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DIPARTIMENTO DI
SCIENZE E TECNOLOGIE
AEROSPAZIALI


POLI-Wind

Cp-Max: an MDO framework for the design of wind turbines

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RESEARCH FRAMEWORK

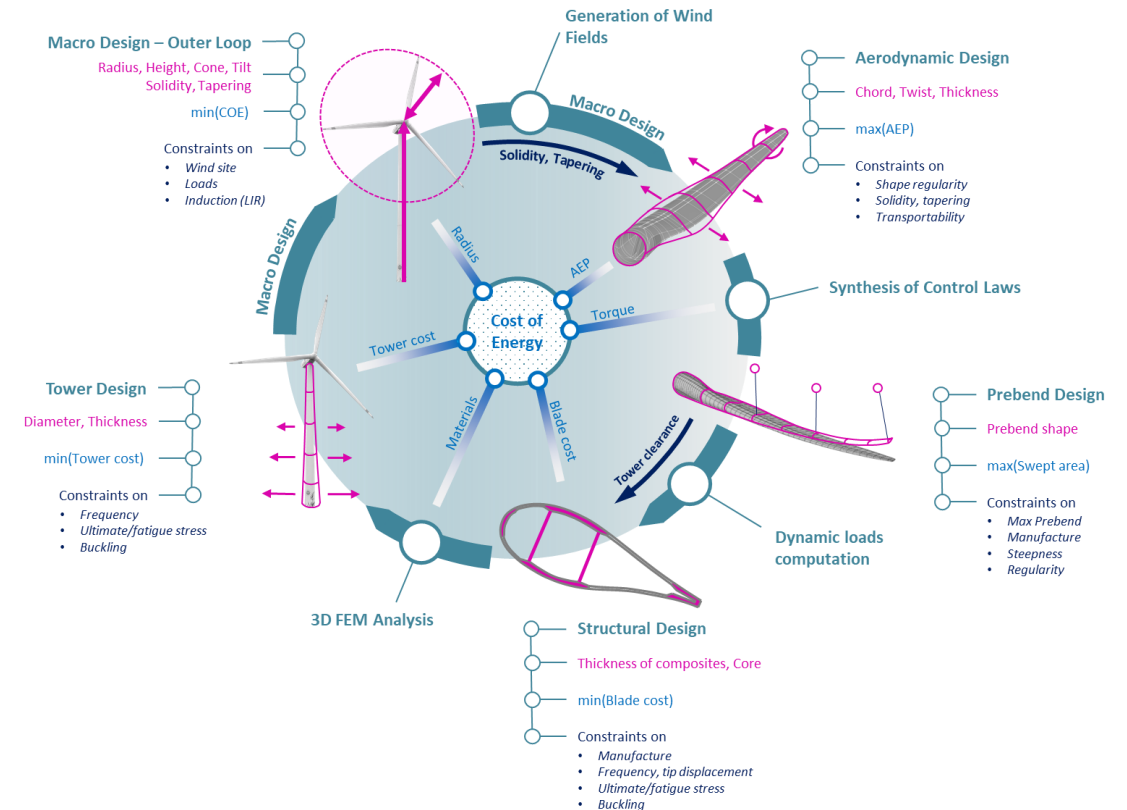
Research framework

- Wind turbines are steadily upscaling
- Some design challenges:
 - High flexibility of elements
 - Unsteady, non-uniform inflow
 - Increased aero-elastic couplings
 - Increased dynamic complexity



Research framework

- **Multi-disciplinary design algorithms (MDO):**
 - Improve physical description (*modelling fidelity*)
 - Implement a system-level design based on COE
 - Manage a wide number of different variables
 - Significant research in the last years



CP-MAX: A MULTI-DISCIPLINARY DESIGN PHILOSOPHY

Cp-Max Timeline



2011: Roll-out of the 2MW-45m blade

2012: Roll-out of the 700kW-23m blade



2014: Roll-out of the 330kW-16m blade

- 2007: First implementation, parametric design only
- 2011: External 3D FEM module
- 2012 - 2015: Studies about aero-structural design
- 2016: Cp-Max in its new multi-level architecture
- 2017: Prebend design module
- 2017-2019: Extensive testing and design studies

Cp-Max development team



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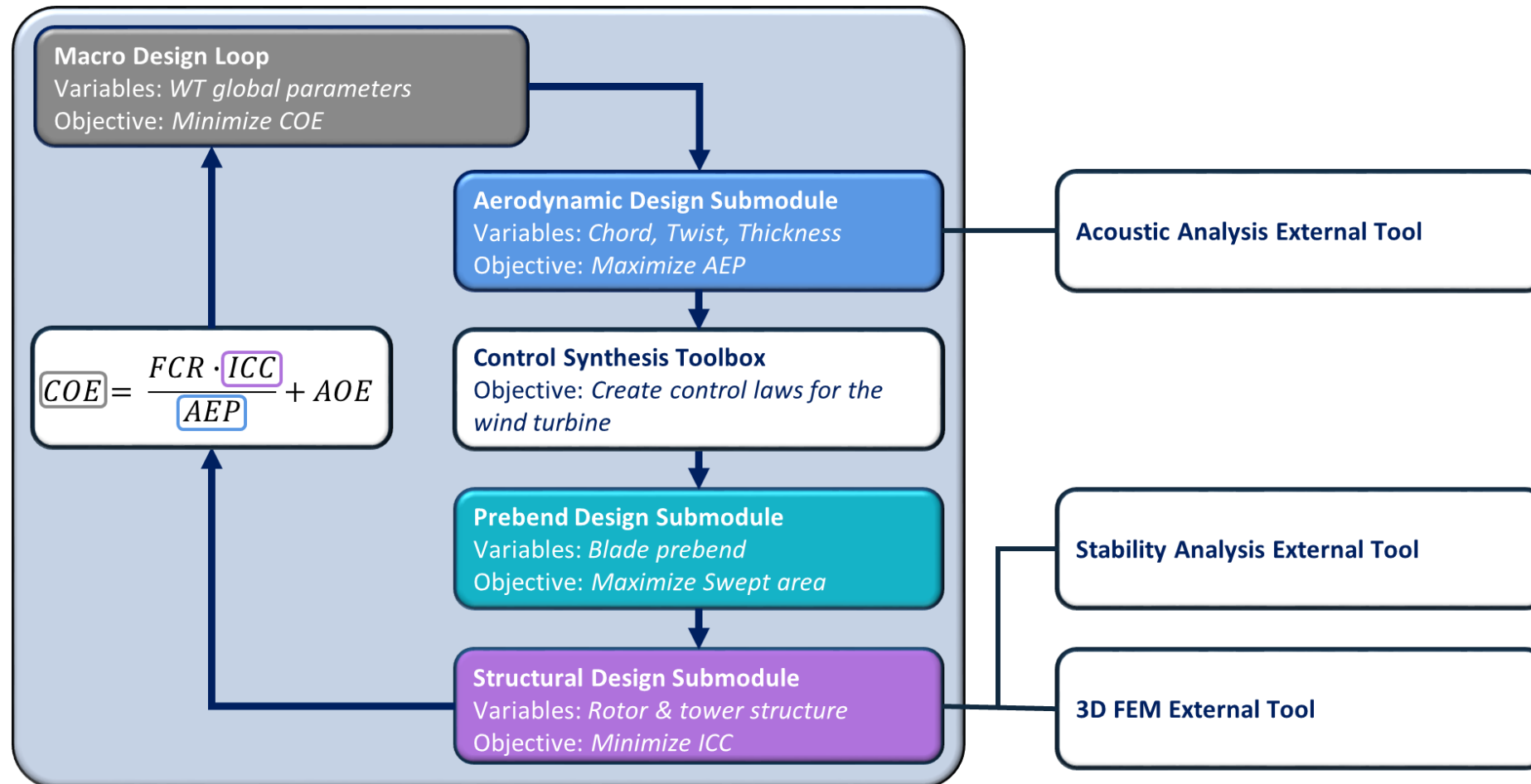


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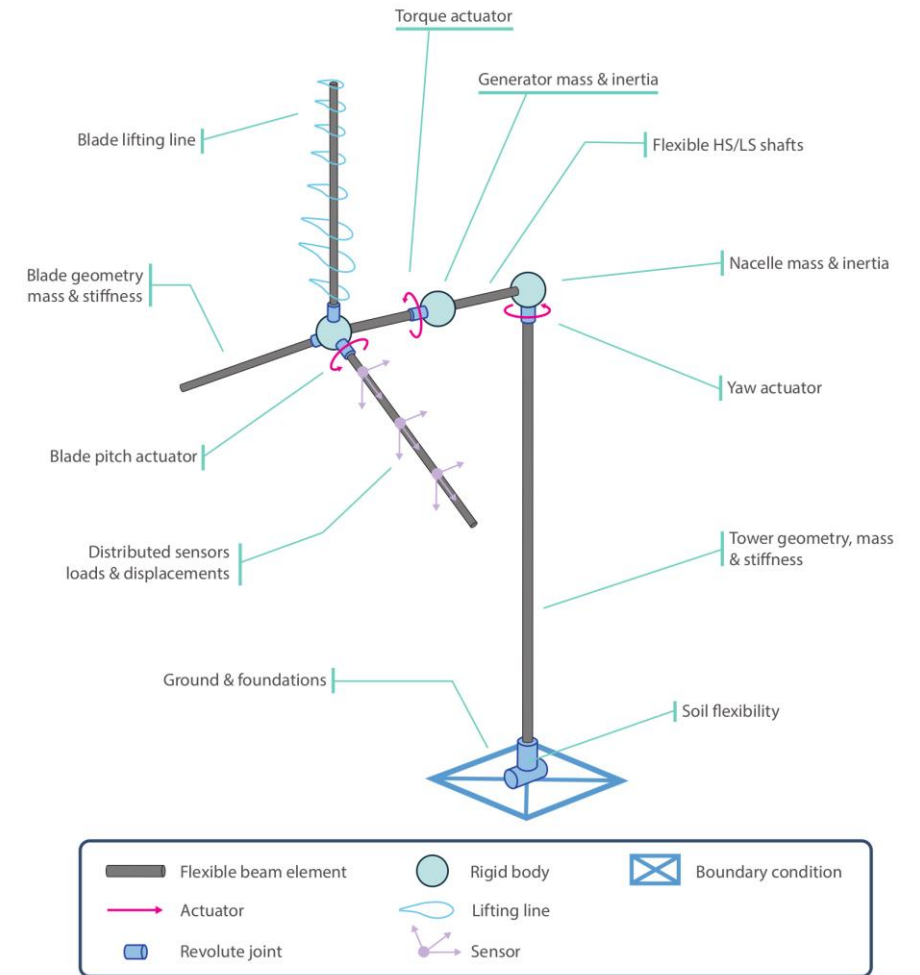
Software architecture



Multi-body modelling of wind turbines

Simulation tool: Cp-Lambda

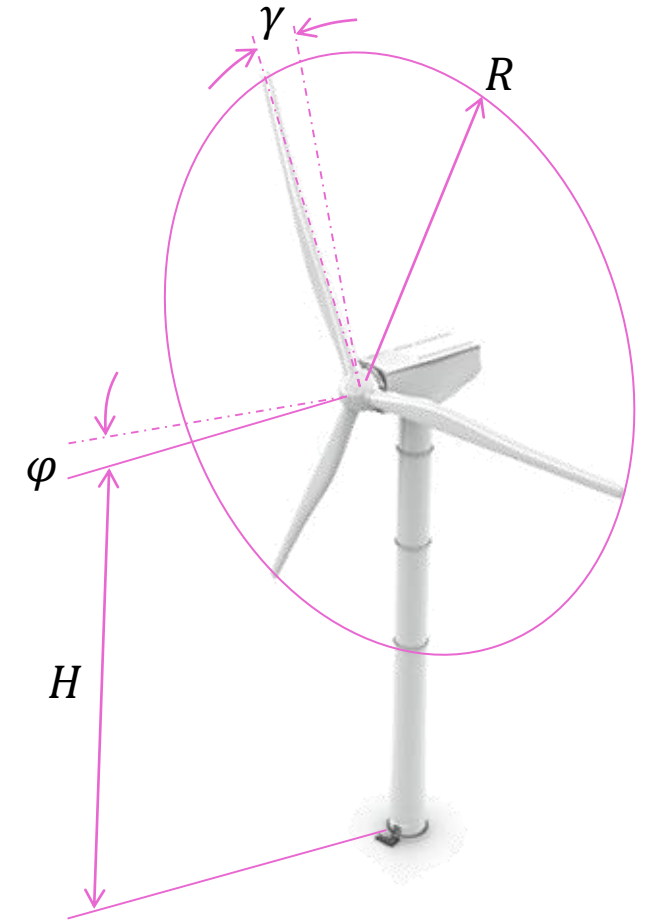
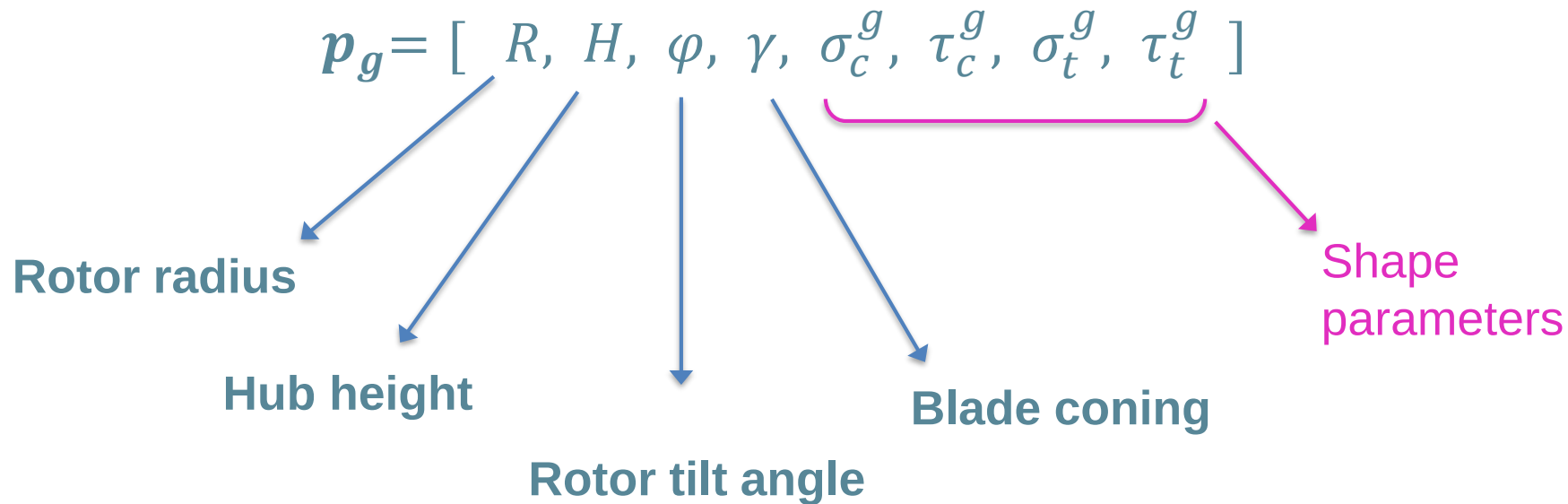
- Multibody solver
- Lifting line + BEM Inflow
- Spatial grid + wind time history
- Nonlinear beam formulation (Bauchau et al. 2001)
- Fully-populated mass/stiffness matrix



MACRO DESIGN LOOP

Macro Design Loop (MDL)

- Optimizes *global features* of the turbine to minimize COE
- Macro design variables:



Macro Design Loop (MDL)

- The **shape parameters** are computed from *chord* and *thickness* distributions:

Rotor solidity

$$\sigma_c^g = \frac{3 \int_0^R c(r) dr}{\pi R^2}$$

Rotor tapering

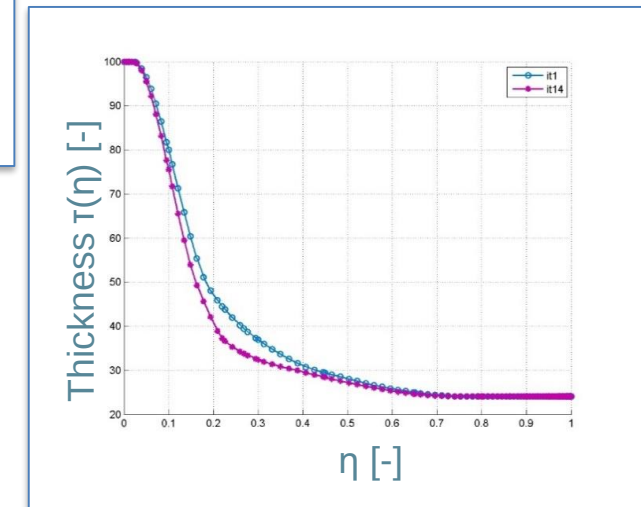
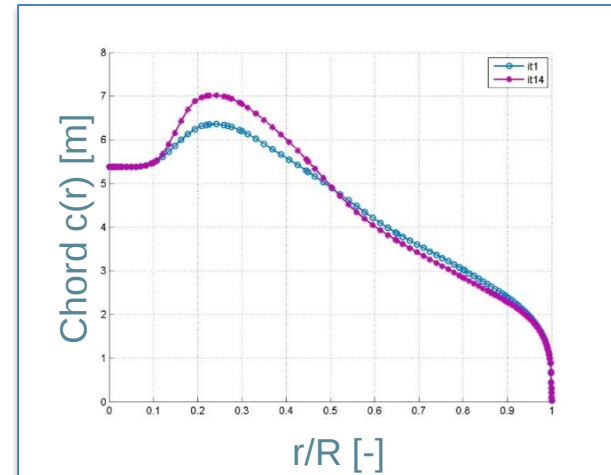
$$\tau_c^g = \frac{\int_0^R r c(r) dr}{\int_0^R c(r) dr}$$

Thickness solid area

$$\sigma_t^g = \frac{1}{100} \int_0^1 t(\eta) d\eta$$

Thickness weighted area

$$\tau_t^g = \frac{\int_0^1 \eta t(\eta) d\eta}{\int_0^1 t(\eta) d\eta}$$



- They link the MDL with the submodules

Macro Design Loop (MDL)

- Simplified workflow of the MDL:

MDL $(COE^*, p_g^*) = MinCOE(p_a, p_b, p_s, p_g, D)$

ADS $(p_a^*, AEP^*) = MaxAEP(p_a, p_b, p_s, p_g, D)$

CST $(r_\varepsilon^*) = CreateControlLaws(p_a^*, p_b, p_s, p_g, D)$

PDS $(p_b^*, A_\delta^*) = OptimizePrebend(p_a^*, p_b, p_s, p_g, D, r_\varepsilon^*)$

SDS $(p_s^*, ICC^*) = MinICC(p_a^*, p_b^*, p_s, p_g, D, r_\varepsilon^*)$

$$COE = CostModel(AEP^*, ICC^*, p_a^*, p_b^*, p_s^*, p_g, D, r_\varepsilon^*)$$

- Available cost models:

Scaling (NREL, 2006), Industrial (SANDIA), Refined scaling (INNWIND)

DESIGN SUBMODULES

Aerodynamic Design Submodule (ADS)

- Optimizes the aerodynamic design variables p_a of the rotor to maximize AEP

$$(p_a^*, AEP^*) = \max_{p_a} (AEP(p_a, p_b, p_s, p_g))$$

s.t.:

$$v_{tip} \leq v_{tip}^{max}$$
$$g_a(p_a, p_g) \leq 0$$

Design variables:

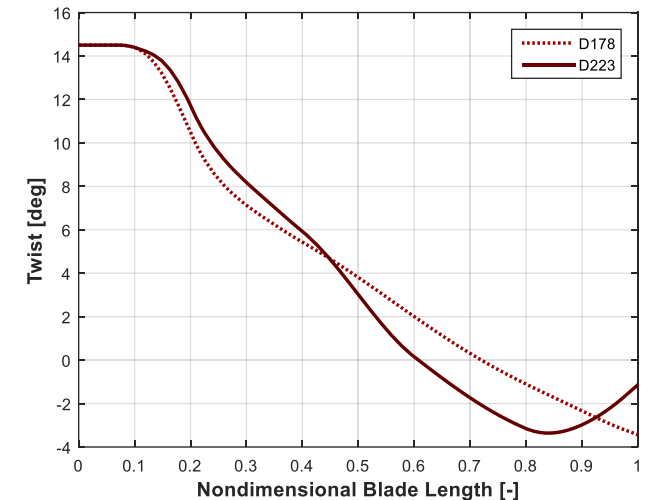
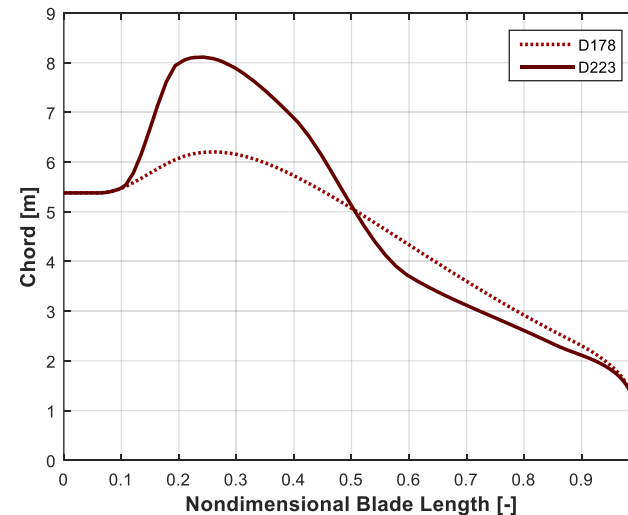
- Chord
- Twist
- Thickness (position of airfoils)

Aerodynamic Design Submodule (ADS)

Chord, twist and thickness are parameterized by multiplicative/additive *bumping* functions

$$\begin{aligned}c(\eta) &= s_c(\eta)c_{bl}(\eta) \\ \theta(\eta) &= s_\theta(\eta)\theta_{bl}(\eta) \\ t(\eta) &= s_t(\eta)t_{bl}(\eta)\end{aligned}$$

$$\begin{aligned}s_c(\eta) &= \mathbf{n}_c(\eta)\mathbf{c} \\ s_\theta(\eta) &= \mathbf{n}_\theta(\eta)\boldsymbol{\theta} \\ s_t(\eta) &= \mathbf{n}_t(\eta)\mathbf{t}\end{aligned}$$



$\mathbf{n}$ are spline shape functions

$\boldsymbol{\theta}$, $\mathbf{c}$ and $\mathbf{t}$ are the associated nodal parameters

Aerodynamic Design Submodule (ADS)

- Theoretical AEP from flexible C_p -TSR curves
- The structure is frozen
- Blade shape and thickness constrained by the MDL:

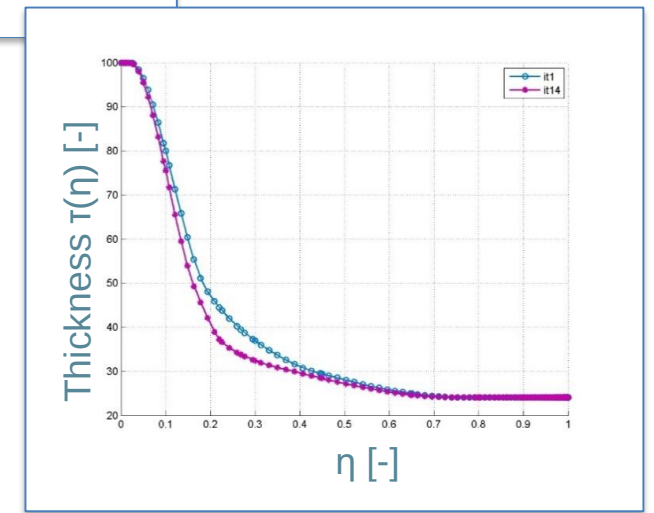
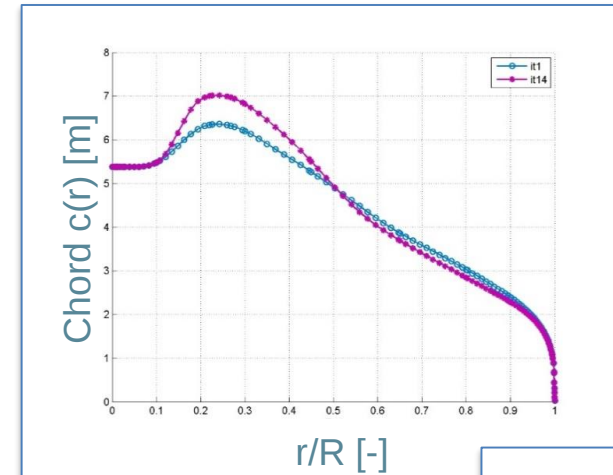
$$\sigma_c^{Aero}(c(\eta), R) = \sigma_c^g$$

$$\tau_c^{Aero}(c(\eta), \eta, R) = \tau_c^g$$

$$\sigma_t^{Aero}(t(\eta), R) = \sigma_t^g$$

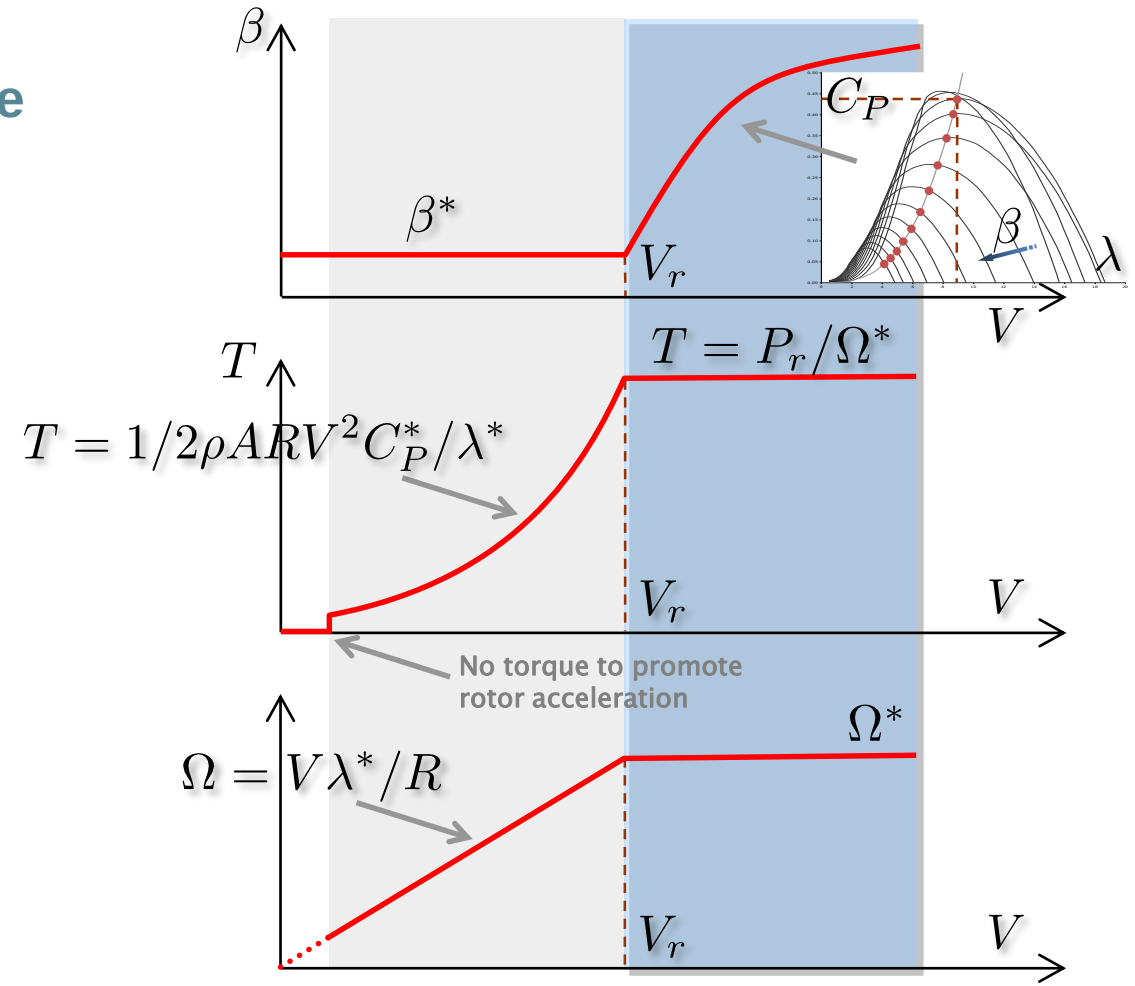
$$\tau_t^{Aero}(t(\eta), \eta, R) = \tau_t^g$$

- Other constraints on max chord, tip speed, shape regularity



Control Synthesis Tool (CST)

- Determines the control laws r_{ε}^* of the turbine
- Required to perform DLC simulations
- Available options:
 - PID on pitch + LUT on torque
 - PID on pitch + PID on torque (DTU)
 - MIMO-LQR model based
 - Individual Pitch Control



Prebend Design Submodule (PDS)

- Optimizes prebend to maximize the deformed swept area

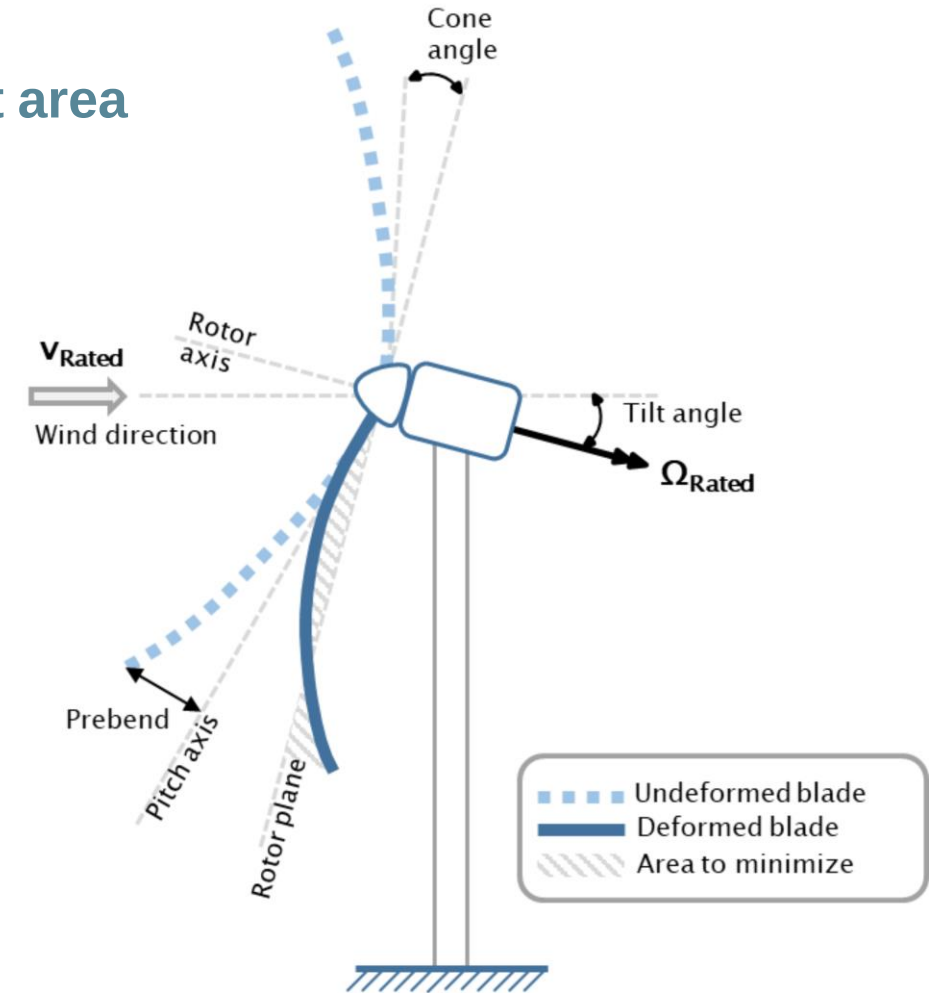
$$(p_b^*, A_\delta^*) = \min_{p_b} (A_\delta^*(p_a^*, p_b, p_s, p_g, r_\varepsilon^*))$$

s.t.:

$$g_a(p_a, p_g) \leq 0$$

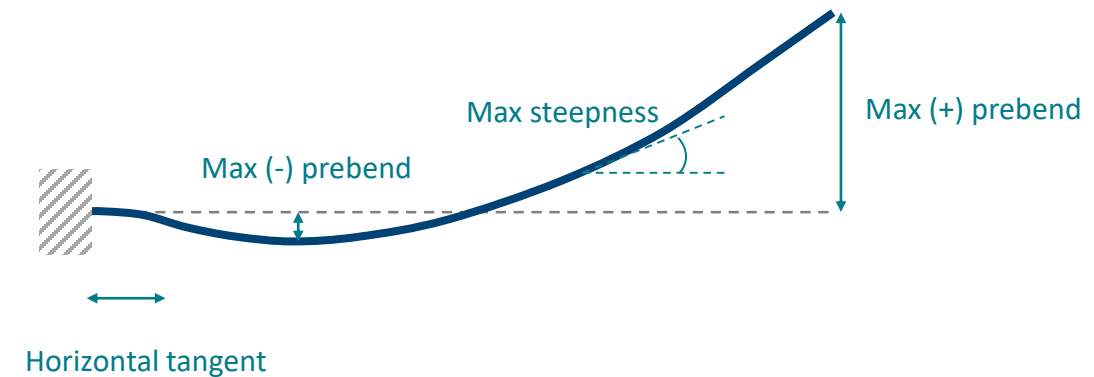
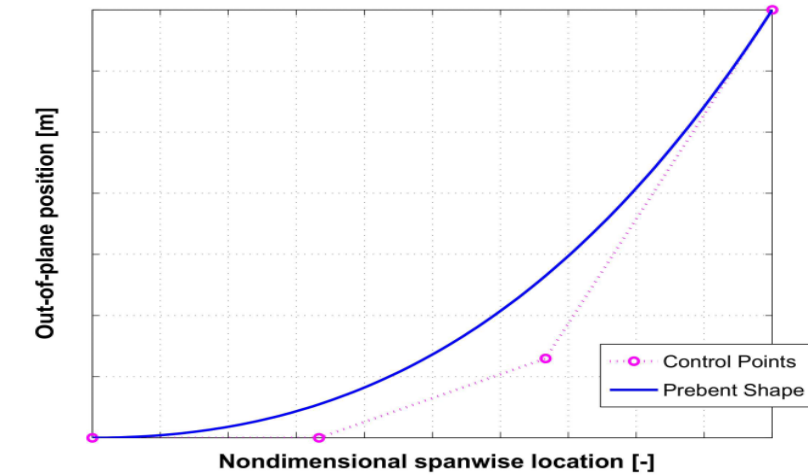
Design variables:

- Prebend shape



Prebend Design Submodule (PDS)

- Prebend is parameterized by a Bézier curve
- Static analysis at rated conditions
- Possible constraints on:
 - Max tip prebend
 - Max steepness
 - Shape regularity
- No associated variables in the MDL



Structural Design Submodule (SDS)

- Optimizes *internal structure* of blade, tower to minimize the ICC

$$(p_s^*, ICC^*) = \min_{p_s} (ICC(p_a^*, p_b^*, p_s, p_g, r_\varepsilon^*))$$

s.t.:

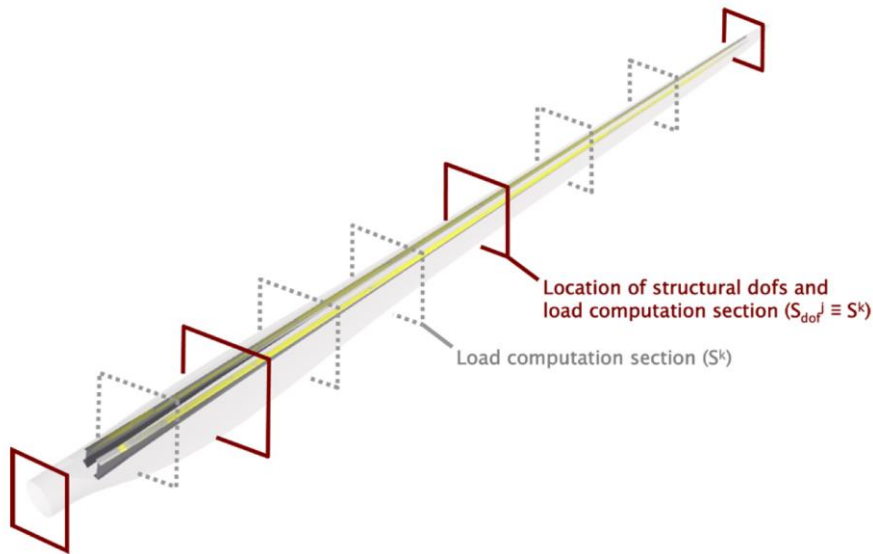
$$g_s(p_a^*, p_b^*, p_s, p_g, r_\varepsilon^*) \leq 0$$

Design variables:

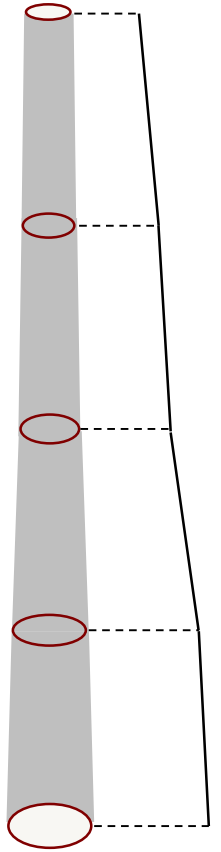
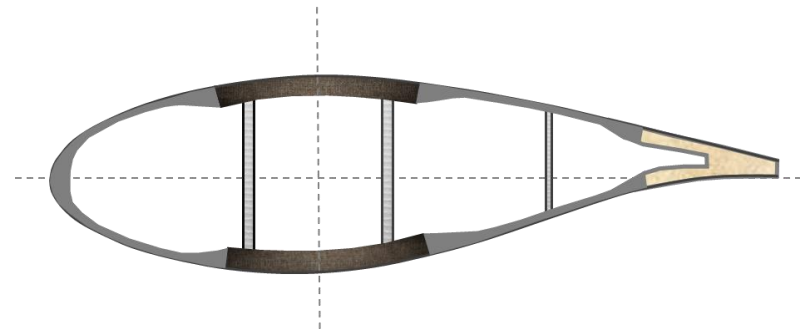
- Thickness of blade structural components
- Wall thickness of tower segments
- Diameter of tower segments

Structural Design Submodule (SDS)

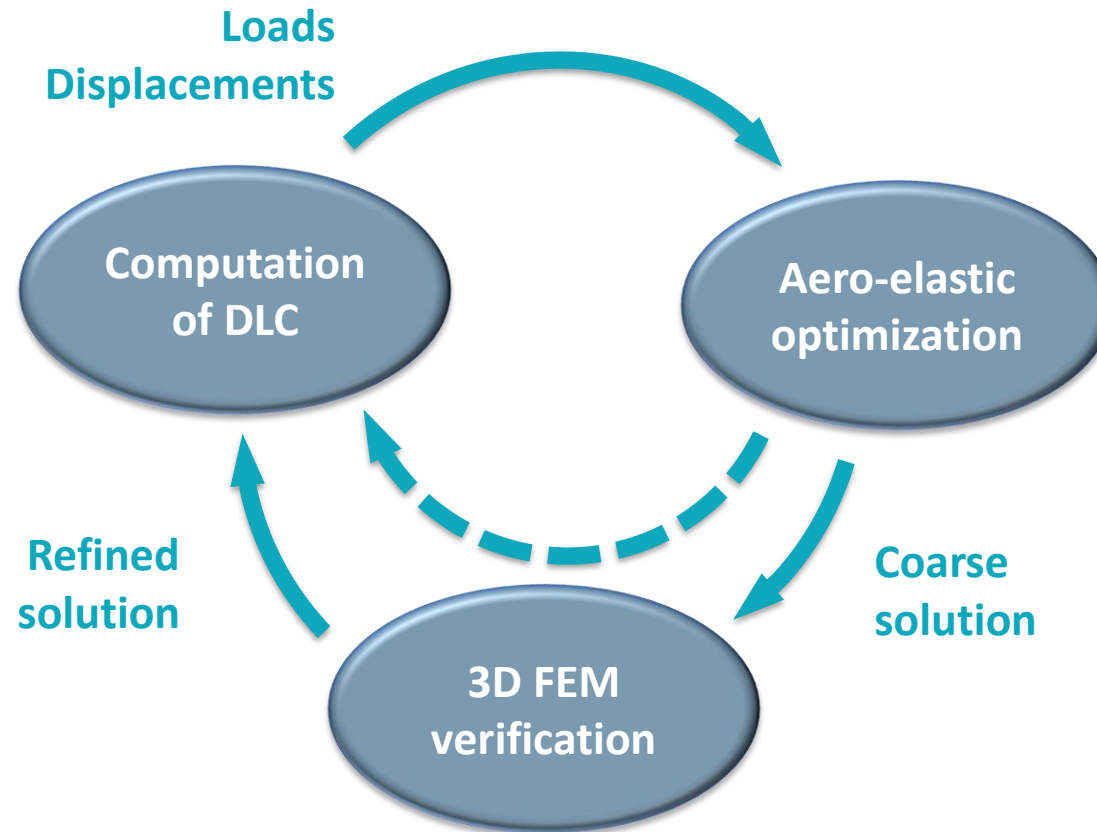
- Thickness of elements is defined at selected stations
- Sectional mass, stiffness computed by ANBA



- Sectors defined along tower height
- Mass, stiffness, stress/strain and buckling computed analytically
- Loads and deformations from *Cp-Lambda* sensors



Structural Design Submodule (SDS)



Constraints:

- Blade tip deflection
- Frequencies
- Manufacturing limits
- Ultimate stress, strain
- Fatigue damage
- Buckling

AN EXAMPLE: DESIGN OF THE POLIMI 20MW BASELINE WT

Definition of the initial 20 MW model

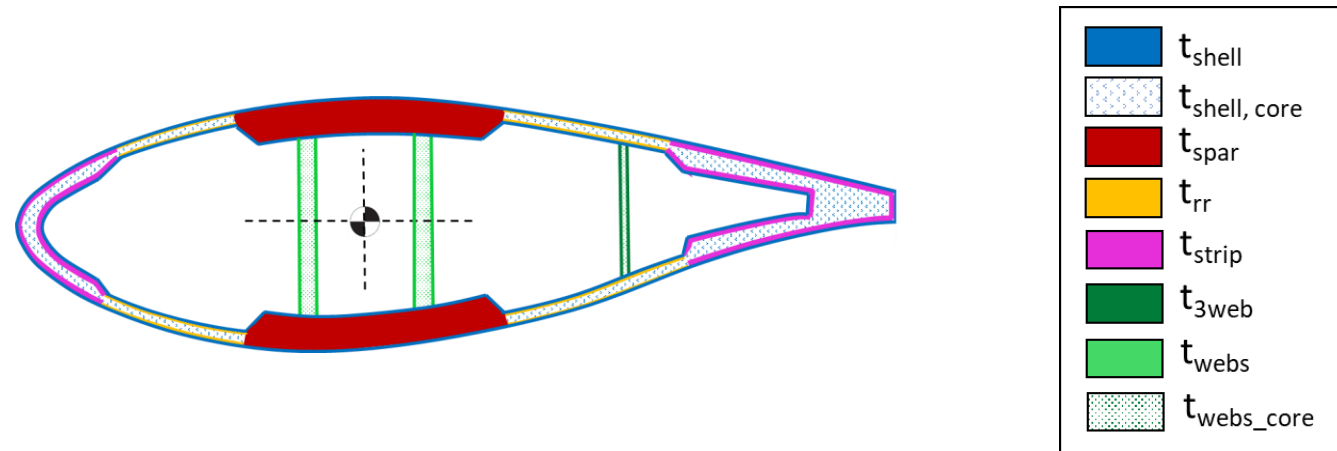
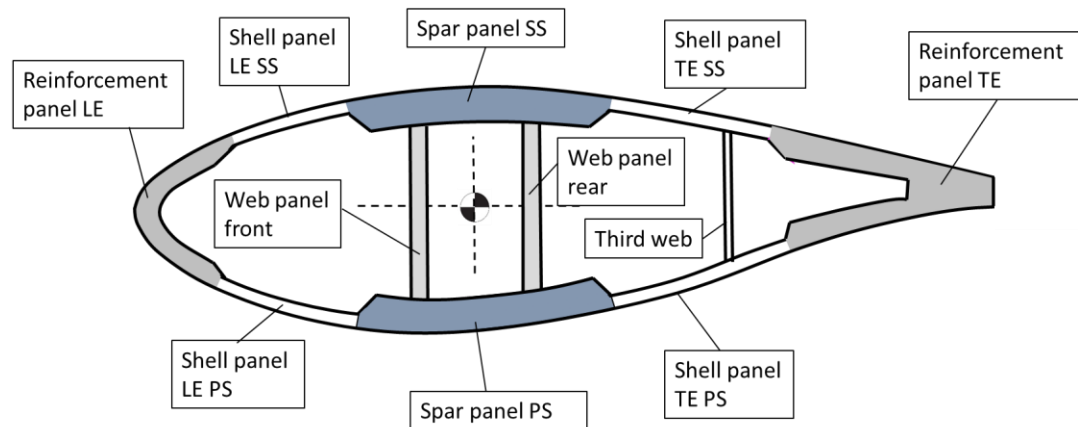
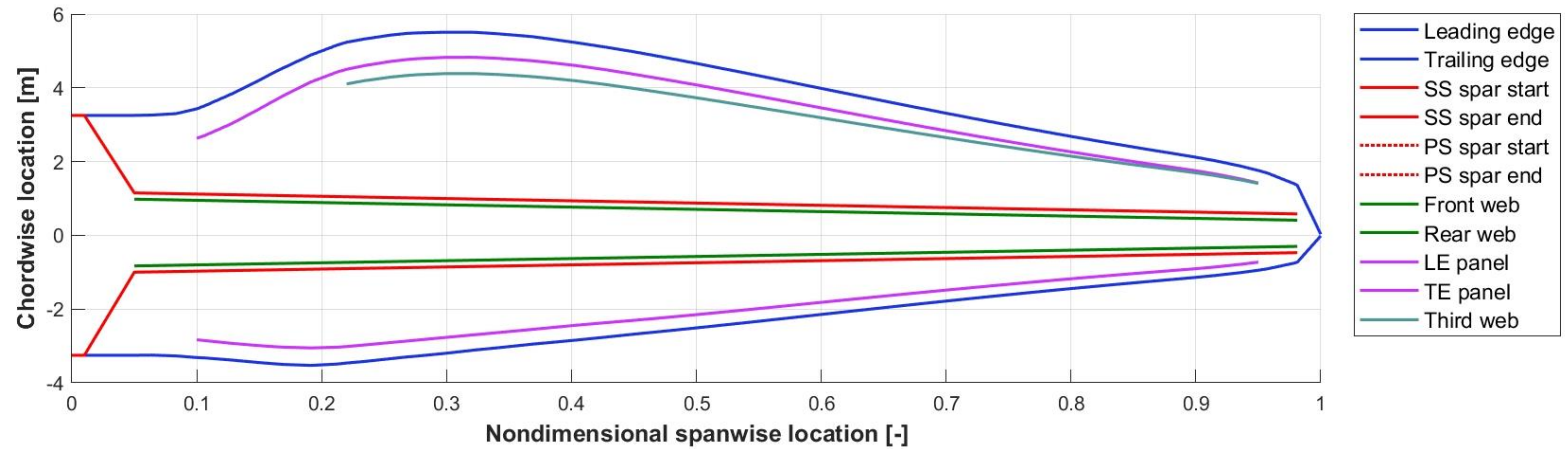
- Initial aeroelastic definition obtained from upscaling the INNWIND.EU 10 MW

Rated power	20 MW	Rotor radius	126 m
IEC Class	IC	Hub radius	3.95 m
Rotor orientation	Clockwise, upwind	Hub height	168 m
Control	Variable speed	Tower height	163 m
Cut-In speed	4 m/s	Blade mass	118 ton
Cut-Out speed	25 m/s	Hub mass	278 ton
Rated wind speed	11.4 m/s	Nacelle mass	1098 ton
Max tip speed	90 m/s	Tower mass	1779 ton
Cone angle	2.5°	Generator Inertia	8488 kg/m2
Tilt angle	5°	Generator efficiency	94%

Reference: INNWIND Deliverable 1.25: *PI-based assessment (application) on the results of WP2-WP4 for 20 MW wind turbines*, June 2017

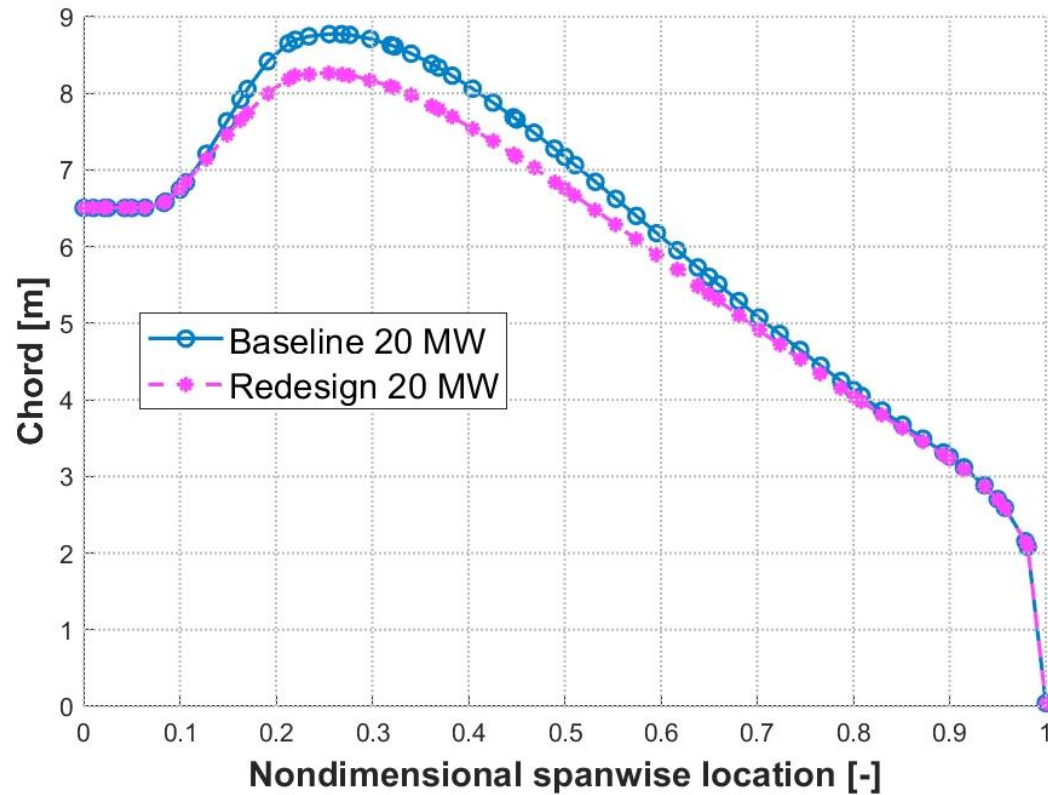
Design assumptions

- Classic *spar-box* layout
- No initial prebend
- Fixed-radius optimization

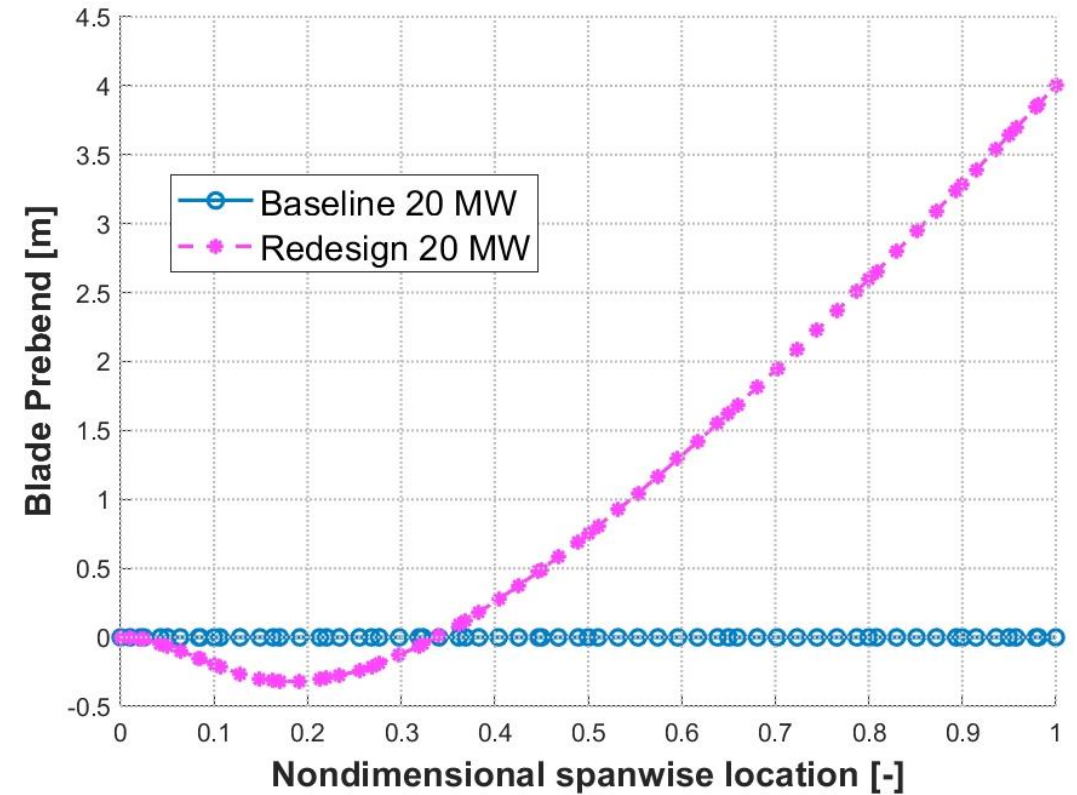


Baseline vs. Redesign comparison

Chord

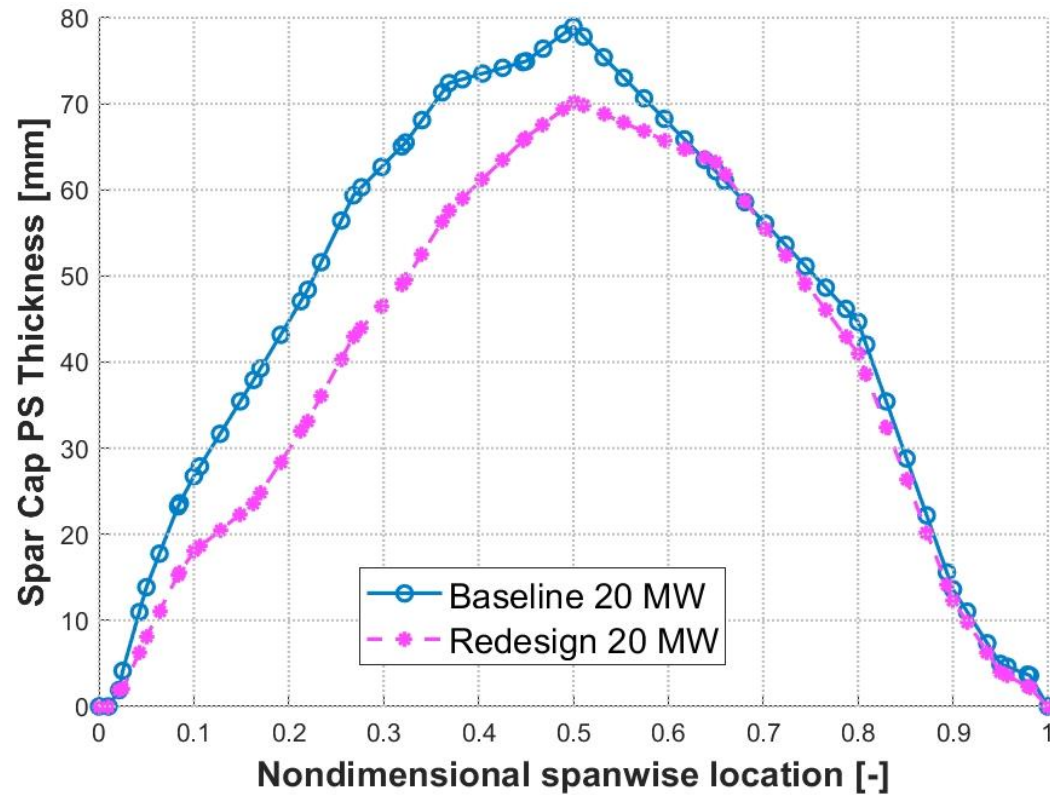


Prebend

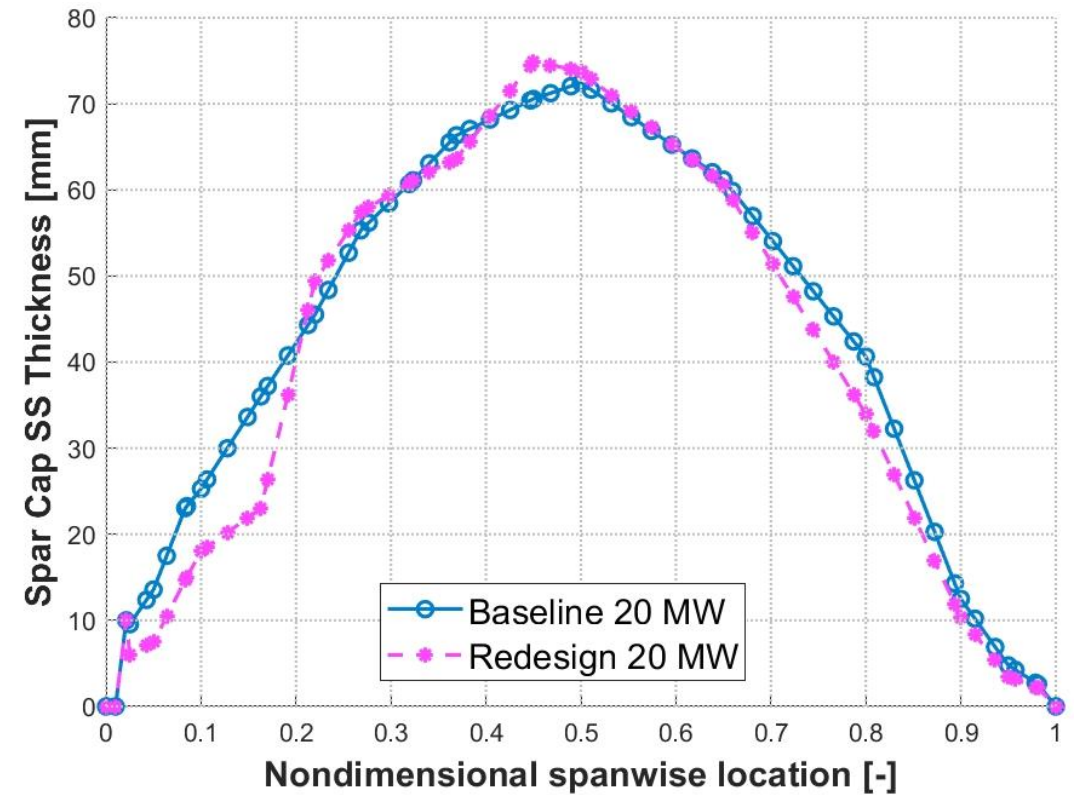


Baseline vs. Redesign comparison

PS Spar Cap thickness

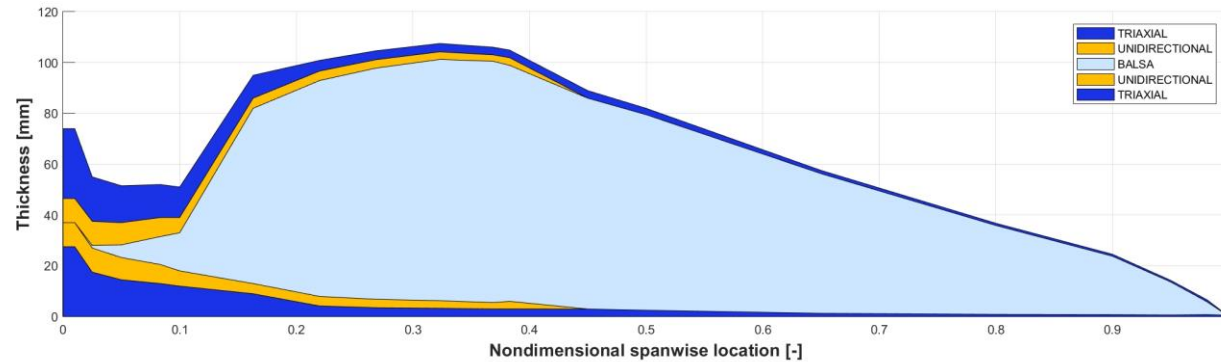


SS Spar Cap thickness

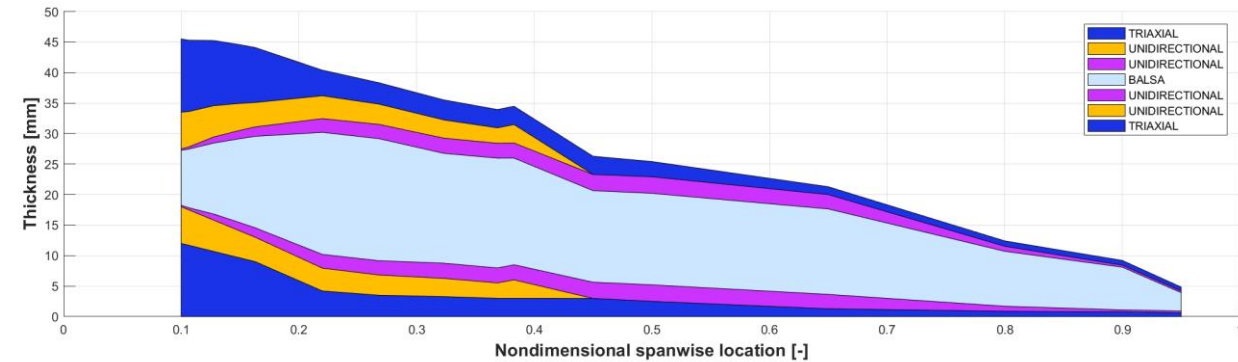


Structural solution of the redesigned rotor

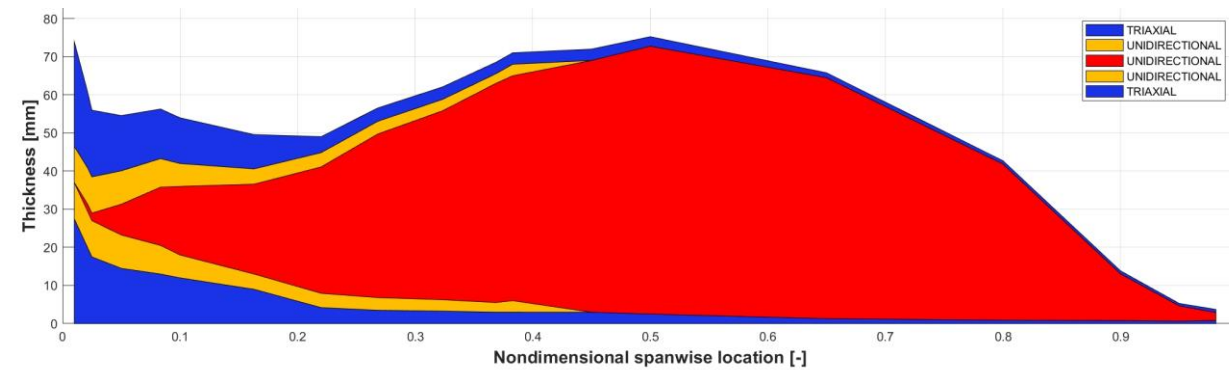
Shell Panels



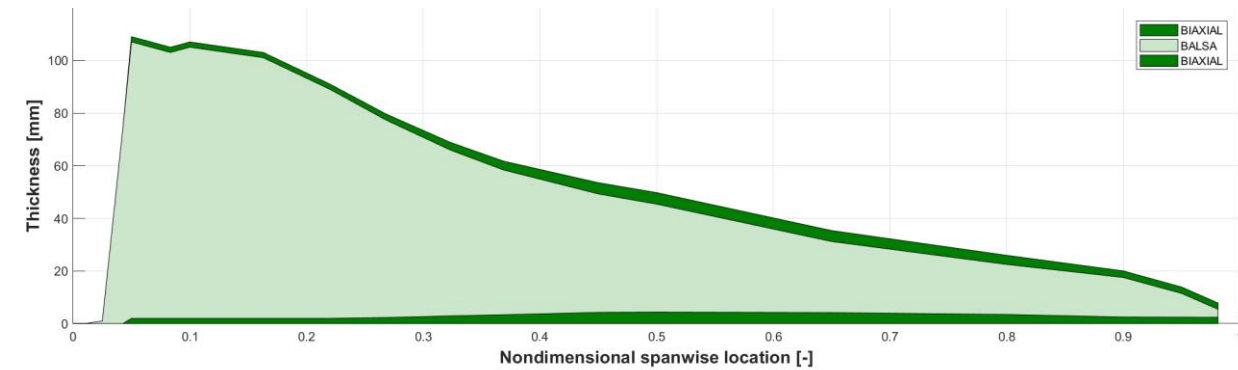
LE Panels



Spar Panels



Shear Webs

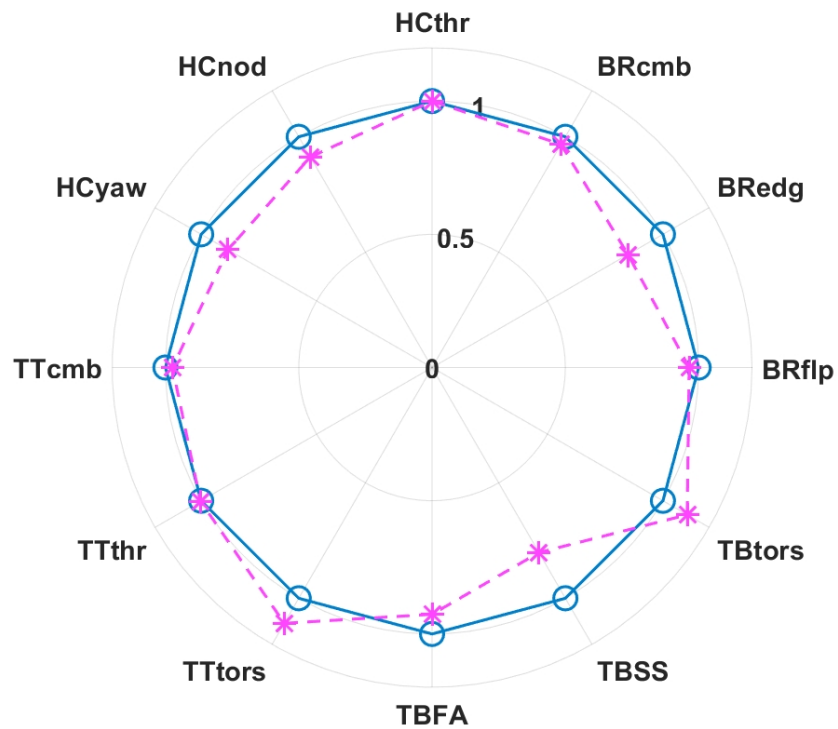


Baseline vs. Redesign comparison

		Units	Baseline 20 MW	Redesign 20 MW	Var. %
Regulation	Rotor speed	[RPM]	6.77	6.82	+ 0.74
	Max tip speed	[m/s]	89.4	89.93	+ 0.59
	Optimal TSR	[-]	7.73	7.86	+ 1.68
	Rated wind speed	[m/s]	11.56	11.45	- 0.95
Design parameters	Max chord	[m]	8.77	8.27	- 5.70
	Prebend at tip	[m]	0	4	-
	Spar caps fiber angle	[deg]	0	6	-
KPIs	Total blade mass	[ton]	113.5	107.8	- 5.05
	AEP	[GWh/yr]	91.63	91.74	+ 0.12
	COE	[€/MWh]	84.92	84.56	- 0.42

Baseline vs. Redesign comparison

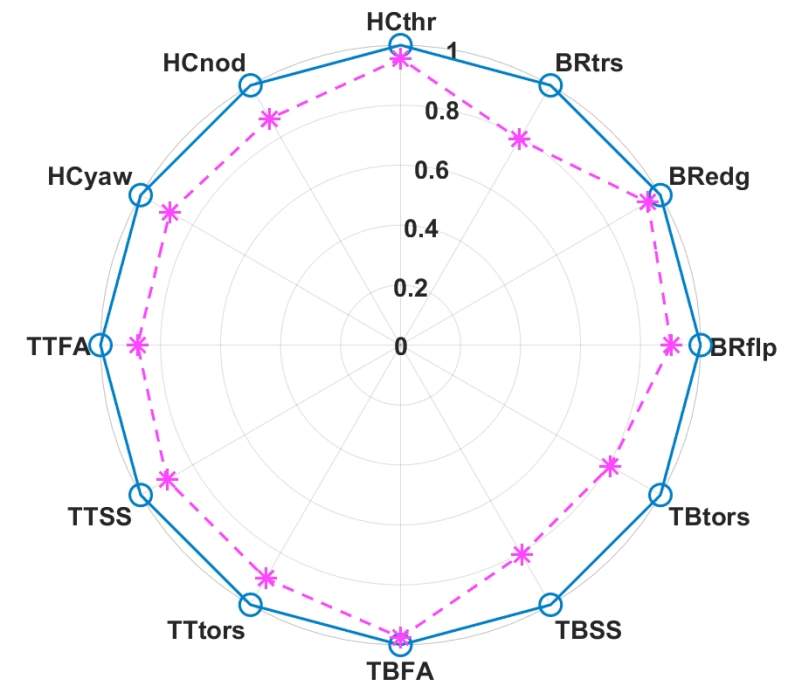
Ultimate loads



BR Blade Root
HC Hub Center
TT Tower Top
TB Tower Base

Baseline 20 MW
 Redesign 20 MW

Fatigue loads



STATE OF THE ART AND OUTLOOK

Completed research projects

- Definition of 10~20 MW reference wind turbines
- Definition of a 3.4 MW reference WT for the IEA-Task 37 project
- Integration of active/passive load mitigation in the design
- Development of upwind/downwind two-bladed rotors
- Study of the impact of WF control on a single WT design
- Global WT design with noise emissions constraints



CL-Windcon



iea wind

Completed industrial projects

1 m (for wind tunnel)

100kW – 10m

300kW – 16m

700kW – 24m

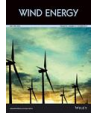
2MW – 45m



Ongoing activities

- Integration of airfoil design
- Development of numerical tools for aero-acoustic modelling and design
- Application of the design to down-scaled WTs for wind tunnel
- Integration of WF-level simulation and design modules
- Integration of additional sub-component design modules (DT & generator, support structure)

Selected references



P. Bortolotti, C.L. Bottasso, A. Croce, L. Sartori: Integration of multiple passive load mitigation technologies by automated design optimization—The case study of a medium-size onshore wind turbine. *Wind Energy*, 2019, 22: 65–79, doi:10.1002/we.2270



H. Canet, P. Bortolotti, C.L. Bottasso: Gravo-aeroelastic scaling of very large wind turbines to wind tunnel size. *J. Phys. Conf. Ser.*, 2018, 1037, 042006, doi:10.1088/1742-6596/1037/4/042006



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THANK YOU FOR YOUR ATTENTION