



Andrey Bernstein AES Industry Workshop May 9, 2022

AES Control and Optimization Capabilities

AES Capabilities Summary

Algorithms and tools development for

optimization





estimation/prediction



with applications to highly distributed energy systems integration problems



AES Capabilities

Distributed optimization and control of millions of DERs

Data-driven (ML/AI-based) optimization and optimal control

Adaptive control for improving system real-time resilience

Optimizing topology and microgrid formation

Real-time state estimation and situational awareness

AES Capabilities

Distributed optimization and control of millions of DERs

Distributed optimization with measurement feedback



- Obtain measurement of the systems output *y* (e.g., voltages)
- Run a simple/lightweight optimization and repeat
- Application: Real-Time Optimal Power Flow (RT-OPF)
 - Avoids explicit modelling of power-flow equations and uncontrollable injections

Distributed optimization with measurement feedback

- Break large-scale problem into smaller parallel ones
- Solve small-scale subproblems locally
- Coordinate to arrive at system-wide solution



- Developed under ARPA-E NODES and internal LDRD funds
- Implemented in:
 - Large-scale simulation with 10s of thousands of devices (SF Bay Area system)
 - HIL testbed at NREL with >100 physical devices and hundreds of simulated devices
 - Field demo at HCE (20 devices, 4 homes)
 - Field demo at Stone Edge Farm microgrid (~20 devices)



Hierarchical-distributed optimization

- Motivation: Fast OPF solutions for large distribution networks w/o losing optimality
- Methodology: Multi-level algorithms that exploit the network/OPF problem structure and improve the computational efficiency
- Results and Impact:
 - >10-time "free" speed improvement in a 11K distribution system
 - Enabling 1-second/iteration online OPF solving for large networks
 - Capability of handling solutions for millionnode systems



Stochastic/robust optimization

- Incorporate uncertainty in optimization
- **Robust**: e.g., ensure voltage regulation no matter what the uncertainty is
- Chance-constraints: e.g., ensure voltage regulation with given probability (less conservative)

$$\max_{\left[\overline{p_{i},\underline{p}_{i}},\overline{q}_{i},\underline{q}_{i}\right]} \sum_{i=1}^{N} \alpha_{i} \left(\overline{p_{i}} - \underline{p}_{i}\right) + \sum_{i=1}^{N} \beta_{i} \left(\overline{q_{i}} - \underline{q}_{i}\right)$$
(RBOPF)

s.to:
$$u_i = (p_i, q_i), \ i = 1, ..., N$$
 (C1)

$$\underline{p}_i \le p_i \le \overline{p}_i, \ i = 1, \dots, N \tag{C2}$$

$$\underline{q}_i \le q_i \le \overline{q}_i, \ i = 1, \dots, N \tag{C3}$$

$$\Pr\{x_i = u_i + w_i \in X_i, i = 1, ..., N\} \ge 1 - \delta$$
(C4)

$$\Pr\left\{\mathbf{v} = \mathbf{M}\mathbf{x} + \mathbf{m} \in \mathcal{V}\right\} \ge 1 - \lambda. \tag{C5}$$

AES Capabilities

Data-driven (ML/AI-based) optimization and optimal control ("Learning to Optimize and Control")

Data-Driven (ML/AI-based) Optimization and Optimal Control

Model-Free RT-OPF



- RT-OPF: requires system information (e.g., topology, line parameters)
- Use "probing" and measuring the output to optimize "on the fly" without explicit system model
- Slower convergence than standard RT-OPF

Data-Driven (ML/AI-based) Optimization and Optimal Control

Building control using Reinforcement Learning

- Future building control requires **optimal control**
 - E.g., to implement grid-interactive buildings
- Classic approach: model predictive control (MPC)
 - Requires buildings model
 - Need to be tailored for each building
- Reinforcement learning (RL) allows to learn the optimal controller from data and interaction with the building
- Demonstration in real commercial building in NYC



Data-Driven (ML/AI-based) Optimization and Optimal Control

Online data-enabled predictive control (ODeePC)

- An alternative to RL
- Uses historical data directly in MPC
- Allows explicit constraints
- Online algorithms to adapt to system changes
- Computationally efficient
- Evaluated on SDG&E feeder for voltage regulation with HIL+ADMS

$$\begin{array}{ll} \underset{g,u,y}{\text{minimize}} & \sum_{k=0}^{N-1} \left(\|y_k - r_{t+k}\|_Q^2 + \|u_k\|_R^2 \right) \\ \text{subject to} & \begin{pmatrix} U_{\mathrm{p}} \\ Y_{\mathrm{p}} \\ U_{\mathrm{f}} \\ Y_{\mathrm{f}} \end{pmatrix} g = \begin{pmatrix} u_{\mathrm{ini}} \\ y_{\mathrm{ini}} \\ u \\ y \end{pmatrix}, \\ u_k \in \mathcal{U}, \ \forall k \in \{0, \dots, N-1\}, \\ y_k \in \mathcal{Y}, \ \forall k \in \{0, \dots, N-1\}. \end{array}$$

AES Capabilities

Adaptive control for improving system real-time resilience

Adaptive Control for Improving System Real-Time Resilience

Emergency Voltage Control using ``Hotline" Comms

MOTIVATION

- OPF problems are solved periodically (~ 15 min)
 Abrupt change in the network (line tripping) or in the load demand might occur between 2 OPF instances
- Real-time emergency control for avoiding network (voltage) collapse



Adaptive Control for Improving System Real-Time Resilience



CONTROL RATIONALE AND FEATURES

- Buses first try to fix their issue locally
- If the control effort is not enough, assistance is sought from neighboring buses on a communication network in a ripple-type manner
- The control is a model-free feedback based scheme



even its effort is not enough.

AES Capabilities

Optimizing topology and microgrid formation

Optimizing Topology and Microgrid Formation

- Co-optimizing topology (switches) and DER setpoints
- During normal operation: minimize losses and cost of generation
- During faults: island the cells/areas to become microgrids
- Restoration: reconnect microgrids to form the grid



AES Capabilities

Real-time state estimation and situational awareness

Real-time state estimation and situational awareness

Low-observability state estimation

- Systems with less measurements than unknowns (states)
 - Distribution systems
 - Attacks/disruptions
- Form data in a 2D or 3D array a matrix or tensor
- Due to correlations: matrix/tensor is low rank
- State estimation = low-rank matrix/tensor completion



Real-time state estimation and situational awareness

Low-observability state estimation

Dynamic state estimation

- Leverages previous estimates
- Measurements processed as they come in
- Simple update rules



Real-time state estimation and situational awareness

Topology identification

- Methods for topology identification using historical and real-time data
- Identification of status of switches
- Bus clustering according to substations



Examples of Demonstration and Partnerships

ARPA-E NODES: NREL, Caltech, Harvard, UM, SCE, HCE, Heila Technologies (Stone Edge Farm)

- Distributed DER control (RT-OPF)
- 100+ devices PHIL experiment, large-scale CHIL at SCE
- Field demonstration at HCE (4 homes, 20 devices)
- Field demonstration at Stone Edge Farm (~20 devices)
- Completed

SETO SolarExPert: UCF, NREL, HNEI, Duke, Siemens, OPAL-RT

- Distributed DER control
- Large-scale PHIL and CHIL experiments
- Simulation on >100k nodes system
- Completed

SETO GoSolar: NREL, HECO

- Distributed DER control + control of legacy devices
- PHIL with >100 inverters
- Simulation on >2k nodes system
- Completed

SETO AURORA: Siemens, NREL, Columbia University, HCE

- Networked microgrids and autonomous blackstart
- Demonstration on HCE system at Siemens testbed
- Ongoing

OE DynaGrid: NREL, LLNL, LANL, SNL, DTE Energy, ComEd

- Dynamic microgrid formation + distributed DER control
- Large-scale (Bay Area) simulation
- Field demo at LLNL site
- Potential field demo with DTE Energy
- Ongoing

DOE Connected Communities: PGE, NEEA, CEP, NREL, OSI

- Accelerate development and deployment of flexible load resources
- Field demo with 580 community buildings
- Ongoing



Thank you

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