

Map Matching and Real World Integrated Sensor Data Warehousing













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NREL-Real World Vehicle Drive Cycle Database

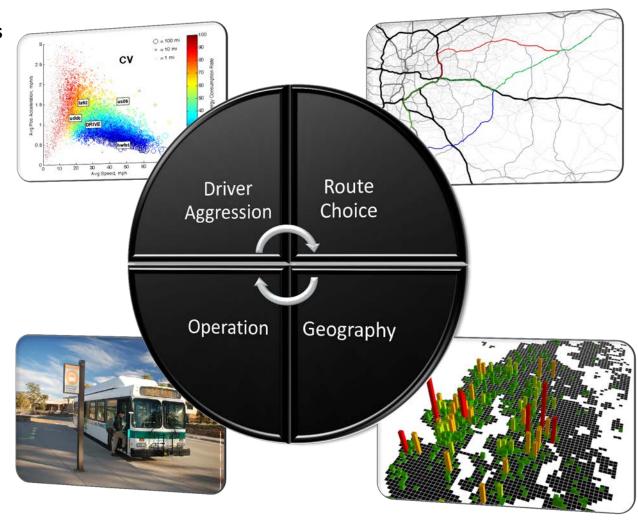
Quantifies otherwise overlooked variables in vehicle analysis.

Map matching sensor data appends additional variables at second-bysecond increments:

- Allows for scalability of analysis
- Incorporates route choice and geography into results

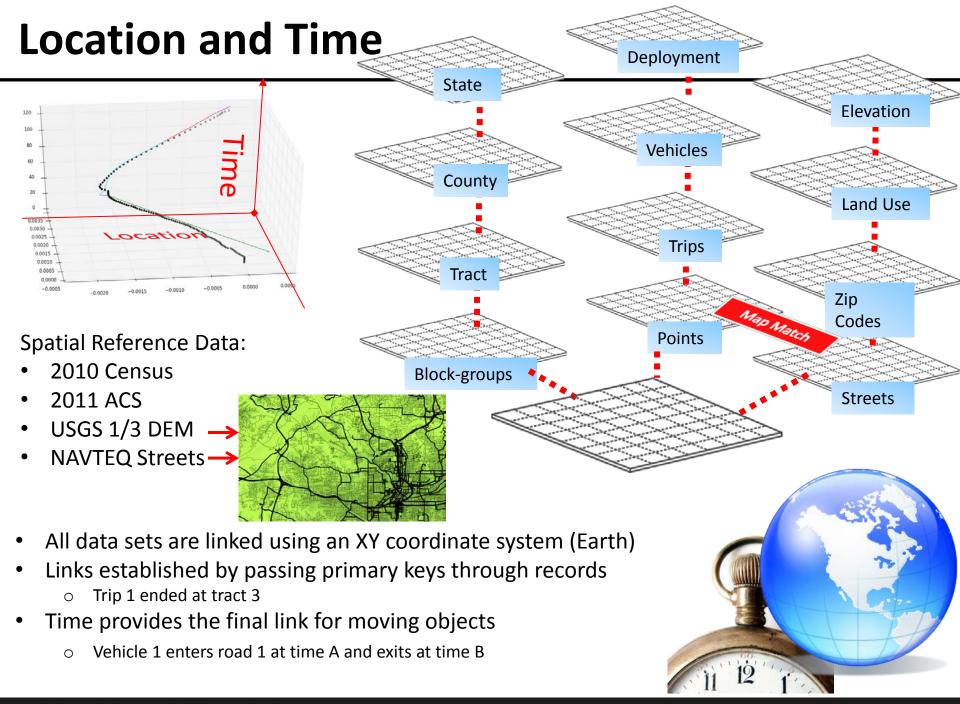
Uses a significant sample group of both personal and commercial vehicles to provide a resource for engineers and researchers focusing on:

- Regional vehicle emissions modeling
- Alternative vehicle application identification
- Vehicle-to-grid electrification
- Regional transportation demand modeling
- Green routing
- Intelligent route-based control strategies for hybrid electric vehicles
- Long-term battery degradation analysis



The Data - Location/Speed/Time









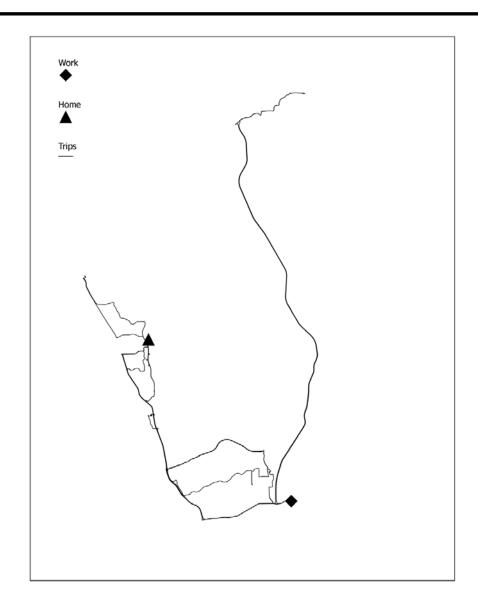
Map Matching

Vehicle Processing – End Product

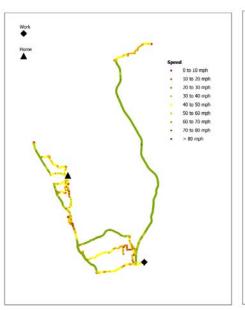
- Second-by-second data are summarized at the trip level
 - Trips are also categorized by end and start type (home/work/school)
- Vehicle processing of the second-bysecond data includes:
 - o Filtering the recorded data
 - Appending data from additional data layers to second-by-second data
- Summary statistics are generated at the vehicle, day, and trip levels
- Trip classifiers are grouped to vehicle and day levels

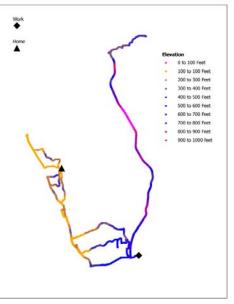
Vehicle Processing (Next Slide)

- Speed Filtered
- Location Filtered
- 3. Elevation Appended
- 4. Grade Appended
- 5. Street ID Appended
- 6. Street Functional Class Appended
- 7. Street Speed Category Appended



Vehicle Processing – End Product







Speed – Filtered Location – Filtered

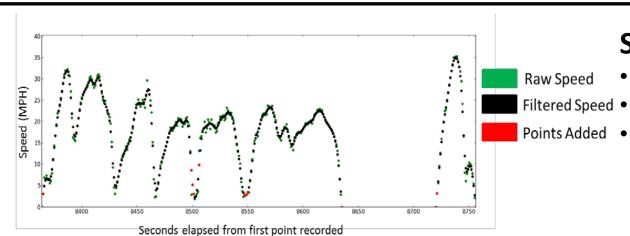
Elevation – Appended

Grade – Appended

Street ID – Appended
Street Functional Class
– Appended
Street Speed Category
– Appended

Speed & Location Filters

1



Speed Filtration

- Flags unrealistic speed
- Backfills missing points
- Interpolates missing and flagged data

Severe outlier filter

 Removes points falling outside a data defined buffer

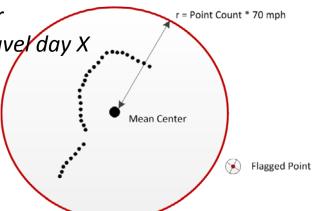
Radius = Hours of travel day X

70 mph

2

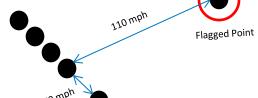
Mean Center

 The mean latitude and longitude independently



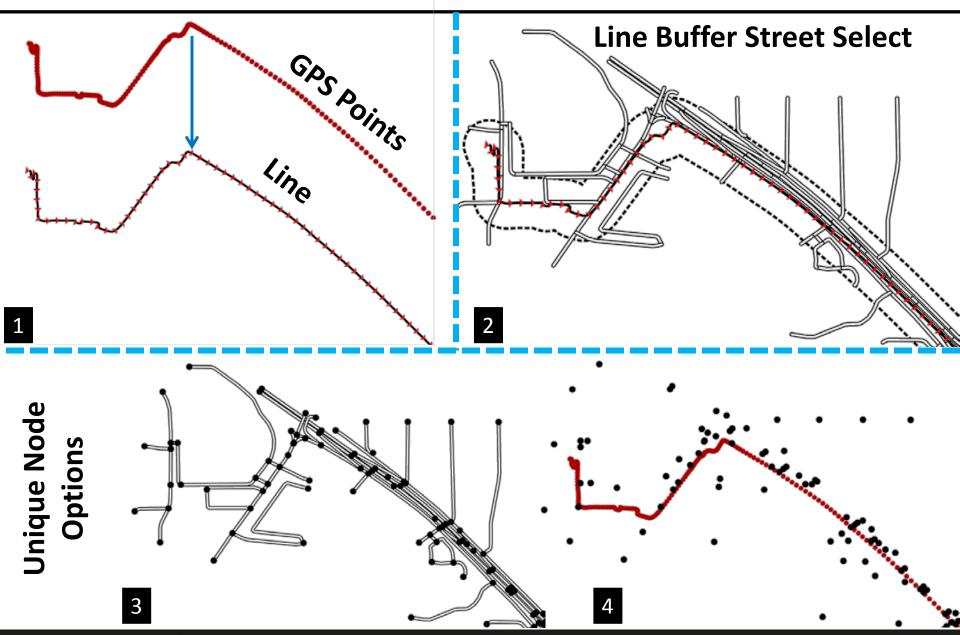
GPS Jumps Filter

- Calculates a rough speed value from distance and time
- Points where the calculated speed is > 100 mph are flagged until calculated speed falls under 100 mph

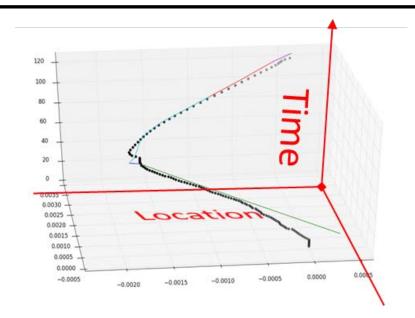


Typically less than 2% of GPS points require these processing adjustments

Map Matching: Dynamic Node Selection



Map Matching: Solve



Point-to-node links are established using time

- Each point is linked to the nearest node within 500 feet of a road
- Link is established by appending the node identifier to the point data (time)
- Points are down sampled to a discrete time at which the vehicle passed the node
- Vehicle x passed this node at this second

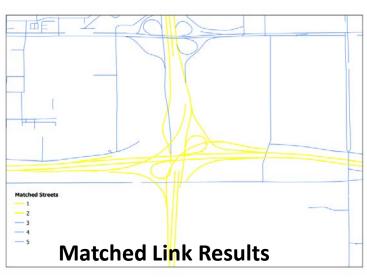
Solving connections logically (topology)

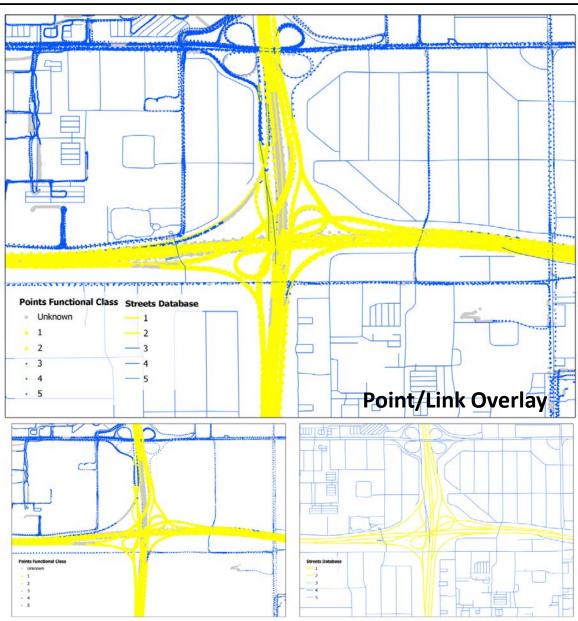
- The segments connected to the node and the possible exit node options for each entry node are identified independent of previous or next known results
- Options are then tested logically in order using multi-step decision tree
 - Identifies and removes latent links
 - Fill gaps in connection of consecutive segment links
- Appends attributes from the linked street segment to the data points falling within the entry and exit time of the matched segment

Map Matching: Accuracy

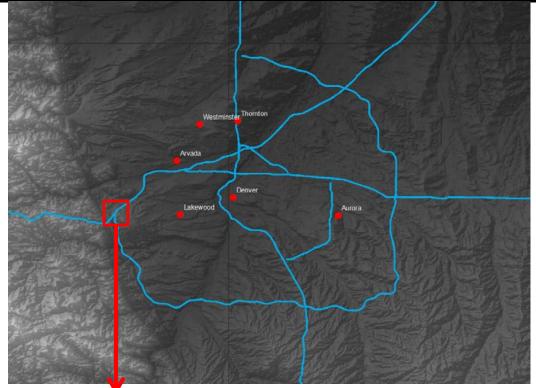
Complex overpasses

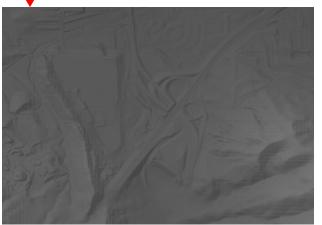
- Connectivity can become ambiguous when so many options are available
- 95% of distance matched across all data sets
- Cleaned up post processing during road based analysis

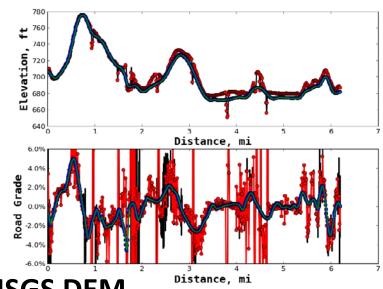




Elevation/Grade







USGS DEM

- The elevation for each location recorded is looked up from the USGS Digital Elevation Model (DEM)
- The elevation profile returned is smoothed
- Down sampled to normalize for distance to calculate grade
- The processing accuracy has been validated against roads with available ADAS grade measurements





Integrated Sensor Data Warehousing

NREL - Real World Vehicle Data Warehousing

Fleet DNA – DOE

- Warehouses medium- and heavy-duty fleet vehicle operational data across vocations, drivetrains, fuel type, and vehicle types
 - Has the ability to crowd source data collection, allowing for large-scale comparative analysis
- Removes identifying information and provides data to public for vehicle performance comparisons



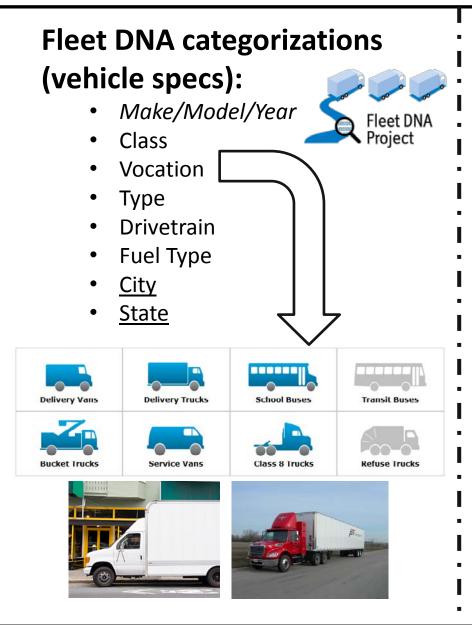


Secure Data Center (TSDC)

Transportation Secure Data Center (TSDC) – DOT and DOE

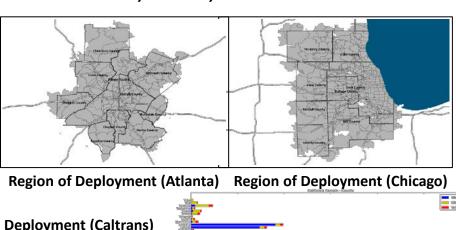
- Securely archives and provides public access to detailed regional transportation survey data
- Speed/time/location data for personal vehicle samples
- Reporting is specific to project using the same source data, but different ways of looking at it
 - TSDC Trip starts and ends are classified relative to the <u>home</u>, <u>work</u>, <u>school</u> location
 - Fleet DNA Trip starts and ends are classified relative to the <u>depot location</u>

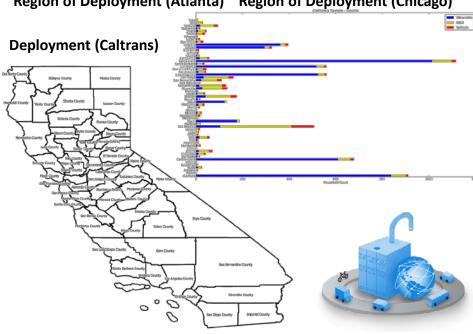
Geography: Sample Groupings



TSDC categorizations (geographic)

- Regions for data collection
- Make/Model/Year





Privacy & Data Security

- Both TSDC and Fleet DNA data sets contain extreme detail regarding the travel of the vehicles
 - Vehicles equipped with GPS sensors require certain precautions to be taken to ensure privacy and data security
- Each public distribution portal has specific controls in place

Fleet DNA

- Reports and downloads are grouped by vocation
- Allows comparative analysis between deployments
- Deployments can be identified within the data through an identifier, but the lookup is not made available
- NREL processing is applied to the vehicle GPS samples, and 360+vehicle travel statistics are provided by vocation



TSDC - Public

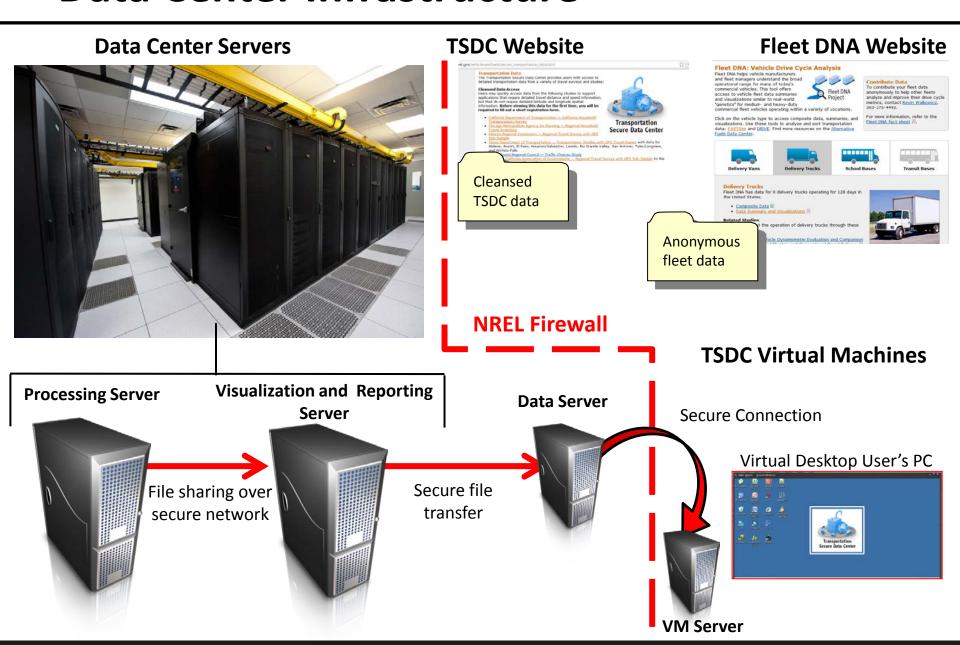
- Personally Identifying information is removed from source data
- Spatial reference identifying any geographic identification below the census tract is removed
- Vehicle model is removed
- Original study data are provided for download
- NREL processing is applied to the vehicle GPS samples, and 360+vehicle travel statistics are provided by <u>vehicle</u>

TSDC - Controlled

- Following a approval process, researchers gain access to the <u>full</u> <u>TSDC data sets</u> through a virtual desktop (VM – Virtual Machine)
- An NREL administrator acts as the gatekeeper for all data in and out of the environment
- Users can work within NREL's databases within the VM using software provided
- Data may only be removed by the NREL administrator

Transportation Secure Data Center (TSDC)

Data Center Infrastructure







Analysis Examples

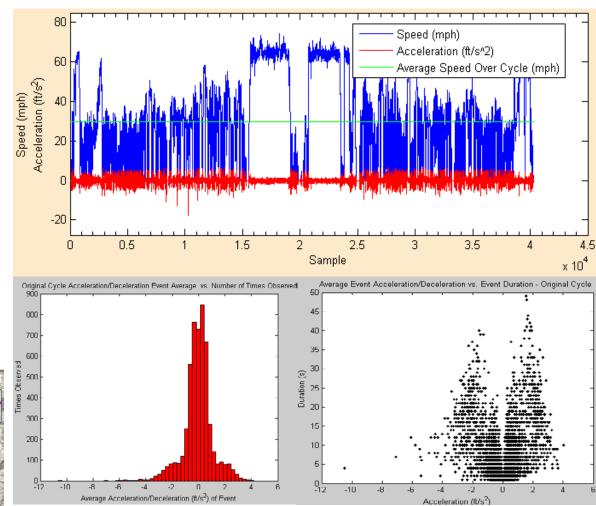
Vehicle Drive Cycle Characterization

Analysis Level: Vehicle

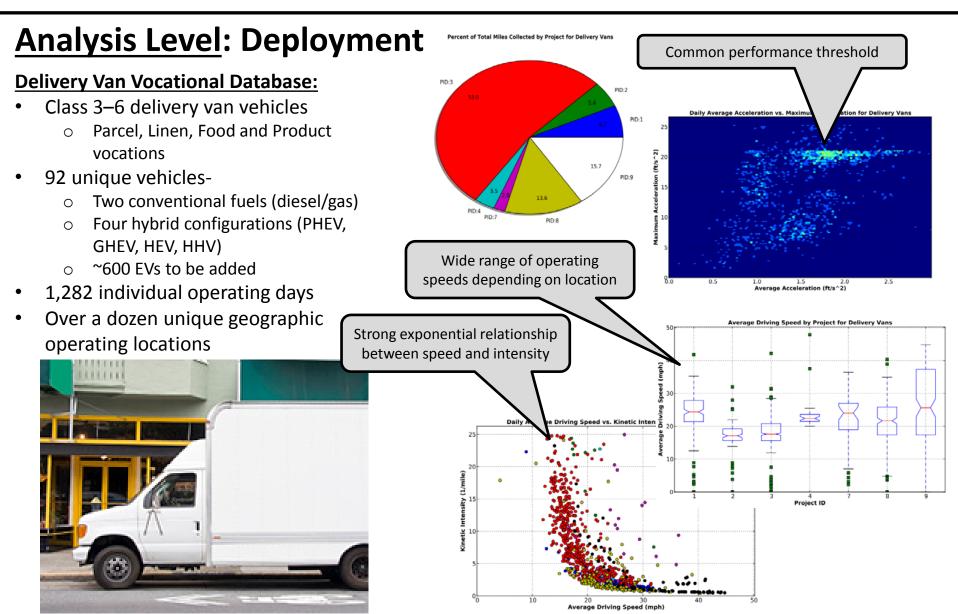
Drive Cycle Visualization

- Generate graphs of speed vs. time to observe vehicle operation
- Display histograms of useful statistics such as acceleration for analysis of performance envelopes
- Output latitude and longitude data for route visualization and mapping to ensure route/data consistency



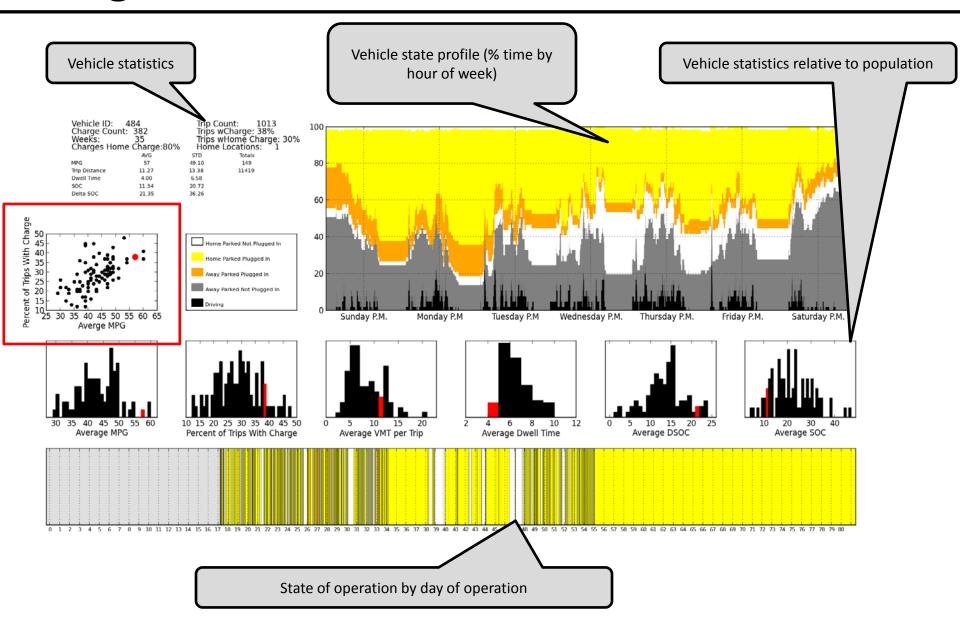


Fleet Drive Cycle Characterization



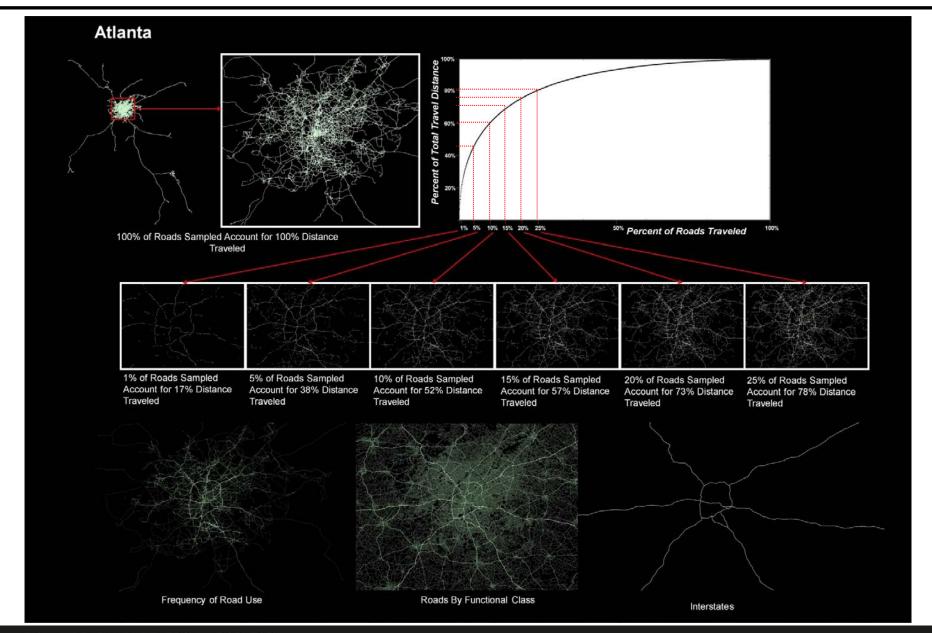
Charger Utilization: PHEV

Analysis Level: Vehicle relative to population



Regional Road Usage

Analysis Level: Regional Infrastructure Utilization



Daily Road Utilization

<u>Analysis Level</u>: High resolution daily vehicle road use

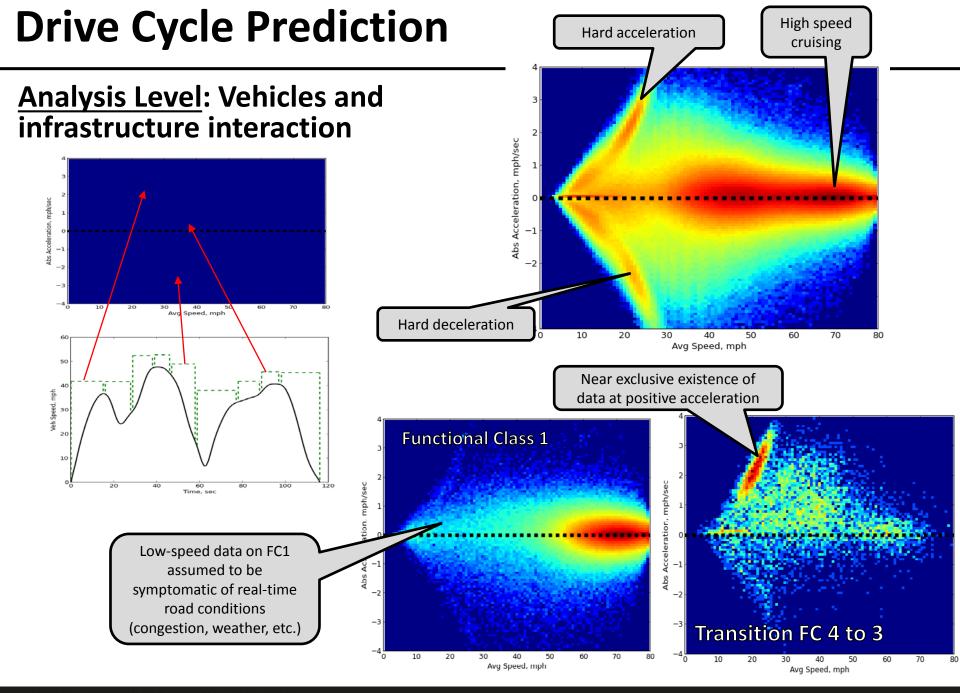


Cumulative Daily distance vs. Distance on Functional Class

- X axis is cumulative distance
- Y axis is cumulative distance functional class 1

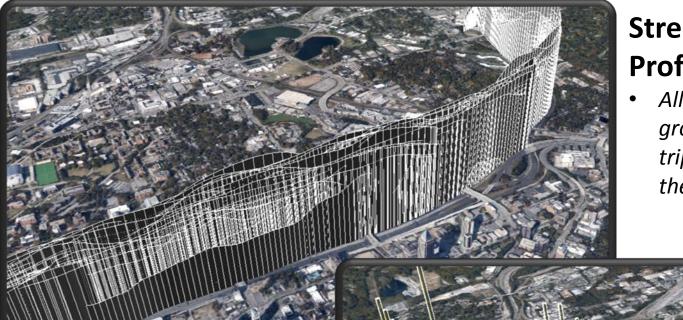
Vehicle Sub-sample Road Use

 A small sample of vehicle days where the daily distance traveled exceeds 50 miles



Road Use by Lane

Analysis Level: High resolution infrastructure utilization by time of day (5 a.m. to 10 a.m.)



Street Segments Driver Profiles

All point data collected for a grouping of roads ordered by trip visualized where speed is the z axis (left)

Road Grid Segments Lane Summary

- Road segment is divided into grid cells by lane
- Speed data are summarized by grid cell
- STDDEV of speed of travel by grid cell is visualized (right)

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Conclusion

 By organizing sensitive, high-resolution data appropriately and linking the data to additional data sets using location and time, the quality and quantity of data available for researchers can be greatly improved while still maintaining restrictions placed upon the data

Benefits

- Results in an infinite number of ways to group and sort the data for reporting
- Increases the number of applications for the data, and the amount of data distributed without violating restrictions

Why never before?

- Location data are very restricted and have a high value, so very little data of this kind are available publicly
 - In-vehicle navigation systems utilize similar approach to analysis, but do not provide it publicly
- Programming languages and databases now incorporate spatial analysis capability, providing free and open source tools with which to perform analysis