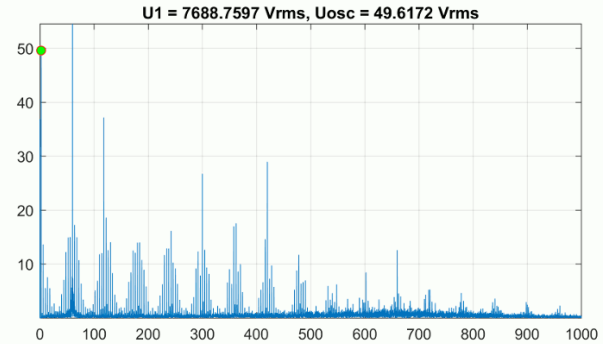
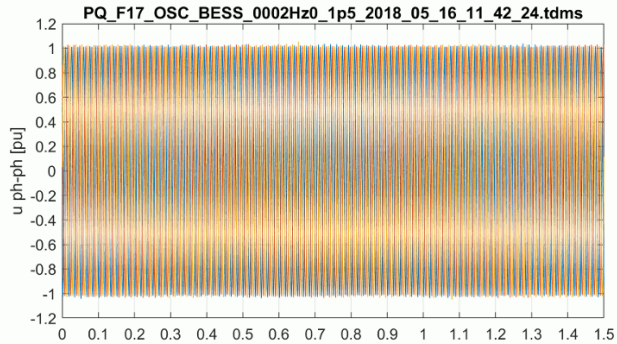


Source: NREL

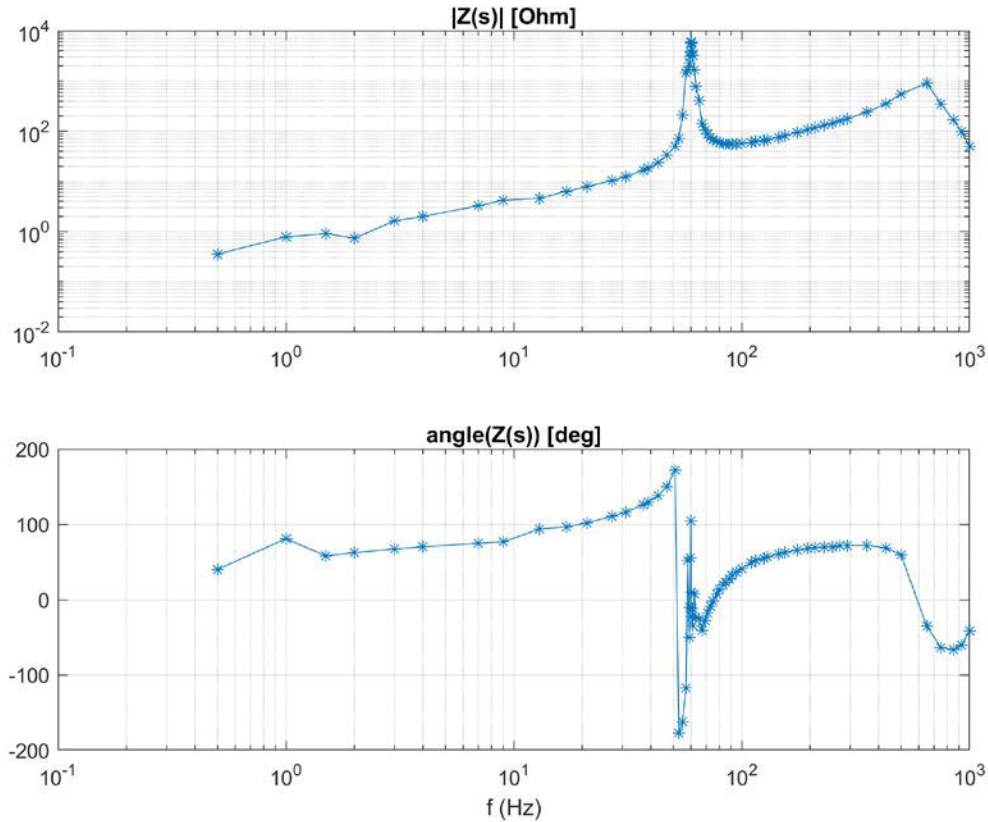
Open-Loop Single PCC: DER Validation Examples



Impedance Measurements



Impedance Measurements



Source: NREL

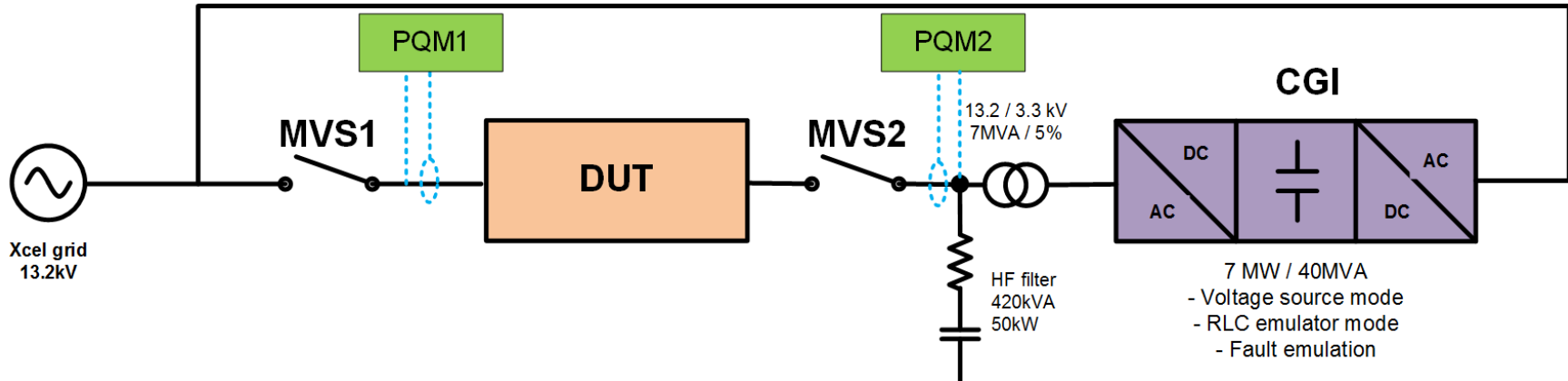
Open-Loop Double PCC: DER Validation

Example device:

- Microgrid feeder breakers
- Power electronic tie controllers
- AC/AC converters
- Protective relays/synchronization check logic
- Transformers.

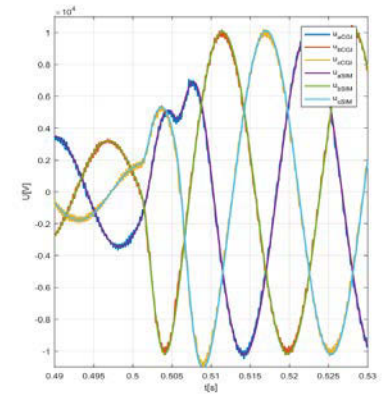
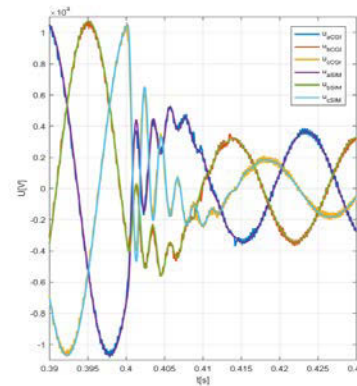
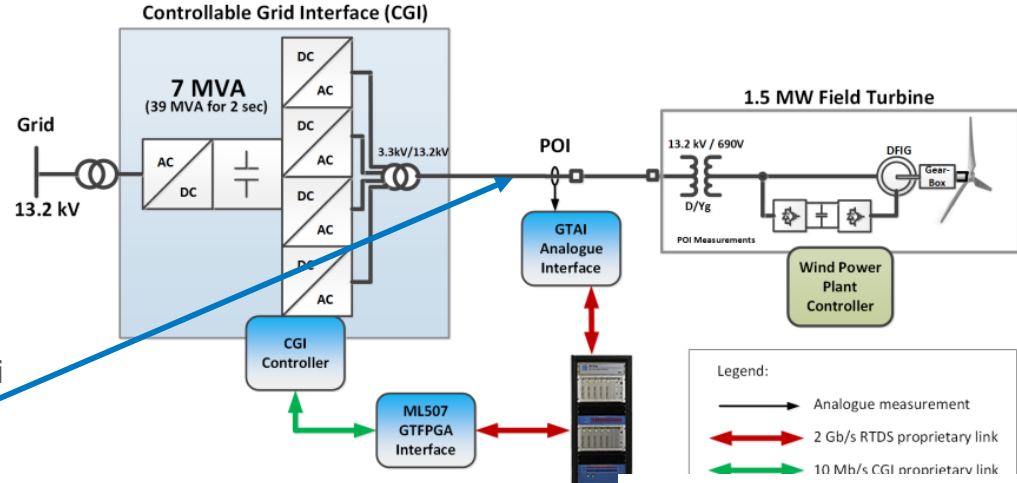
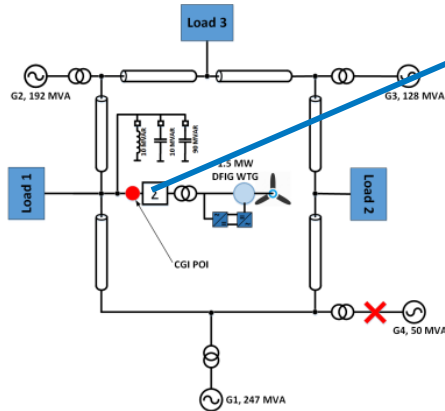
Capabilities:

- Ability to generate any angle difference
- Ability to generate independent frequencies
- Fault testing at CGI side possible
- CGI side can run as voltage or current source inverter (VSI or CSI).

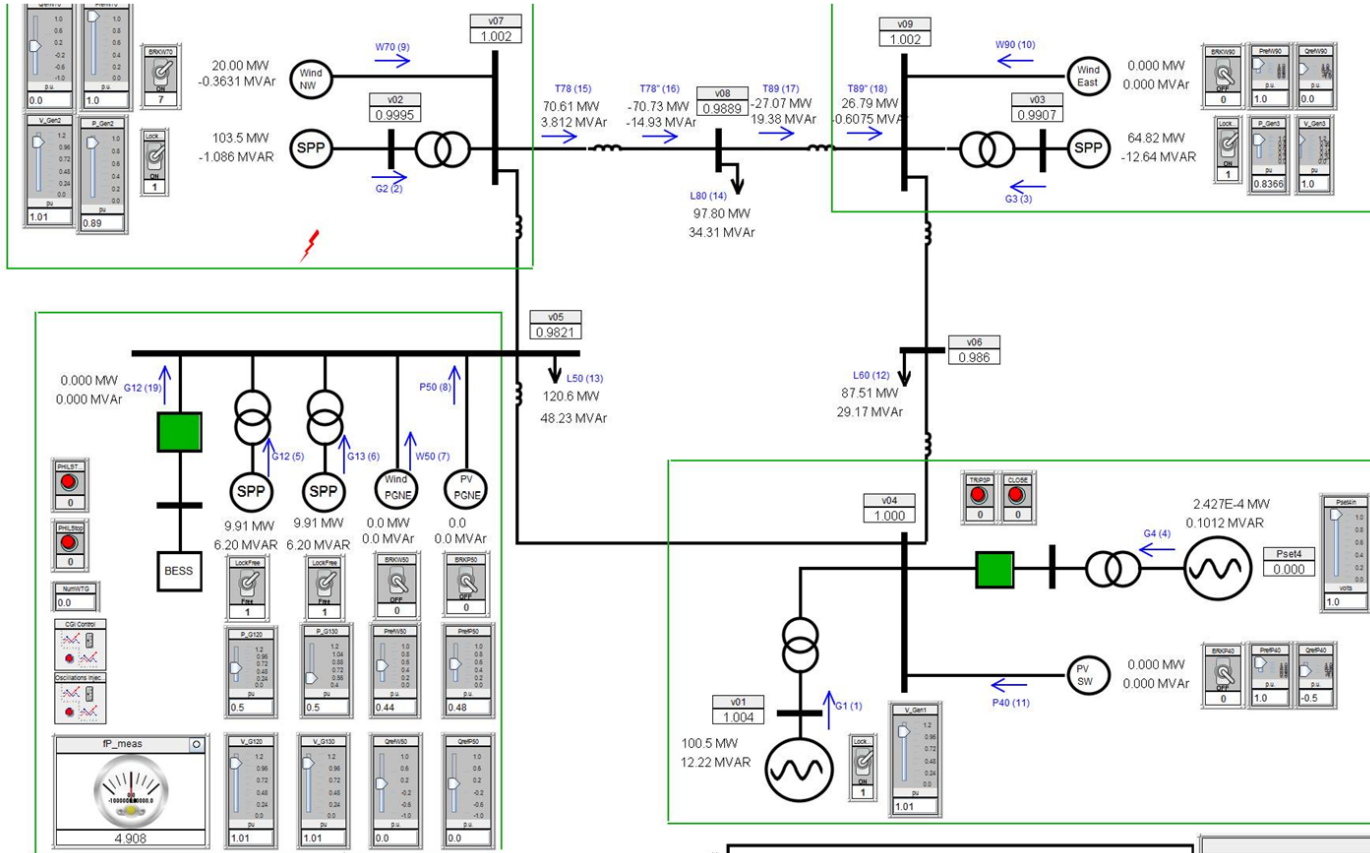


Closed-Loop Testing: PHIL

- Voltage from simulation is tracked by CGI in real time.
- Current measured is injected back to RTDS model.
- Allows testing device under test under various grid conditions and events (e.g., microgrids)
- Distances between RTDS point of interconnection and CGI ca. 300 ft
- 2 Gb/s RTDS optical link: Glass Optical Fiber
- 10 Mb/s CGI-ABB proprietary link: Plastic Optical Fi
- Data exchange every 25 us (40 kHz).



RTDS 9-Bus Transmission Model



Source: NREL

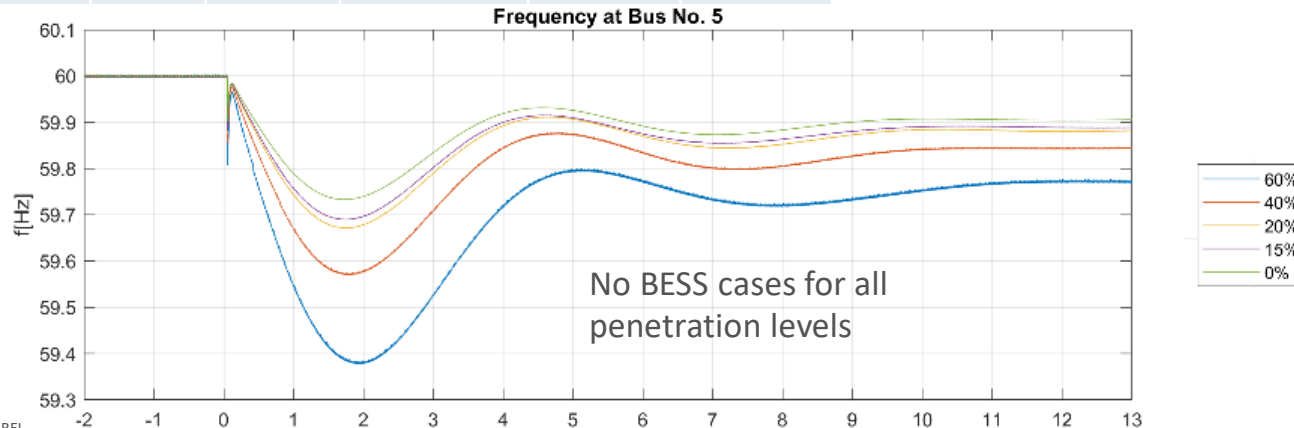
Assumptions Used for PHIL Testing of 9-Bus System with BESS

Renewable penetration	Conventional Generators			PV & Wind	Loads	Total H
	P_{Gn} , MW	H_G , sec	$P_{Gdispatch}$, GW	P_{Rn} , GW	Loads GW	H_{Tot}
60%	53.3	4	40	60	100	2.13
40%	80	4	60	40	100	3.20
20%	106.7	4	80	20	100	4.27
15%	113.3	4	85	15	100	4.53
0%	133.3	4	100	0	100	5.33

$$H_{Tot} = \frac{H_G P_{Gn} + H_B P_{Bn} + H_R P_{Rn}}{P_{Tot}}$$

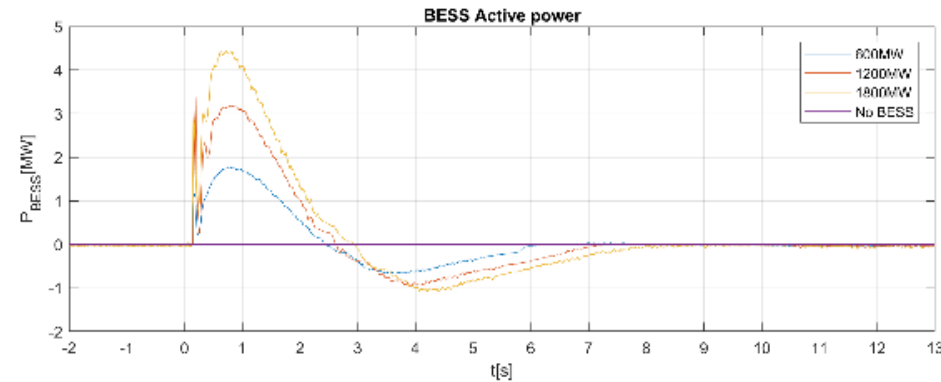
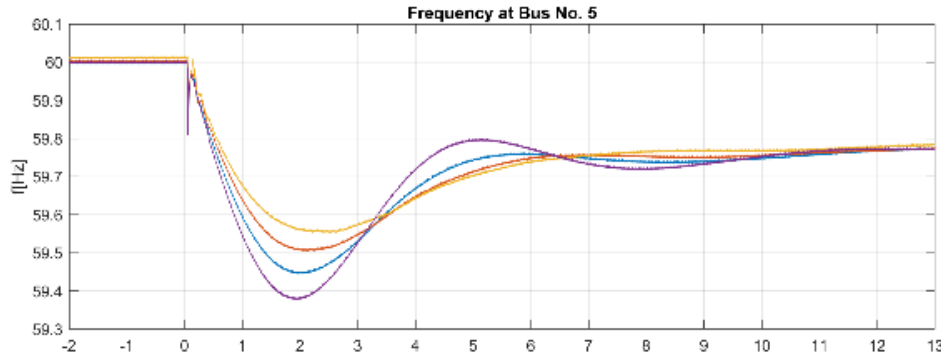
$$H_R = 0$$

Generation loss = 3.8 GW/3.8%



Source: NREL

Renewable Penetration 60%: Inertia



Source: NREL

Battery scaling assuming 100-GW system:

- 600 MW -> 0.6%
- 1200 MW -> 1.2%
- 1800 MW -> 1.8%

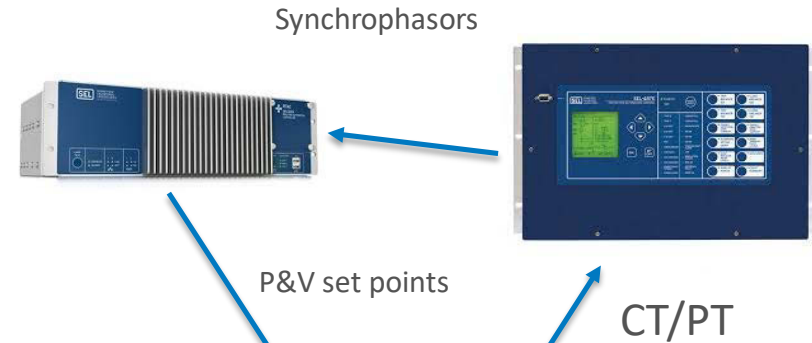
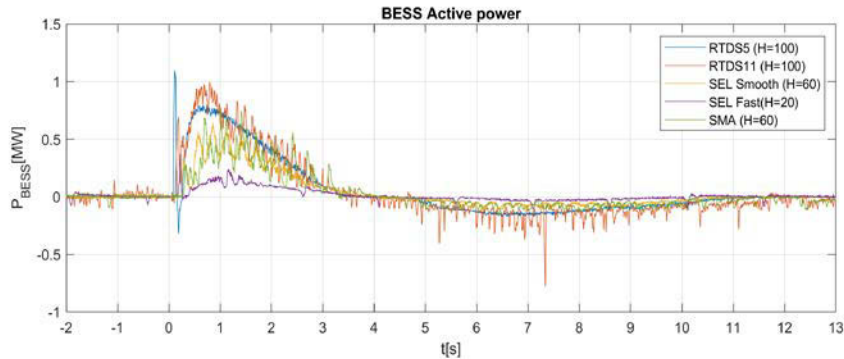
BESS controlled proportional to ROCOF using LabView controller. $H=50$ s

Frequency response improves with increasing BESS installed capacity at 60% renewable penetration.

BESS [MW]	0	600	1200	1800
60%	2.13	2.43	2.73	3.03
40%	3.20	3.50	3.80	4.10
20%	4.27	4.57	4.87	5.17
15%	4.53	4.83	5.13	5.43
0%	5.33	5.63	5.93	6.23

Renewable Penetration: RTAC Inertia Controller

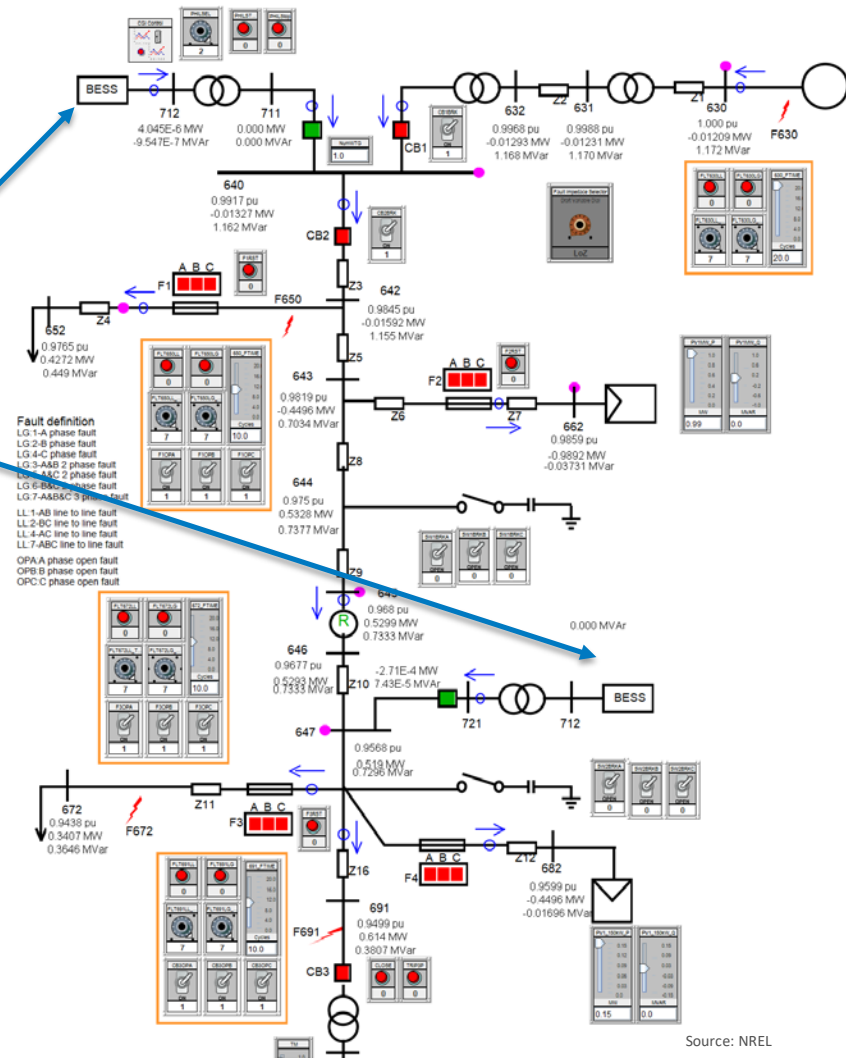
- Implemented inertia controller based on commercial of-the-shelf devices
- Found limitations on maximum inertia depending on where frequency is measured
- Tested various frequency sources.



Source: NREL

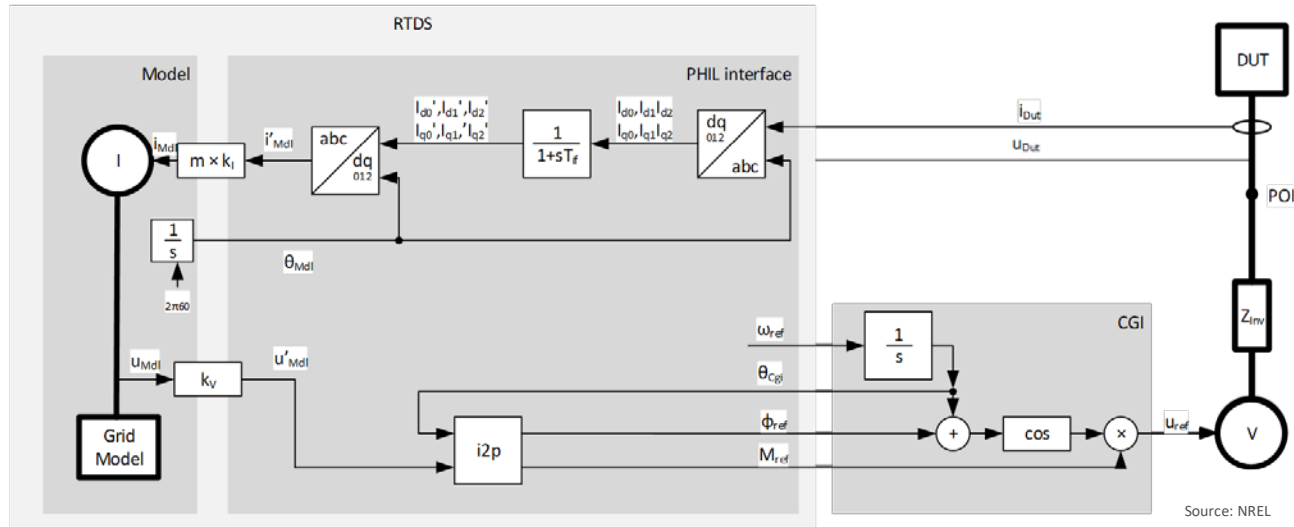
About RTDS Distribution Model

- Model based on data from PG&E
- BESS can be added using PHIL to two locations:
 - Bus 640
 - Bus 647.
- Four fault locations used for fault emulation:
 - Bus 630: Fault at transmission level
 - Bus 650: Fault at load branch—unfused
 - Bus 672: Fault at load branch—fused (F3)
 - Bus 691: Fault at motor branch—unfused
- Faults can be:
 - 1 x L-G, 2 x L-G, 3 x L-G, 1 x L-L, 2 x L-L, open phase
 - Low impedance: 0.1 Ohm
 - High impedance: 10 Ohm.



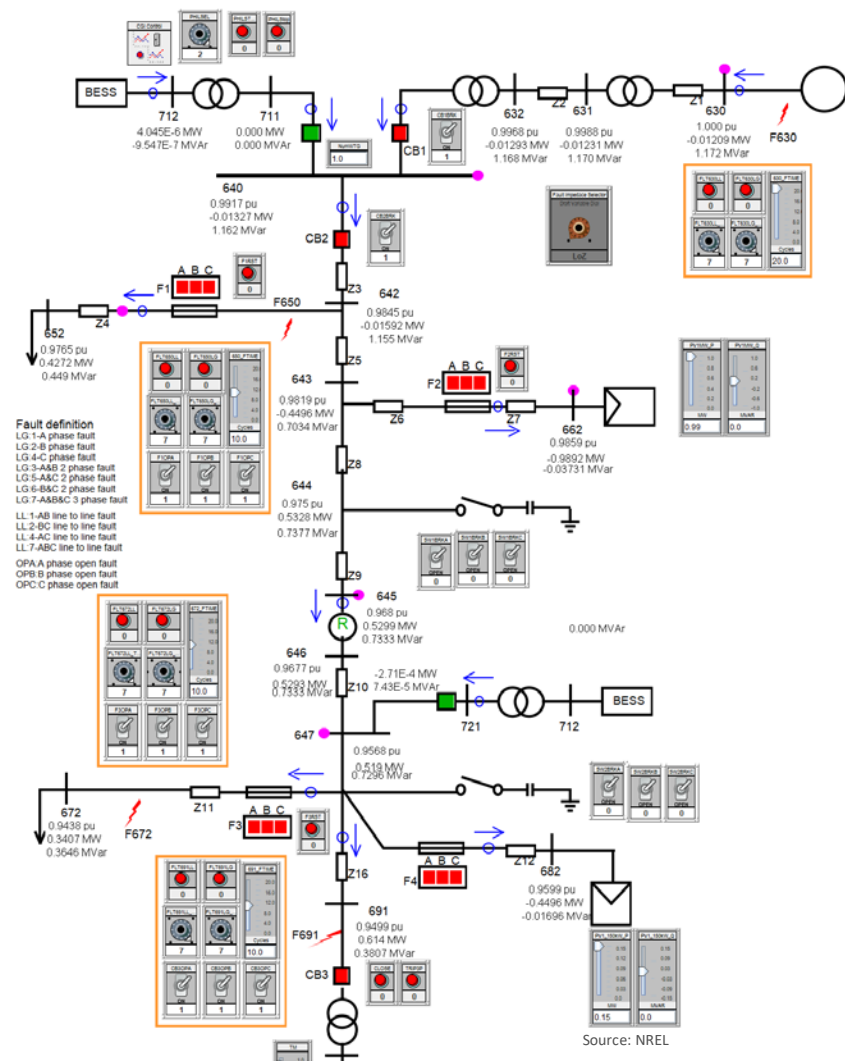
CGI-RTDS PHIL Interface

- Instantaneous voltage measured in model and commanded to CGI
 - Very fast tracking achieved thanks to instantaneous-to-phasor (I2P) algorithm
 - Compensated phase delay.
- Positive-, negative-, and zero-sequence current injection into model
 - Decoupled positive- and negative-sequence DQ current measurement
 - Filtered with 10-ms filter for high-frequency stability.

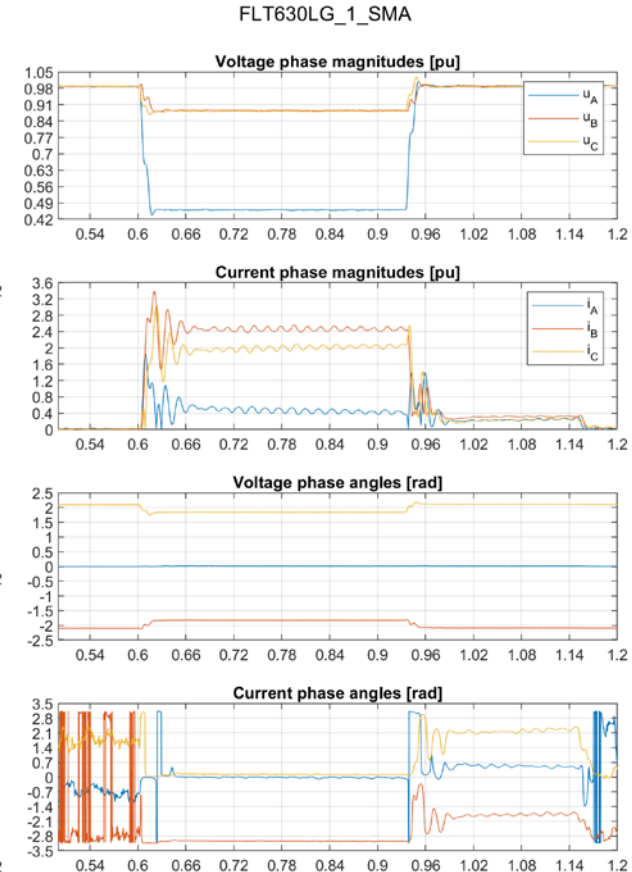
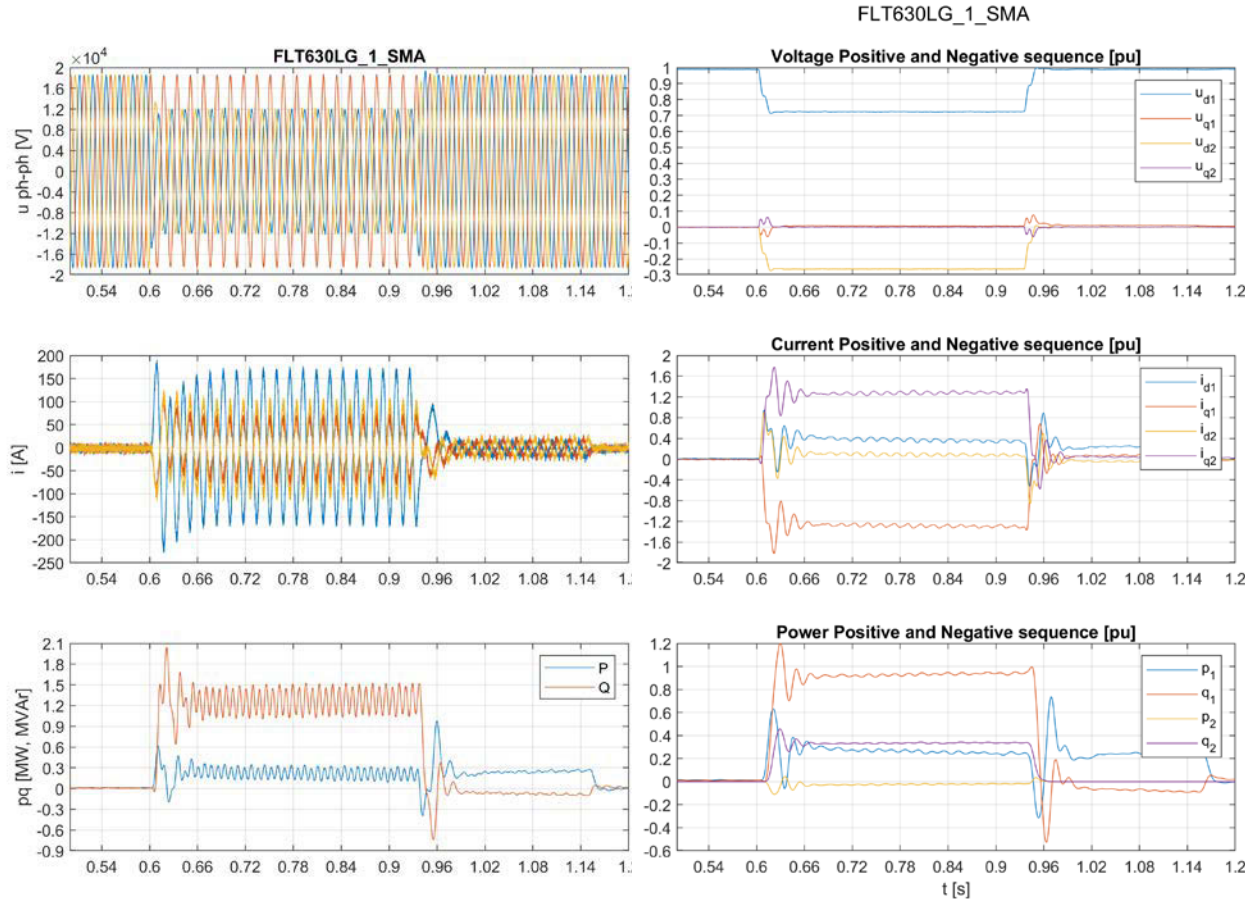


About RTDS Distribution Model

- RTDS automated script
- Total number of fault cases executed per script run (ca. 15 min): 53x
- For each test case, data were captured using RTDS:
 - 100-us resolution
 - 7 x 3 phase voltage measurements (magenta dots)
 - 12 x 3 phase current measurements (blue arrows)
 - 3-s data buffer
 - ~ 1.5 GB of data per run.



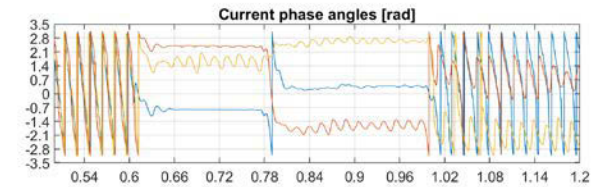
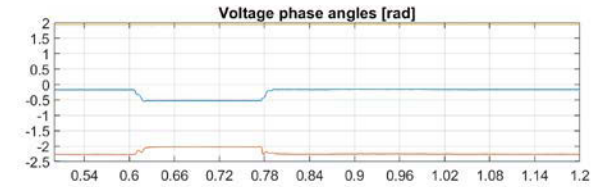
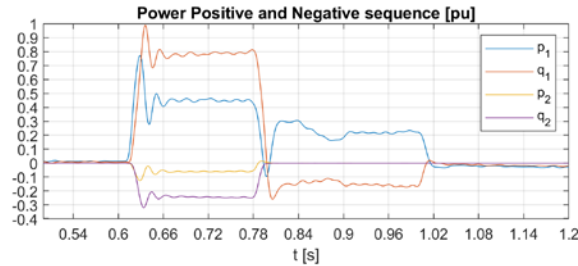
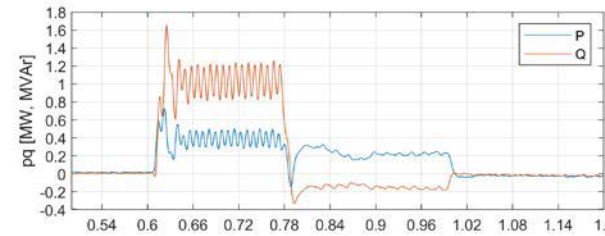
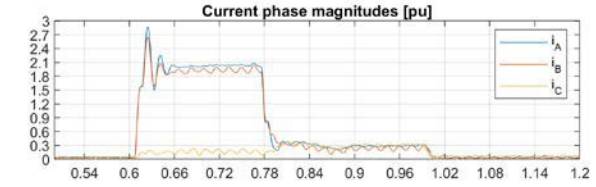
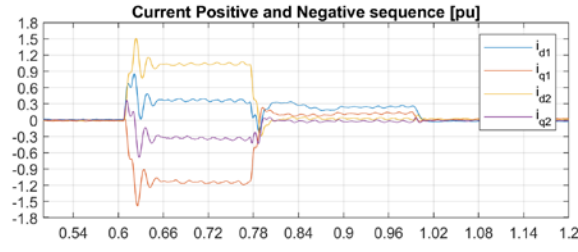
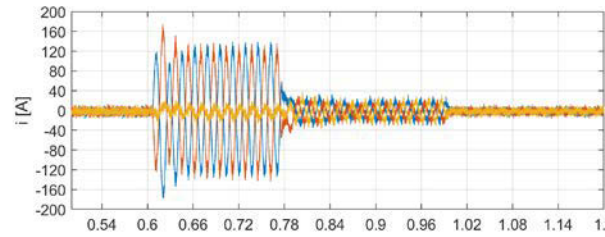
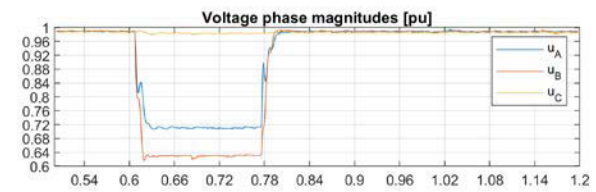
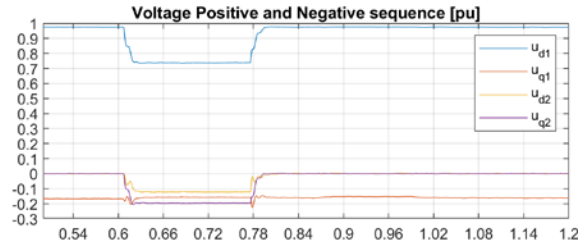
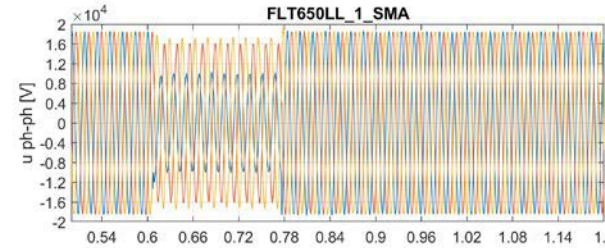
FLT630 Line A to Ground



FLT650 Line A to Line B

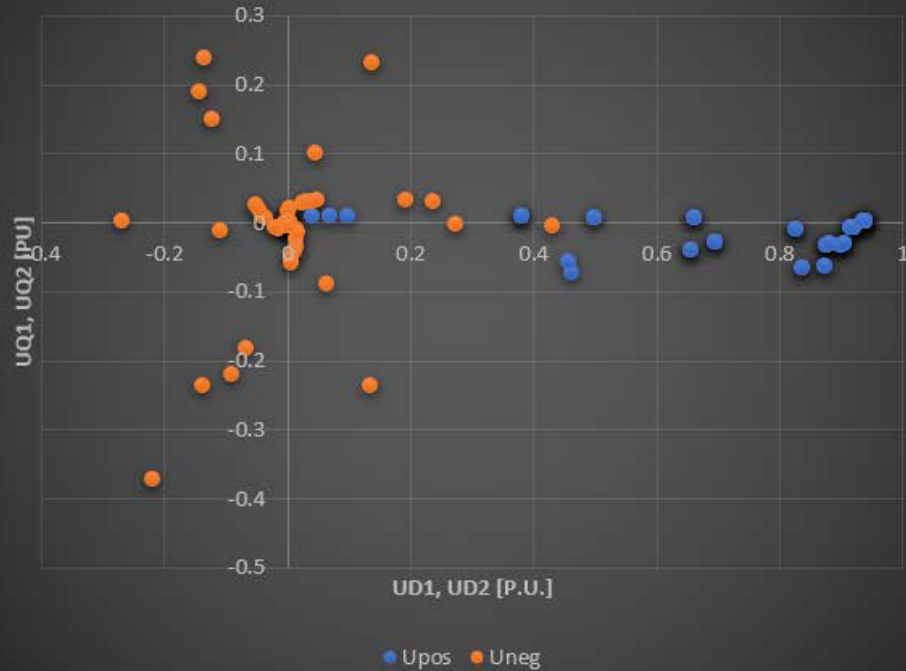
FLT650LL_1_SMA

FLT650LL_1_SMA

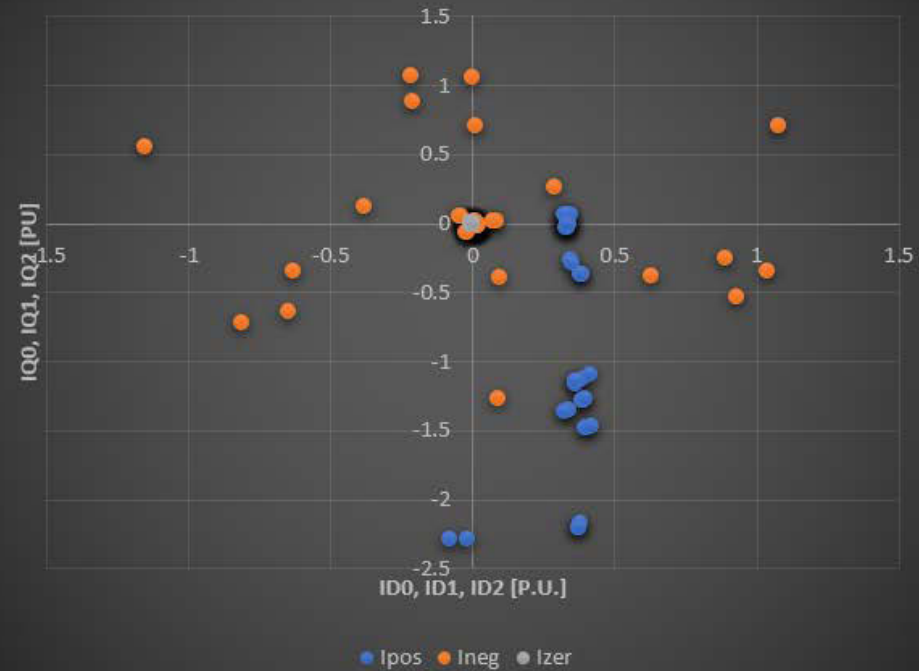


Spectrum of LVRT Voltage During Faults

Voltage at BESS during fault [p.u.]



Current at BESS during fault [p.u.]



Thank you

www.nrel.gov

NREL is a national laboratory of the U.S. Department of Energy, Office of Energy Efficiency and Renewable Energy, operated by the Alliance for Sustainable Energy, LLC.

