Automated Mobility District Toolkit

Venu Garikapati, National Renewable Energy Laboratory (NREL)

Supporting Team:
Lei Zhu, Bingrong Sun, and Stan Young (NREL)
Husain M. Abdul Aziz and Tony Rodriguez (Oak Ridge National Laboratory)
Yuche Chen (University of South Carolina)

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On-demand transportation services have seen a dramatic rise in the past decade, thanks to technology.

Connected and automated vehicle (CAV) technology holds potential for a major transformation in the on-demand mobility services landscape.

The timeline for fully automated vehicles (AVs) to reach the critical market share is still uncertain.

In the short term, many cities in the United States and abroad are testing low-speed automated electric shuttles (AES) as a shared on-demand mobility service in geo-fenced regions.

Automated Mobility District (AMD)
What is an Automated Mobility District?

An AMD is a campus-sized implementation of CAV technology to realize all the benefits of a fully electric automated mobility service within a confined region or district.
Real-World AMD Demonstrations

Find out when driverless vehicles will be hitting the streets of this North Texas city

Self-driving shuttles to start circling Scinto Mile soon

How autonomous shuttles are changing city transportation


Current | Upcoming
--- | ---
Denver, CO | New York City, NY
Houston, TX | Rhode Island
Arlington, TX | Austin, TX
Las Vegas, NV | Reston, VA
Jacksonville, FL | Battle Creek, MD
Columbus, OH | Columbus – Linden, OH
Ann Arbor, MI | Sacramento State University, CA
Bishop Ranch, CA | Dublin, CA
Gainesville, FL | Rivium Park, Netherlands
Babcock Ranch, FL

Automated Mobility Districts

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<th>Operational Challenges</th>
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<td>Fully automated and driverless cars</td>
<td>Customer demand (adoption rate)</td>
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<td>Service constrained to an area with high trip demand</td>
<td>Fleet size</td>
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<td>Operational configuration: Fixed route vs. on-demand</td>
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<td>Multi-modal access within/at the perimeter</td>
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Current State of AMD Modeling

Where We Are

Existing tools primarily emphasize:

• The road network, with minimal to no consideration for pedestrian/bike/transit

• Privately owned vehicles, but do not model shared economies

• Solutions not customized to guide early-stage deployments

Where We Want To Be

Need modeling tools that:

• Capture private as well as shared economies in vehicles

• Are built from field deployments of emerging transportation technology

• Can quantify energy and emissions as well as mobility benefits
AMD Simulation Toolkit: Model Flow

Travel Demand
- Origin-destination data from regional travel demand model
- Local surveys or counts
- Induced travel demand
- Passenger travel behavior; adoption rates

SUMO (Mobility Analysis)
- SUMO — Simulator of Urban Mobility
- Carries out the network simulation of vehicles
- SUMO will output travel trajectories

FASTSim (Energy Analysis)
- FASTSim — Future Automotive Systems Technology Simulator
- FASTSim will output vehicle energy consumption

Mode Choice Modeling
- Initially tagged to be developed based on user surveys from Greenville
- Resorting to a model based on existing literature owing to lack of data from Greenville

Optimization Module
- Fleet size: How many electric shuttle units will be required?
- Routes: What are the optimal routes that minimize travel time and energy consumption?
- How do we find solutions that meet customers’ expected waiting time and overall trip duration?
AES: Automated Electric Shuttle; GIS: Geographic Information System
Modes considered in Greenville AMD simulation

1) Auto, 2) Walk, 3) AES, 4) Fixed Route

General form of mode choice model

\[ V_i = \alpha + \sum_{j=1}^{J} \beta_j x_j \]

Where

\( i \in \{\text{Auto, Walk, AES, Fixed Route}\} \)

\( \alpha \) is the constant value

\( x_j \) is \( j^{th} \) mode choice attribute

\( \beta_j \) is coef. of attribute \( x_j \)

Potential attributes of mode choice model

- In-vehicle travel time (IVTT)
- Out-of-vehicle travel time (OVTT)
- Value of travel distance
- Fixed cost (fare)
- Other costs, e.g., parking cost

Mode shift observed when value of IVTT changed

More tests on other attributes in progress
AMD Simulation Sample
Optimization Framework: Workflow

**INPUT**
- Road network: Graph (nodes, edges)
- On-demand requests: Origin, destination, preferred waiting time window, departure time window
- Cost: Time-dependent generalized travel cost at link level
- AES configurations: Passenger capacity and distance covered by single charge

**OPTIMIZATION**
- Minimize the generalized travel cost
- Find the minimum number of vehicles/AES
- Meet waiting time threshold: A customer may not wait more than 120 seconds before an AES picks her up from the origin node
- Meet single charge distance constraint: An AES only covers the distance allowed by a single charge

**OUTPUT**
- Minimum number of AES units required that meet on-demand requests with specified constraints
- Optimal routes for all AES units in the network
- Total energy consumption (kWh) by the AES units
**Optimization Model**

**Formulation**
- The problem is formulated as a constrained mixed integer program
- Decision variables are integers
- Set of constraints are linear in nature
- Combinatorial problem

**Challenges**
- General solution approaches include branch-and-bound and cutting-plane methods
- Smaller networks can be solved using commercial solvers such as IBM CPLEX and Gurobi
- Computational complexity rises with the size of the graph (network) and the number of on-demand requests
- Exact solution methods are not scalable for large networks
Greenville, South Carolina, network has 554 nodes and 1,340 edges

- Location: Greenville, South Carolina
- Analysis period: a.m. peak hour (6 a.m.–9 a.m.)
- The time-dependent demand distribution:
  - Known and deterministic
  - Total 378 trips
  - AMD share is about 50%
  - Distributed among eight traffic analysis zones
- AES configuration:
  - Capacity: 2, 4, and 8 passengers
  - Range: 20, 30, and 50 km

Greenville, South Carolina, network has 554 nodes and 1,340 edges
Travel Cost and Energy Consumption

- Link travel time data are obtained from the microscopic traffic simulation tool, SUMO, at a resolution of 15 minutes.
- We model the a.m. peak hour (6 a.m.–9 a.m.) in the Greenville, South Carolina, network.
- We assume dynamic travel time that changes each 15-minute interval. Thus, we have \((180/15)\) or 12 interval horizons.

- An average speed and energy look-up table is developed using FASTSim**.
- A relationship between average driving speed and energy consumption rate is developed using SUMO.

Findings: Travel Time (Cost)

- Tabu search performs better compared with commonly used heuristics: RSTM and RSRH.
- Tabu search provides lower travel time (cost) in all demand cases and all AES ranges (the overall savings range from 2% to 10%).

**RSTM**: Real-time solution with trip matching (RSTM) does not use any information regarding future demand for the AMD service.

**RSRH**: Real-time solution with rolling horizon (RSRH) routing uses limited information about future requests from the customers.

**Demand**: Medium (baseline) → 177 requests; Low → 134 requests (25% ↓ baseline); High → 194 requests (10% ↑ baseline).
Findings: Energy Consumption

- Energy savings compared with both RRTM and RSRH ranges from 9% to 18%
- For 30 km AES range, the relative energy savings are most significant

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Findings: Minimum Number of Vehicles Required

- The results are intuitive and conform to general expectations.
- The minimum number of vehicles required rises with higher demand and shorter AES range.
- Higher number of vehicles as the trips are heavily dispersed in space and time.
Next Steps

• Integrating more constraints into the optimization module
  o Soft time window for waiting time
  o Trip duration threshold for group rides
• Replicating the AMD modeling process in one location in addition to Greenville
• Incorporation of additional ‘mobility on-demand’ modes
• Integrating the toolkit into a regional travel demand model
• Inter-AMD travel modeling and simulation
Thank you

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